

Biomechanical outcome after computer-assisted Femur First vs. conventional THR

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Implant system

■ Companies



Musculoskeletal computations



Medical image processing



Finite Elemente Analysis

1. Introduction
2. V&V – Verification and Validation
3. Study Results and Discussion
4. Outlook

- Increasing numbers of patients that are subject to Osteoarthritis (OA)
- OA in the hip is the leading cause for
 - Pain
 - Stiffness
 - Difficulty in moving (limited range of motion)
- 300,000 Total Hip Replacements (THR) in Germany¹

¹) OECD: Health at a Glance 2013: OECD Indicators.

Total hip replacement (THR)

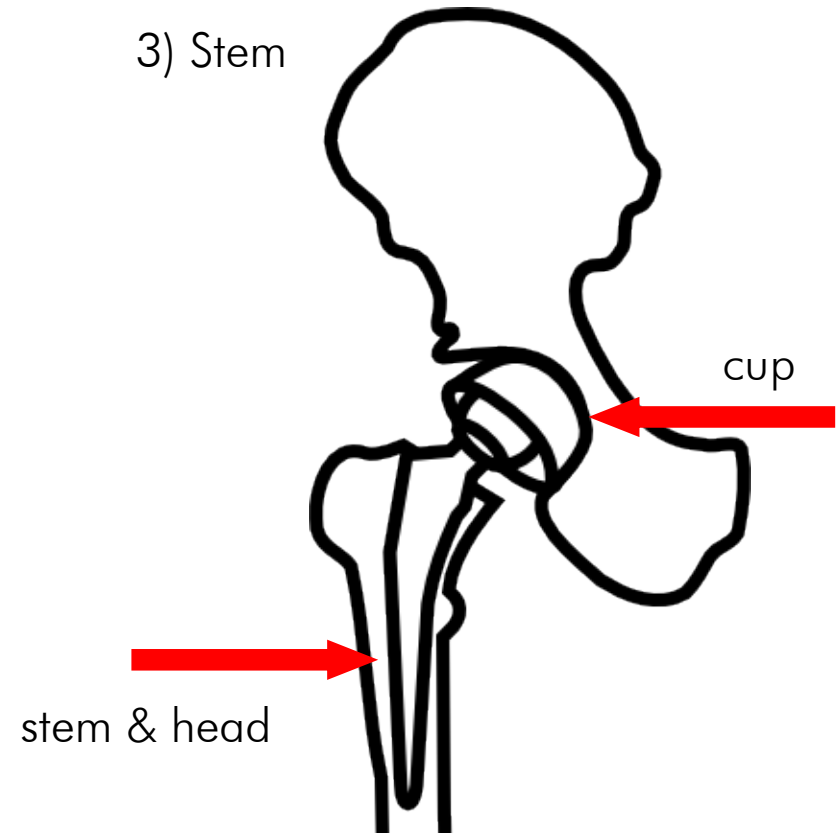
1) Resection



2) Cup



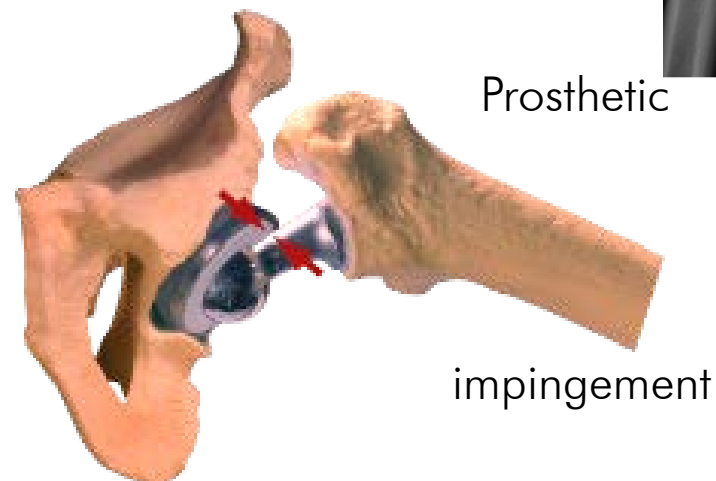
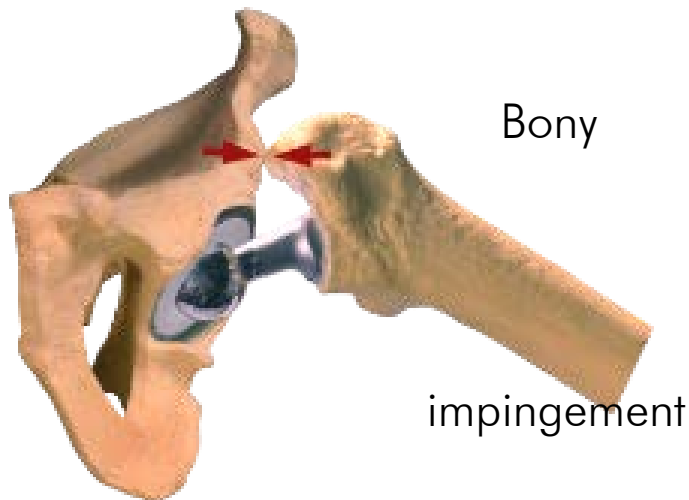
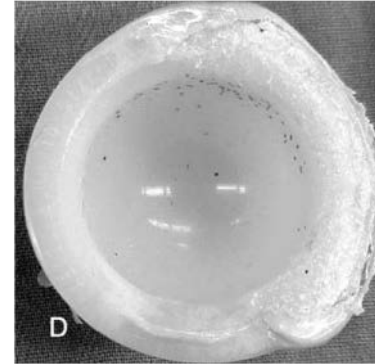
3) Stem



- Up to 25% are still failing¹ --- but why?

1) Melvin et al.: Early Failures in Total Hip Arthroplasty – A Changing Paradigm. 2013

- Malpositioning leads to
 - Impingement
 - Increased wear rates and
 - Increased risk for dislocation



