

The webcast will start in a few minutes....



LifeLongJoints

MUSCULOSKELETAL VALIDATION AND WEAR SIMULATION



Grant agreement
no. NMP-310477

Outline

- Brief introduction
- Today's webcast:
 - Musculoskeletal validation and wear simulation
- Models and batch processing
- Questions and answers



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Control Panel

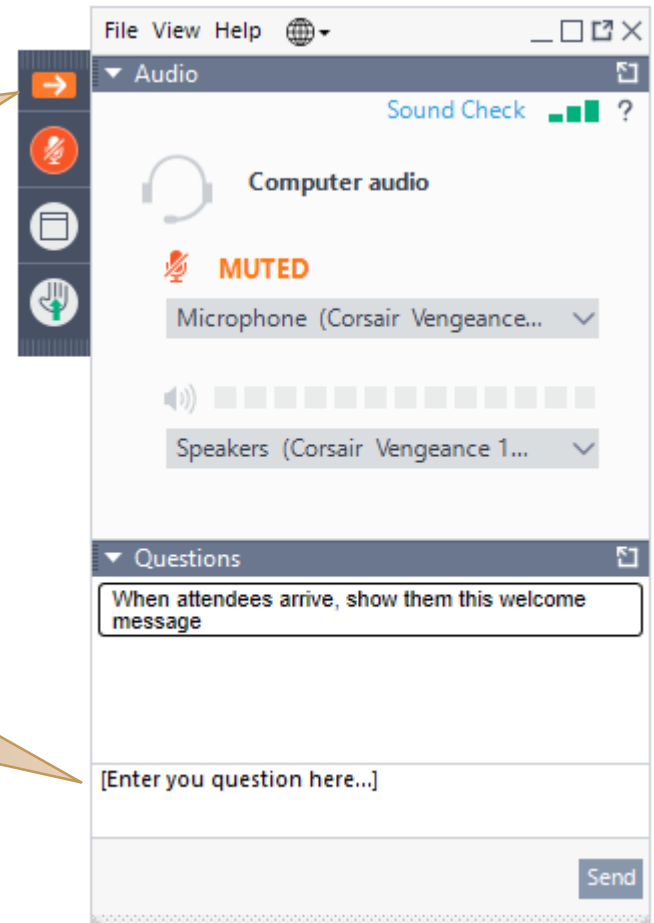
The Control Panel appears on the right side of your screen.

Submit questions and comments via the Questions panel.

Questions will be addressed at the end of the presentation. If your question is not addressed we will do so by email.

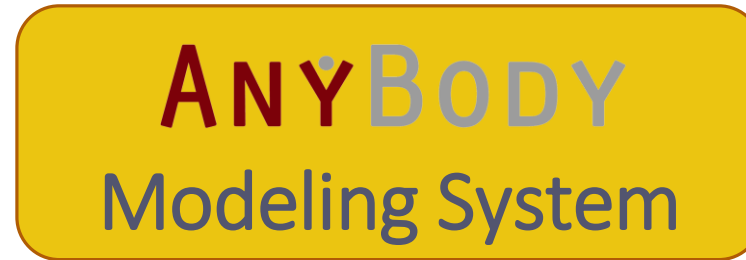
Expand/Collapse the Control Panel

Ask a question during the presentation



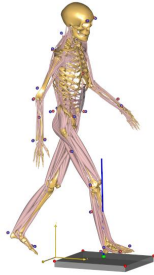
Musculoskeletal Simulation

Motion data
Kinematics + Forces

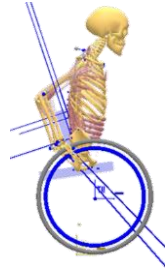


Body Loads

- Joint moments
- Muscle forces
- Joint reaction forces



Movement
Analysis

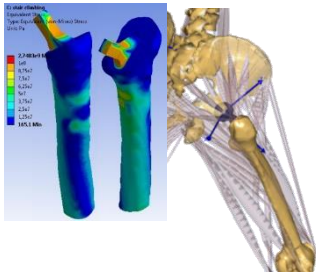


Product Design
Optimization



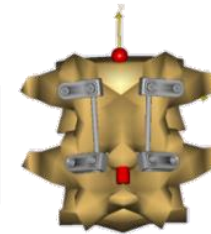
Ergonomic
Analysis

ANYBODY Modeling System



Load Cases for
Finite Element
Analysis

Surgical Planning and
Outcome Evaluation





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LifeLongJoints

MUSCULOSKELETAL VALIDATION AND WEAR SIMULATION



LifeLongJoints: Computational Methods for Implant Design and Treatment Planning "The Virtual Patient"