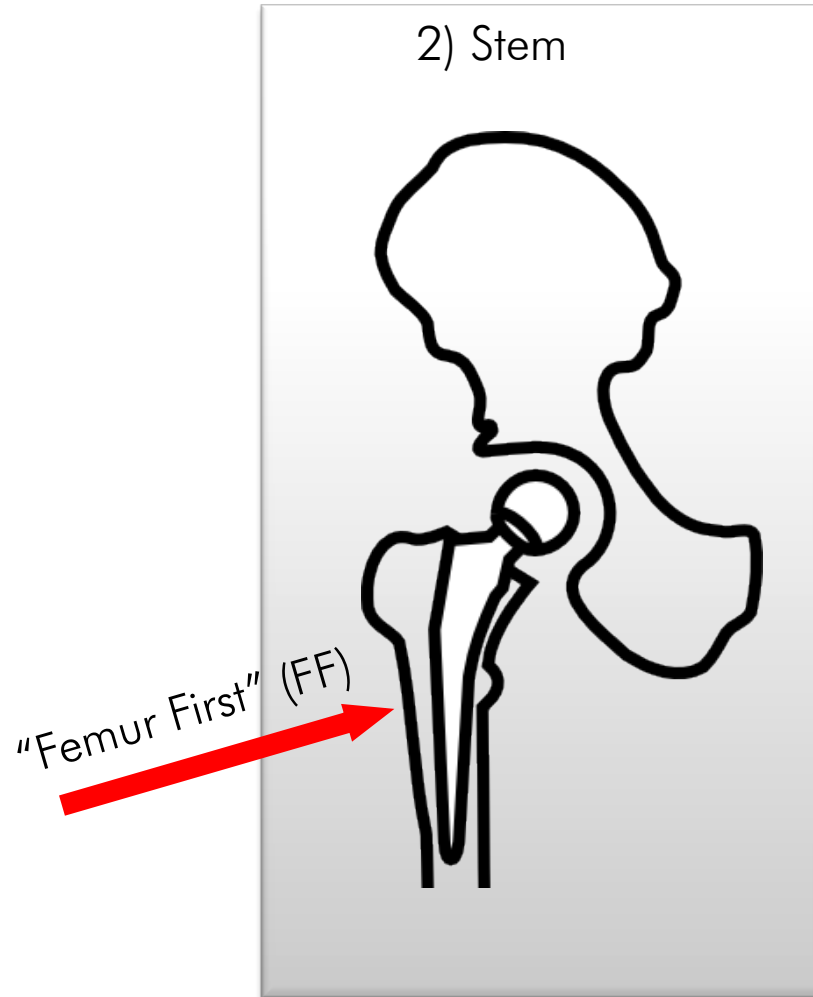
1) Shon et al.: Impingement in total hip arthroplasty a study of retrieved acetabular components. 2005

2) Patel et al.: The dislocating hip arthroplasty: prevention and treatment. 2007

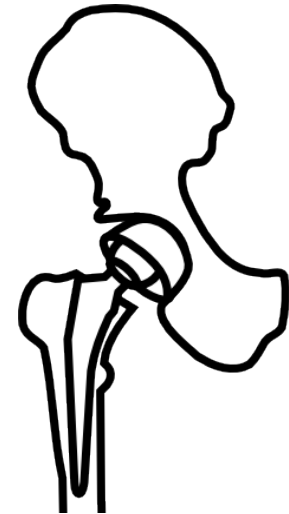
1) Resection



2) Stem



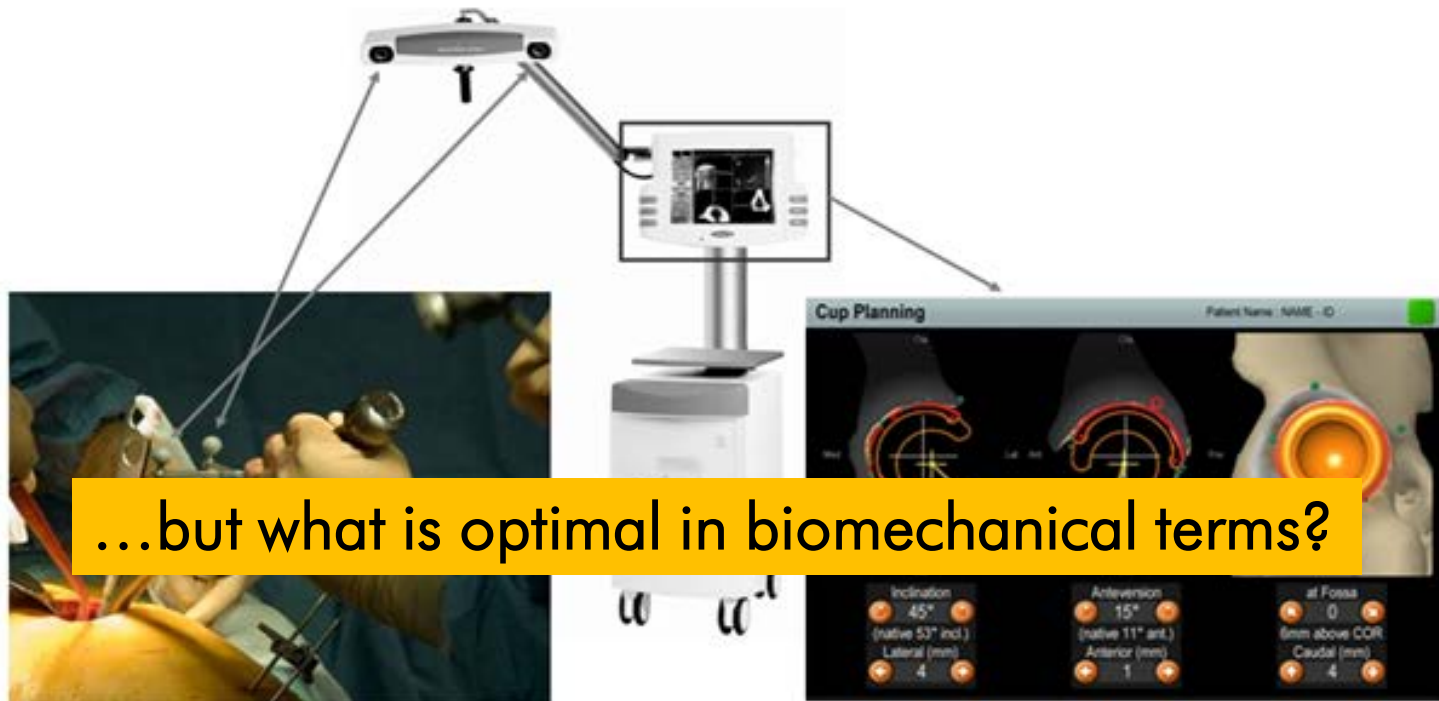
3) Cup



CAS - Computer assisted surgery

- Guided surgery to position implant system with respect to patient anatomy
- Imageless, motion-capture (MoCap)

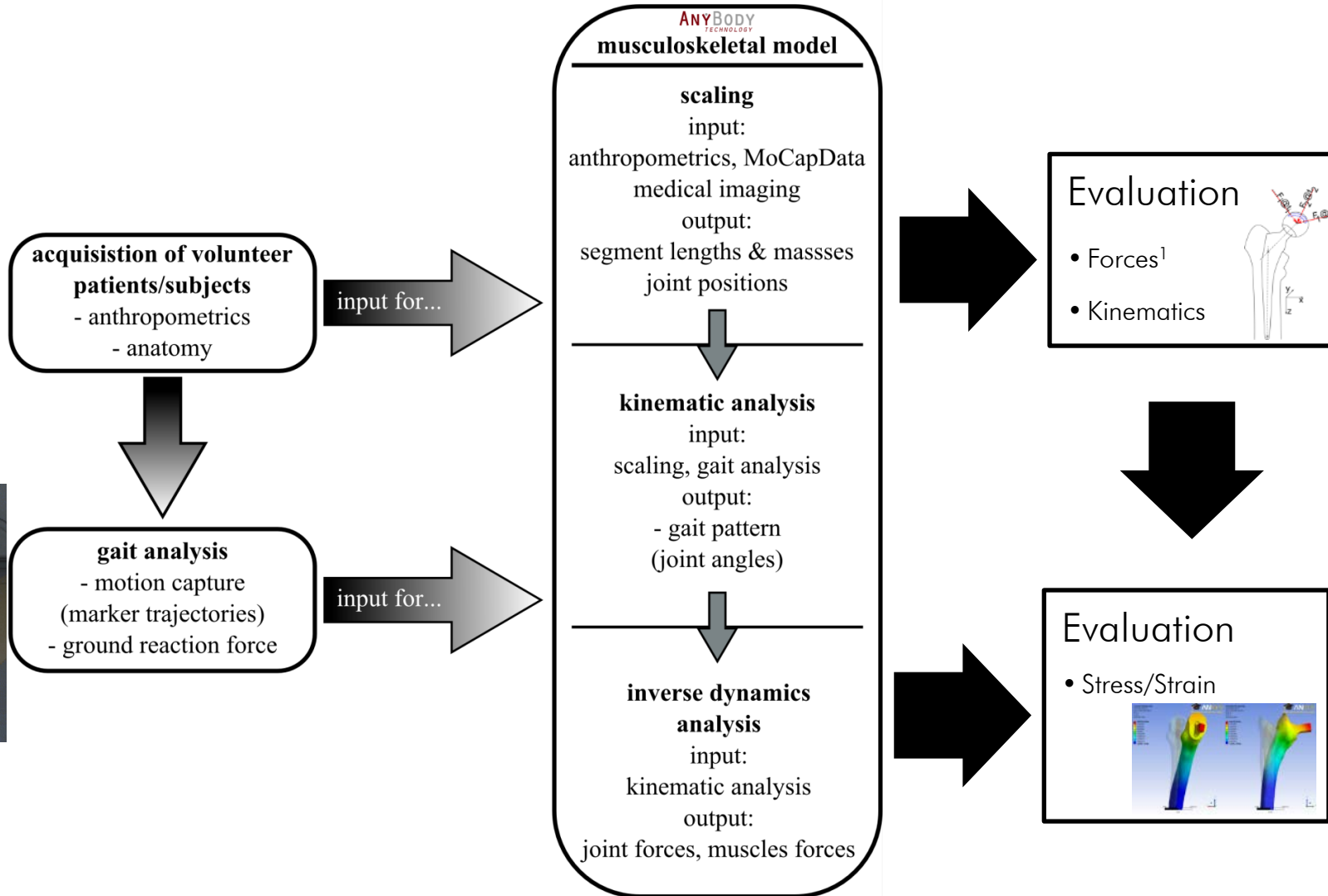
Optimal implant positioning may lead to decreased wear and impingement rates



- 60 Patients (28 CAS FF/32 CON)
 - Subgroup of the FemurFirst¹ study
- Pre-op, 6 months post-op, 12 months post-op gait analysis
- Post-op CT-Scan of all patients
- Randomized
- Double – blinded
- Ethics approval

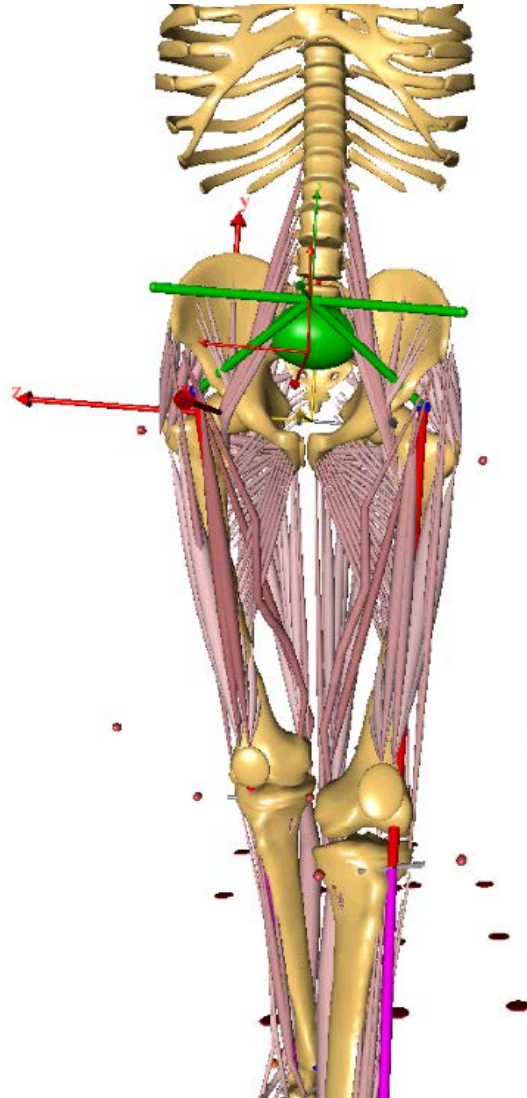
¹) Renkawitz et al. Minimally invasive computer-navigated total hip arthroplasty, following the concept of femur first and combined anteversion: design of a blinded randomized controlled trial. 2011

Outcome variable	Hypothesis
<p>Hip reaction force</p> <ul style="list-style-type: none">- Magnitude- Symmetry	<ul style="list-style-type: none">- Magnitude closer to healthy in CAS group- Symmetry increased in CAS group
<p>Hip reaction force orientation</p> <ul style="list-style-type: none">- Distance to rim- At peak loads	<ul style="list-style-type: none">- Distance to rim increased in CAS group- Distance to rim at peak loads increased in CAS group



1) Weber et al.: Measuring functional outcome after total hip replacement with subject-specific hip joint loading. 2012

2) Dendorfer et al.: Musculoskeletal modeling for hip replacement outcome analyses and other applications. 2014

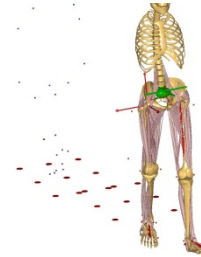
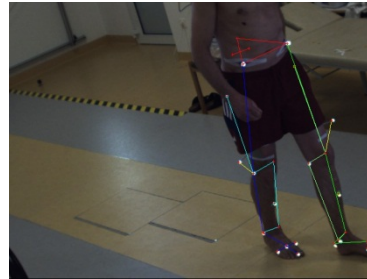


- Over 150 individual activated muscles
- Highly accurate due to non-linear scaling¹
- Cubic muscle activation scheme

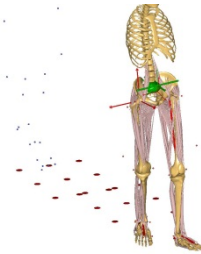
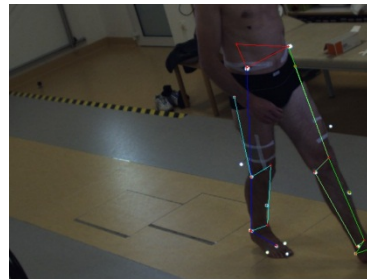
$$G = \sum_i \left(\frac{mf_i}{N_i} \right)^3$$