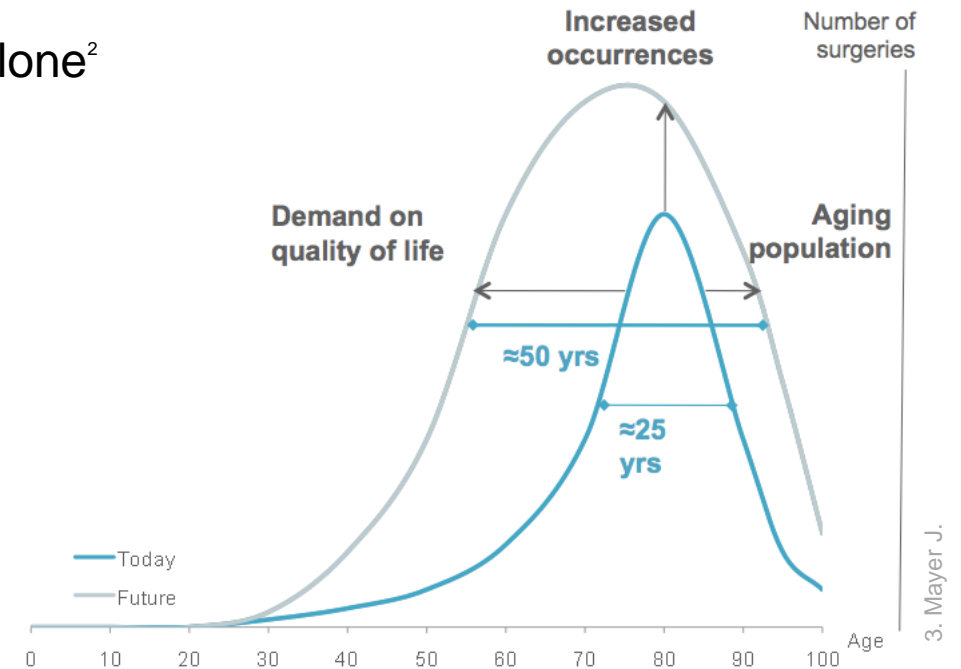
Enrico De Pieri, Stephen Ferguson

Introduction: Total Hip Replacements

- Solution for arthritis and severe fractures
- Failure rate between 3% and 10% at 10 years¹
 - 100.000 failure cases for knee and hip per year in the US alone²
 - Economic burden over 1 billion \$ / year
 - Revision surgery not as successful as primary procedure
- Younger patients needing a THR:
 - Longer life-span of the implant
 - More demanding physical activities

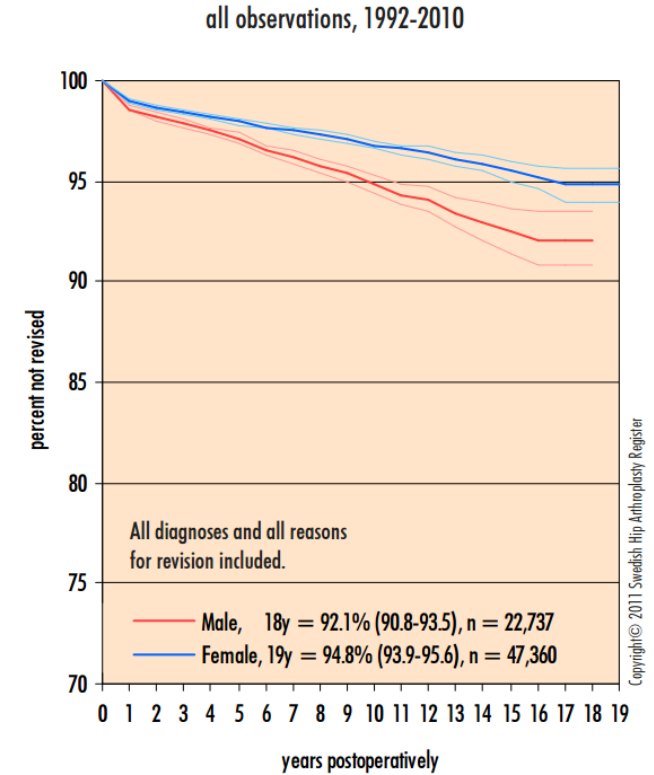
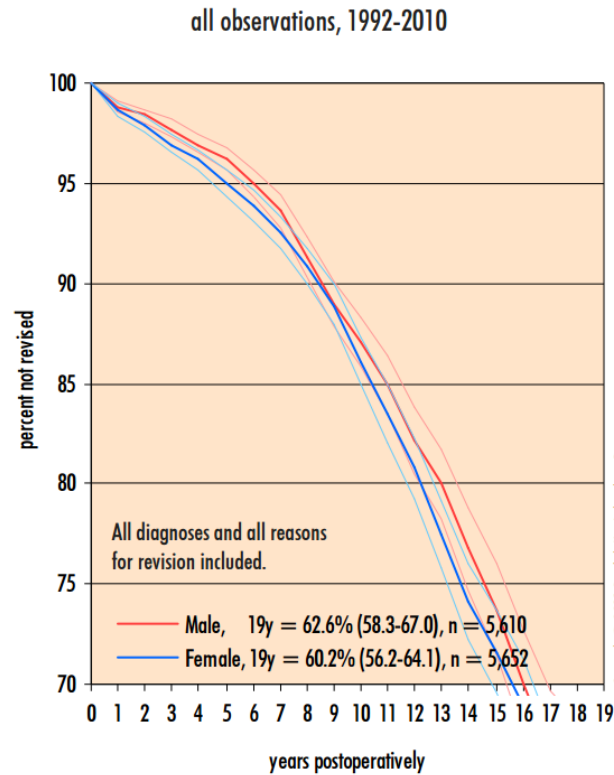


Need to improve longevity and robustness



1. Swedish Hip Arthroplasty Register, Annual Report 2010; <http://www.shpr.se/Libraries/Documents/AnnualReport-2010-2-eng.sflb.ashx>
2. Kurtz S.M. et al., Future Young Patient Demand for Joint Replacement: National Projections from 2010 to 2030. *Clin Orthop Rel Res*, 467: 2606–2612.
3. J.Mayer, S. Hofmann, D. Webster: Biocompatibility of biomedical implants, lecture notes, 2013, ETH Zurich

Implant Performance



Failures beyond 3-5 years are mainly due to wear and related complications

Wroblewski BM, et al. Journal of Bone & Joint Surgery - British Volume. 89(8):1015-8, 2007

Exhaustive Proof Testing

Dauerschwingversuch
ISO 7206-4, 6 und 8



Kugel Torsionstest
ISO 7206-9



Kugel Berstversuch
ISO 7206-10



Kugel Abzugversuch
ASTM F 2009



Luxationsversuch
PI-1/2



GeometrieKennwerte
ISO 7206-1/2



Verschleißversuch
ISO 14242-1



Insert Ausdrückversuch
ASTM F1820



Korrosionsversuch
ASTM F1875



Bewegungsumfang
ISO 21535



Dauerschwingversuch
Modularverbindung
ASTM F 2580



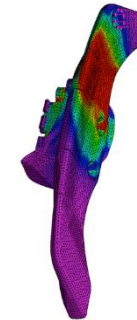
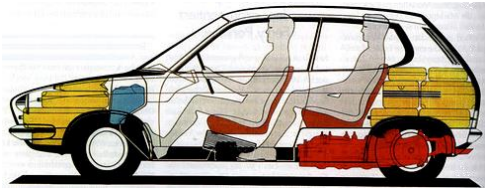
Impingement Test
ASTM F 2582



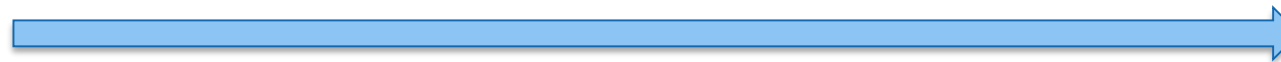
Dauerschwingversuch
Pfanneninserts
PI-11