P24, CAS FF, operated: left

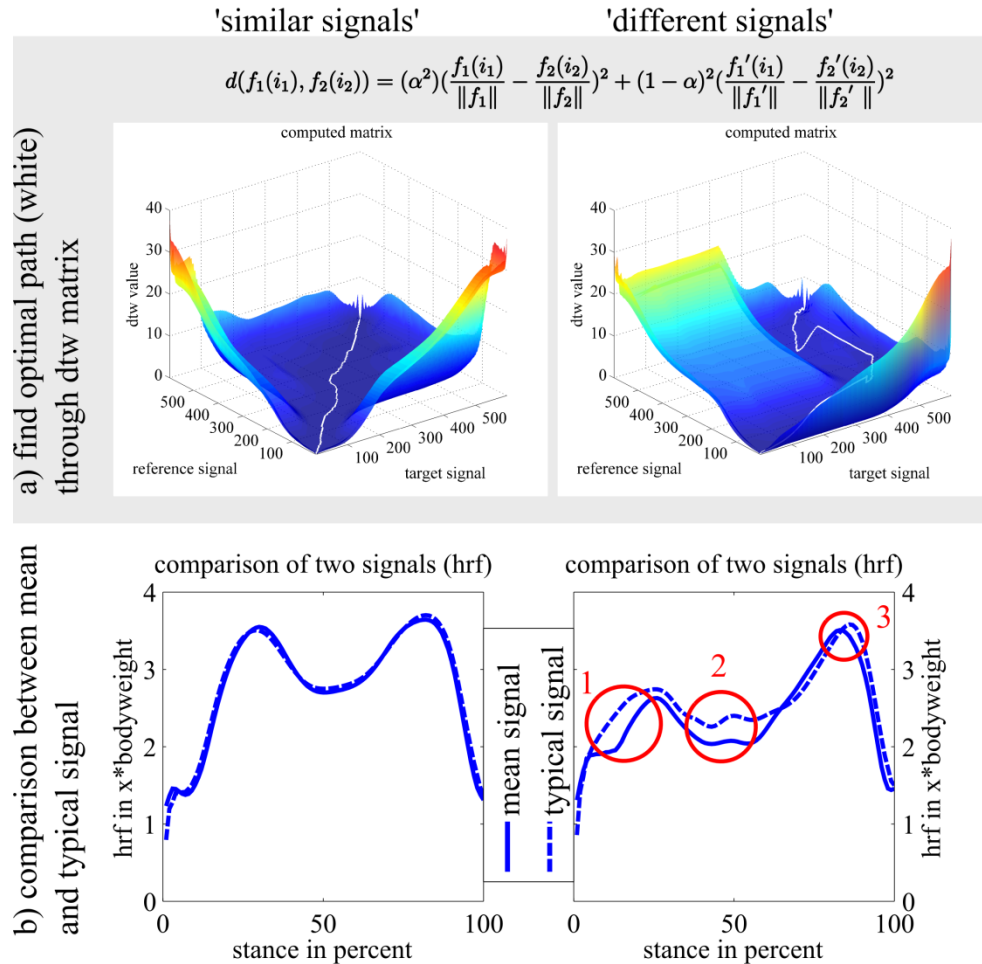
t0 – pre operativ



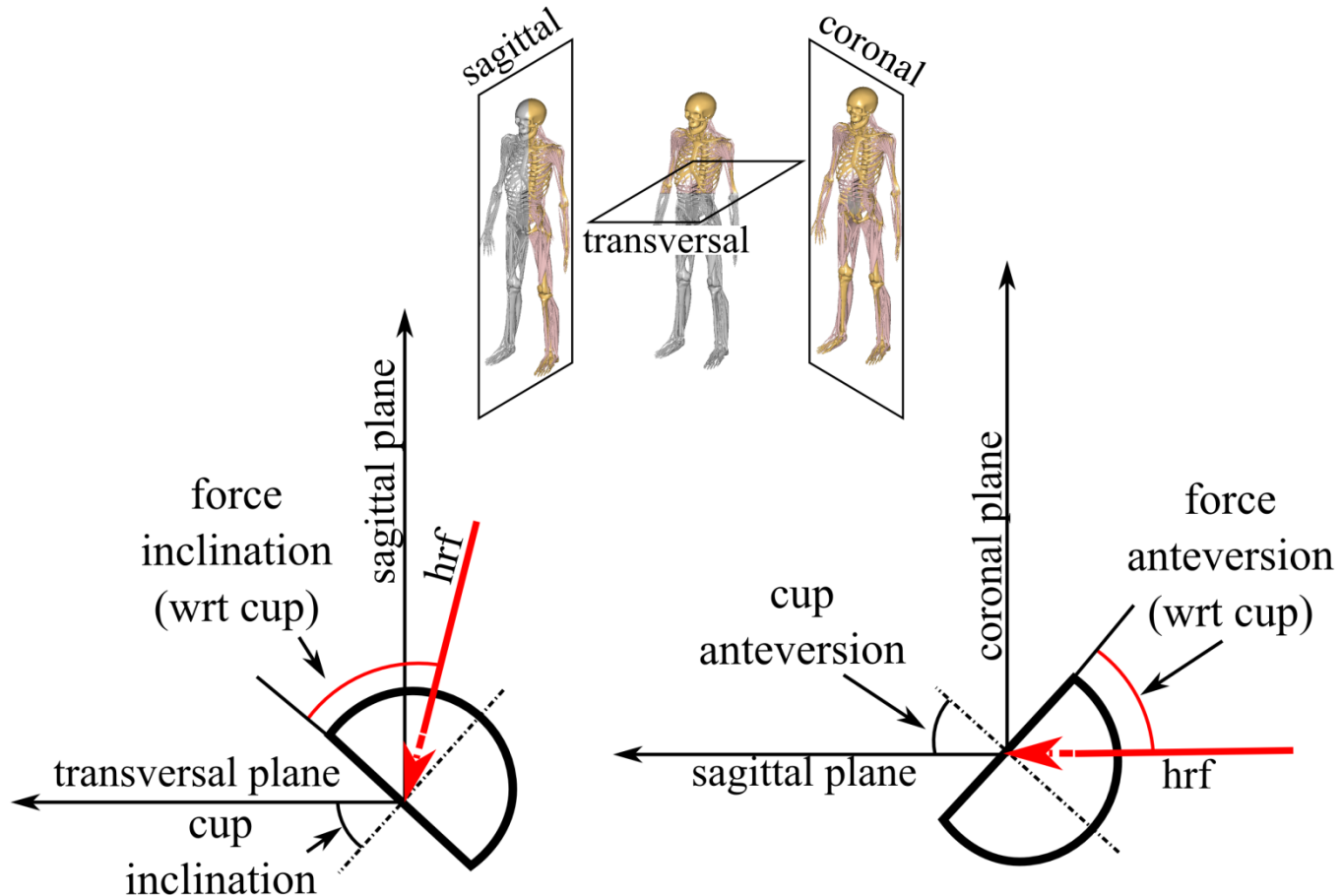
t1 – 6 month post operativ



- “typical signals”¹
- measure of shape similarity



- Radiographic coordinate system¹



1) Murray: The definition and measurement of acetabular orientation. 1993.

Verification & Validation

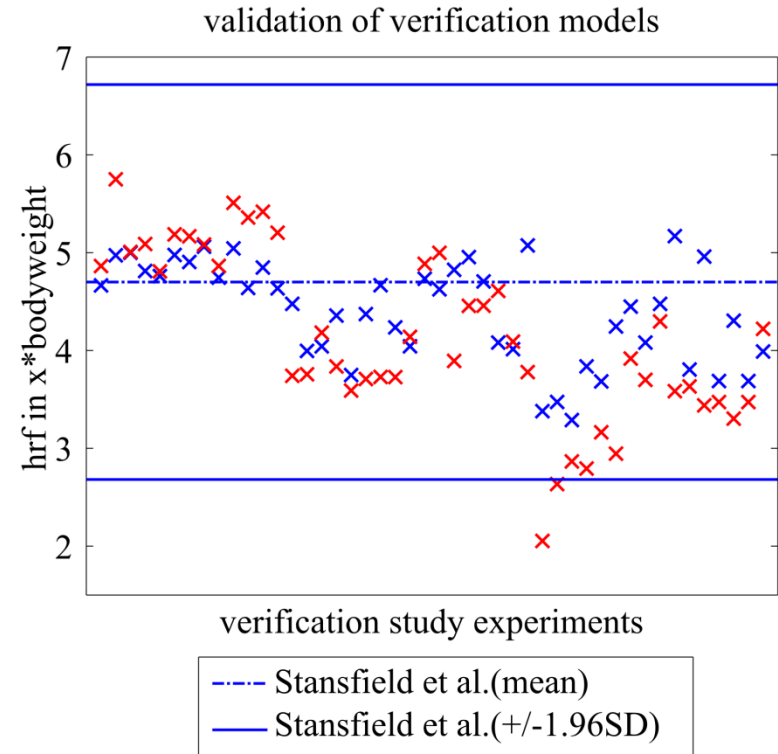
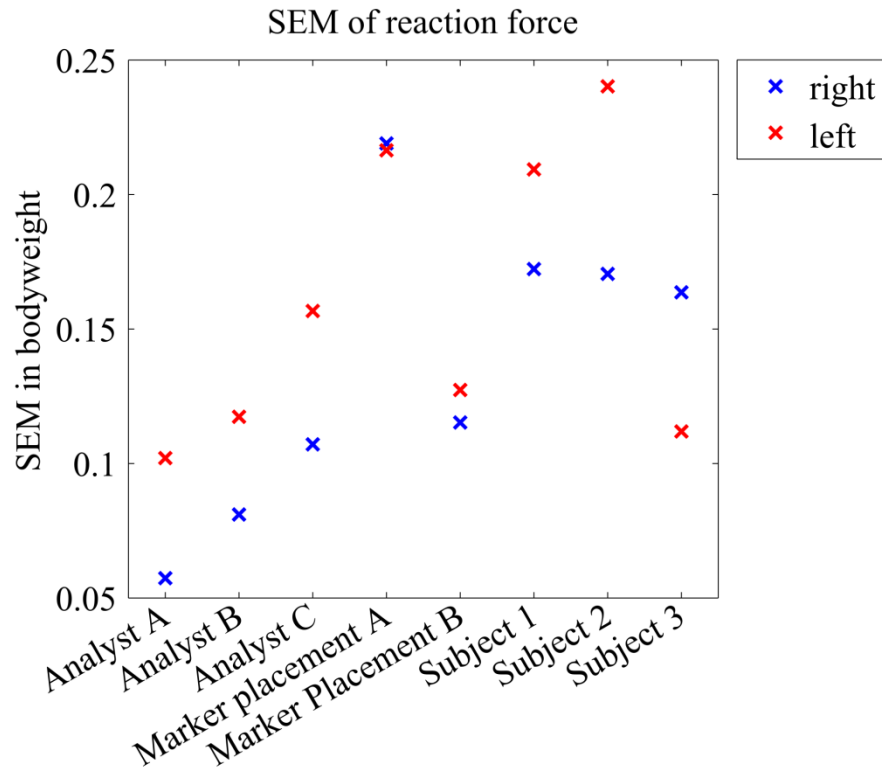
Research question	Source of variance	Study	Target parameter
Is the result obtained dependent on the MoCap Analyst?	MoCap Analyst	1 healthy subject (S1), 1 gait analysis, evaluated 10 times by 3 different examiners: A(experienced), B(experienced), C(not-experienced)	Standard error of mean (SEM) of hrf - HRF_{SEM}
How big is the influence of marker-placement on the results obtained	MoCap – marker placement	1 healthy subject (S1), 10 gait analysis, application of marker set in alternating manner by 2 analysts: A(experienced), B(experienced)	HRF_{SEM}
Is the method robust enough to produce repeatable results?	Measurement chain	3 healthy subjects (S1,S2,S3), 10 gait analysis, evaluation by 1 experienced analyst (A)	HRF_{SEM}