Design Process Evolution



1978

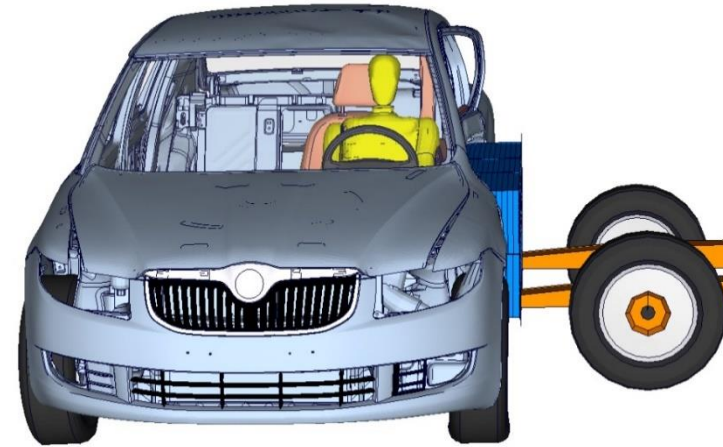


2018

How has the design process changed? What can we learn?

The Value of Simulation

- Computer simulations to define better experiments
- Few experiments to validate computer models
- Computer simulations to explore 1000s of situations – reduce time and cost



<http://www.esi-group.com>

Is Prosthesis Wear an "Implant" Problem?

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Which Factors Determine the Wear Rate of Large-Diameter Metal-on-Metal Hip Replacements?

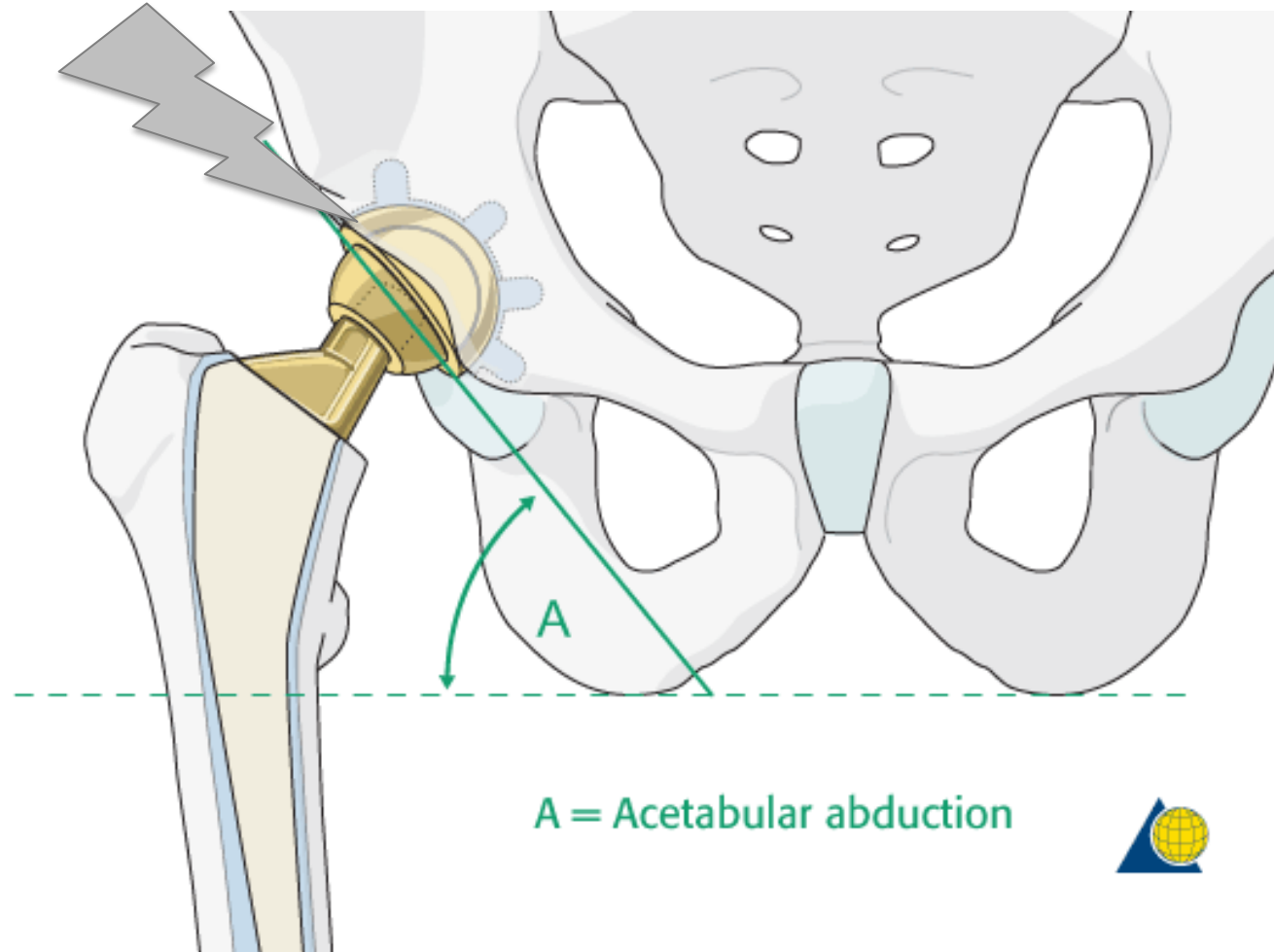
Multivariate Analysis of Two Hundred and Seventy-six Components