SEM : standard error of the mean

$$SEM(\bar{X}) = \frac{\sigma}{\sqrt{n}}$$

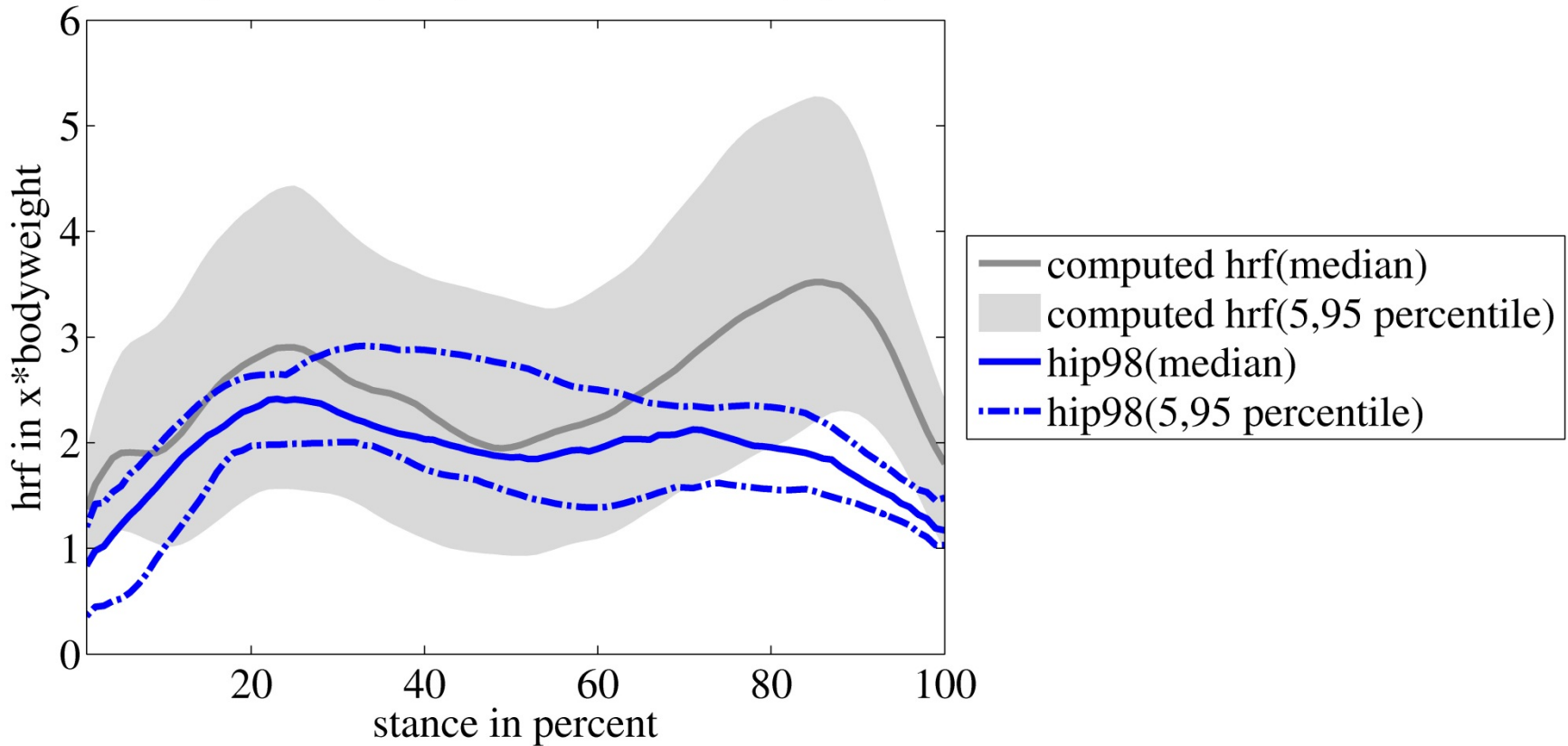
σ : standard deviation

n : sample size



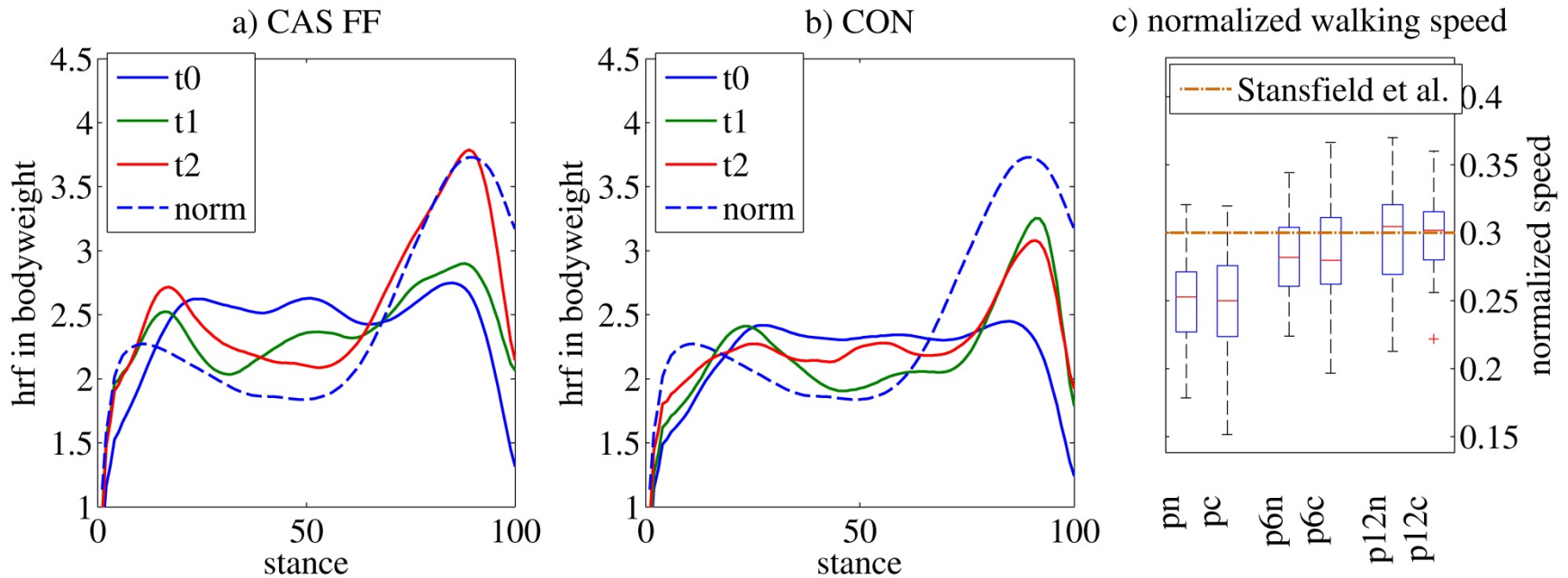
- Hrf accuracy: $2 \cdot \max SEM \sim 0.5BW$

computed hrf (at t2) vs. measured hrf (hip98)



- STUDY RESULTS -

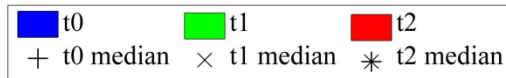
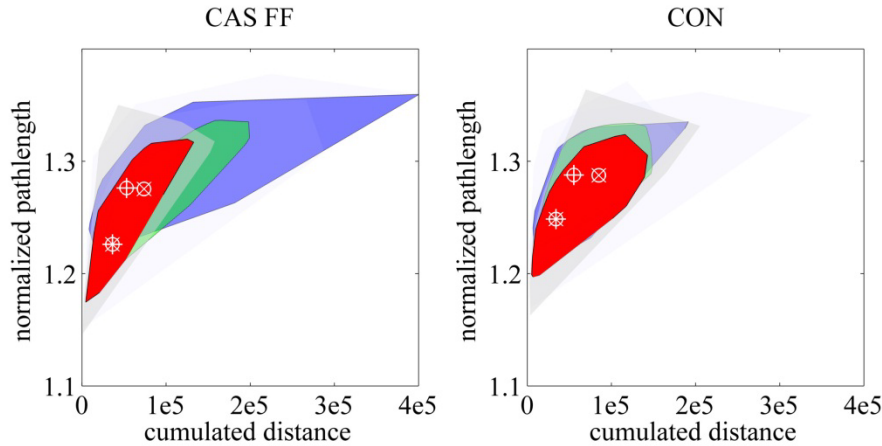
typical hip reaction force



- Computed by means of dynamic time warping¹
- Walking speed normalized to body height²

1) Bender and Bergmann: Determination of typical patterns from strongly varying signals. 2012.
2) Hof: Scaling gait data to body size. 1996.

a) operated vs. not-operated side

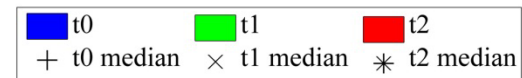
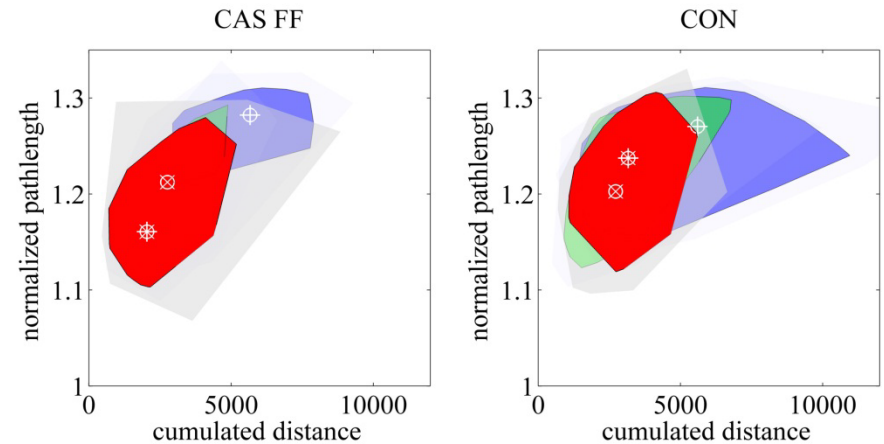


Pathlength: phase shift symmetry
Cumulated distance: magnitude symmetry

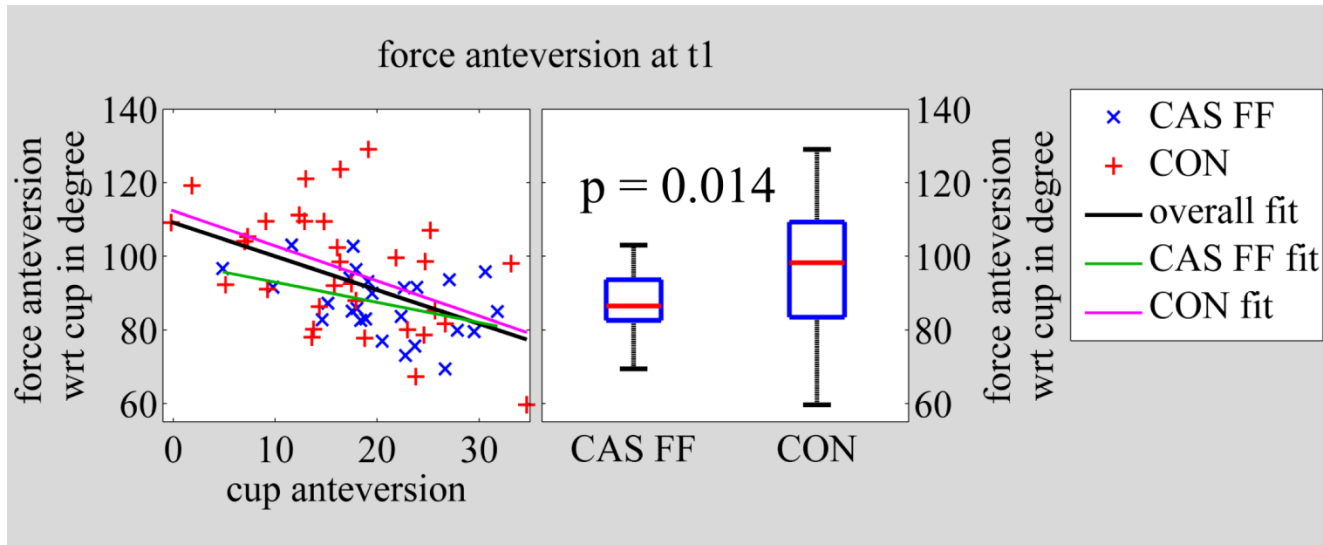
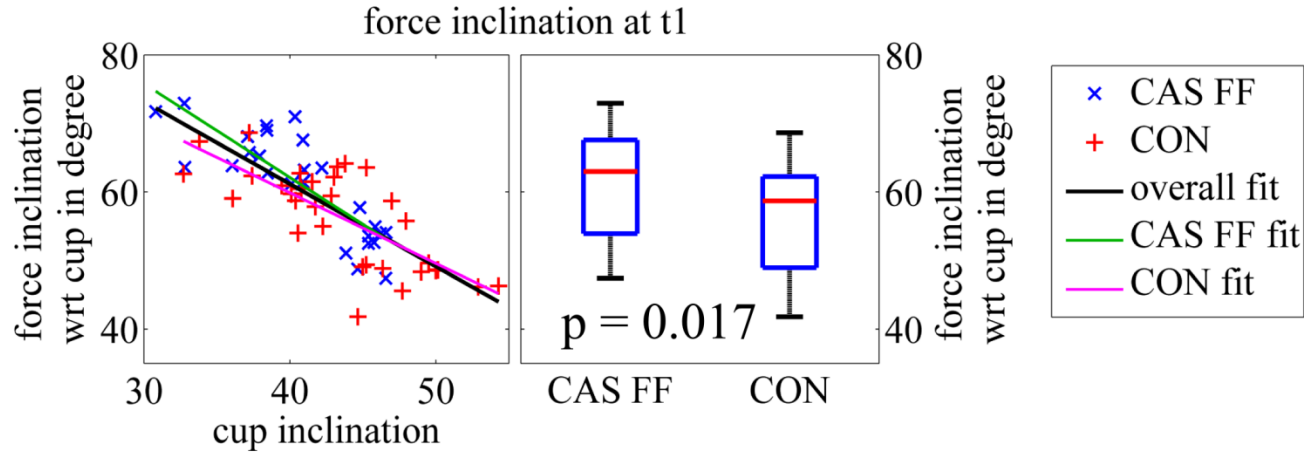
- Computed by means of dynamic time warping¹

1) Bender and Bergmann: Determination of typical patterns from strongly varying signals. 2012.

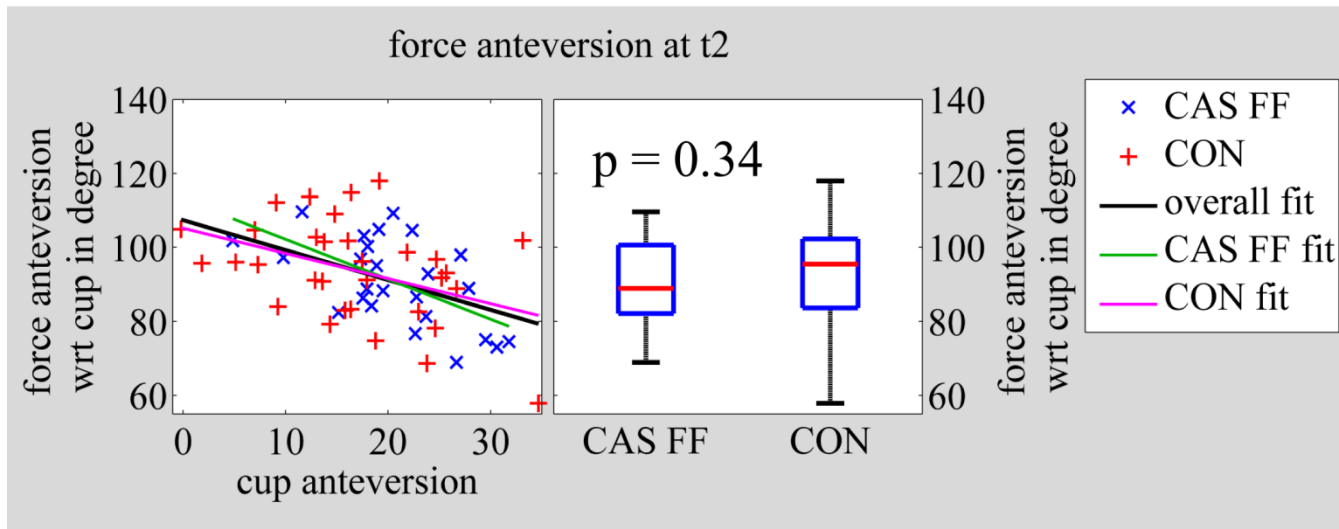
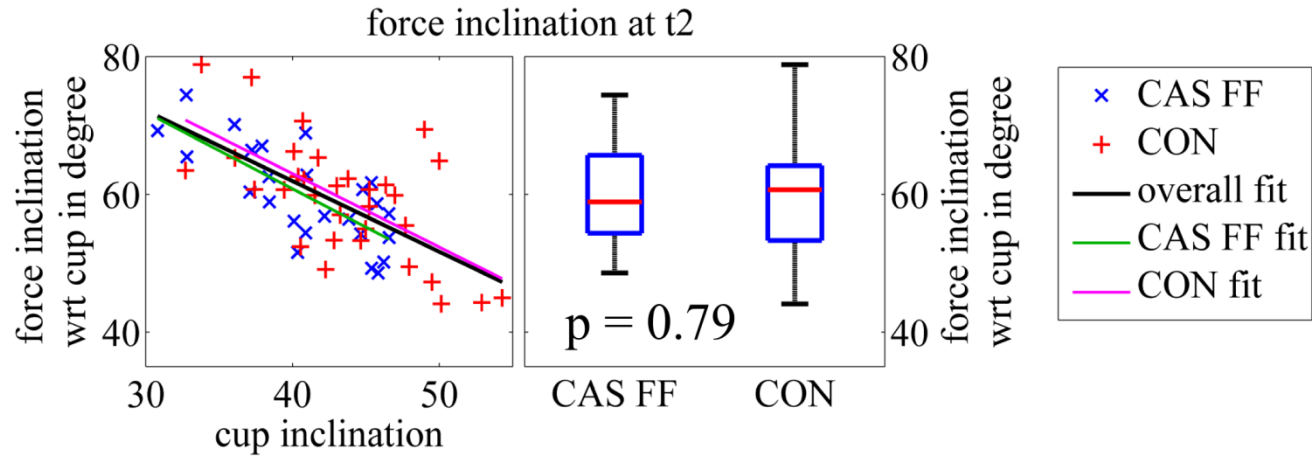
b) operated side vs. normative data



Hrf orientation (wrt cup)



Hrf orientation (wrt cup)



- Hip reaction forces:
 - CON hrf are closer to a healthy normal at 6 month postop
 - CAS FF hrf are closer to a healthy normal at 12 month postop
- Asymmetries:
 - decrease more in the CAS FF group, but insignificantly
 - CAS FF group closer to healthy normal in terms of phase-shift
- Orientation:
 - At t1 hrf Orientation of the CAS FF closer to optimal (90° - $p < 0.05$)
 - At t2 no significant differences between the groups

- t1 (6 month):
 - CON hrf are closer to healthy normal
 - Hrf orientation is closer to optimum in the CAS FF group

Trend for lower propensity for impingement and dislocation early after surgery for CAS FF

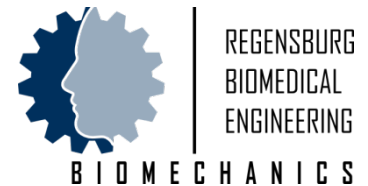
- t2 (12 month) :
 - Increased phase-shift asymmetry
 - CAS FF are closer (practically the same) to healthy optimum

Possible long-term benefit due to restored walking ability for CAS FF patients

- Comprehensive data set (32 vs. 28 patients)
 - Double blinded, randomized, prospective
- Validated and detailed model (AnyBody – AnyGait Model)
- Symmetry captures not only point of times, it is rather a measure of shape similarity

- Only post6, no earlier results
- Only walking as motion
 - More critically motions may be used for bigger effects (ethics)
- Greater sample size would increase statistic validity

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 - <https://www.linkedin.com/pub/tim-weber/88/222/1a1>

Literature (in order of appearance):

- ❖ OECD: Health at a Glance 2013: OECD Indicators.
- ❖ Melvin et al.: Early Failures in Total Hip Arthroplasty – A Changing Paradigm. 2013
- ❖ Shon et al.: Impingement in total hip arthroplasty a study of retrieved acetabular components. 2005
- ❖ Patel et al.: The dislocating hip arthroplasty: prevention and treatment. 2007
- ❖ Sendtner et al.: [Femur first in hip arthroplasty--the concept of combined anteversion]. 2010.
- ❖ Renkawitz et al.: Development and evaluation of an image-free computer-assisted impingement detection technique for total hip arthroplasty. 2012.
- ❖ Renkawitz et al.: Minimally invasive computer-navigated total hip arthroplasty, following the concept of femur first and combined anteversion: design of a blinded randomized controlled trial. 2011
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- ❖ Dendorfer et al.: Musculoskeletal modeling for hip replacement outcome analyses and other applications. 2014
- ❖ Andersen et al.: The effect of including accurate pelvis bony landmarks in a nonlinearly scaled musculoskeletal lower extremity model. 2012
- ❖ Bender and Bergmann: Determination of typical patterns from strongly varying signals. 2012
- ❖ Stansfield and Nicol: Hip joint contact forces in normal subjects and subjects with total hip prostheses: walking and stair and ramp negotiation. 2002.
- ❖ Bergmann et al.: Hip contact forces and gait patterns from routine activities. 2001 - <http://orthoload.com/>
- ❖ Hof: Scaling gait data to body size. 1996.
- ❖ Weber et al.: Influence of minimally invasive total hip replacement on hip reaction forces and their orientations. 2014.