A.J. Hart, MA, MD, FRCSG(Orth), S. Muirhead-Allwood, FRCS(Orth), M. Porter, FRCS(Orth), A. Matthies, BSc, MBBS, K. Ilo, BSc, MBBS, P. Maggiore, BSc, MBBS, R. Underwood, PhD, P. Cann, PhD, J. Cobb, FRCS(Orth), and J.A. Skinner, FRCS(Orth)

Investigation performed at the London Implant Retrieval Centre, a Collaboration Between Imperial College London, London, and the Royal National Orthopaedic Hospital NHS Trust, Middlesex, United Kingdom

- “...edge-loading was the most important predictor of wear rate”

Prosthesis Positioning?

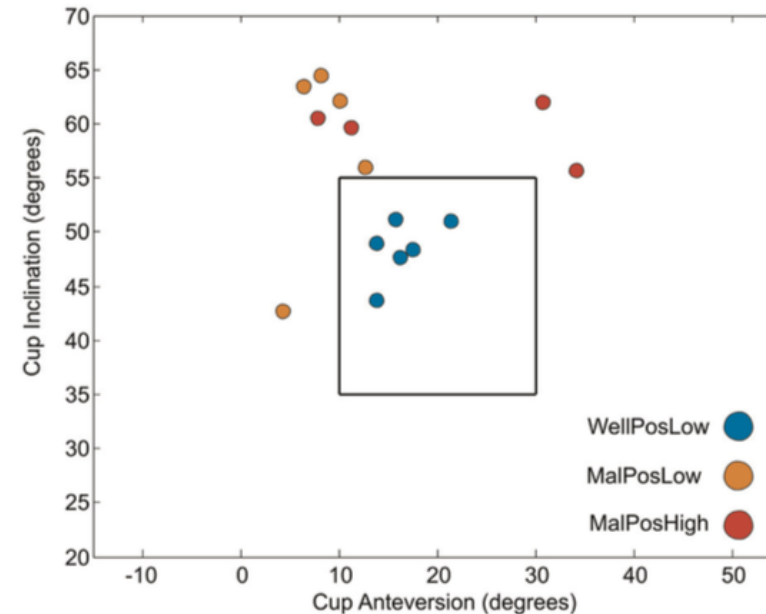
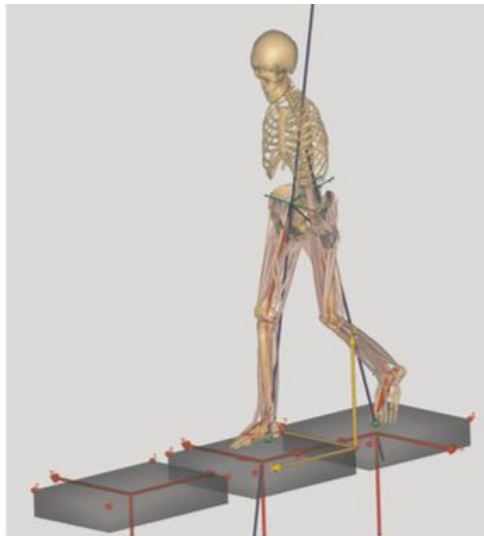


A = Acetabular abduction



Prosthesis Wear

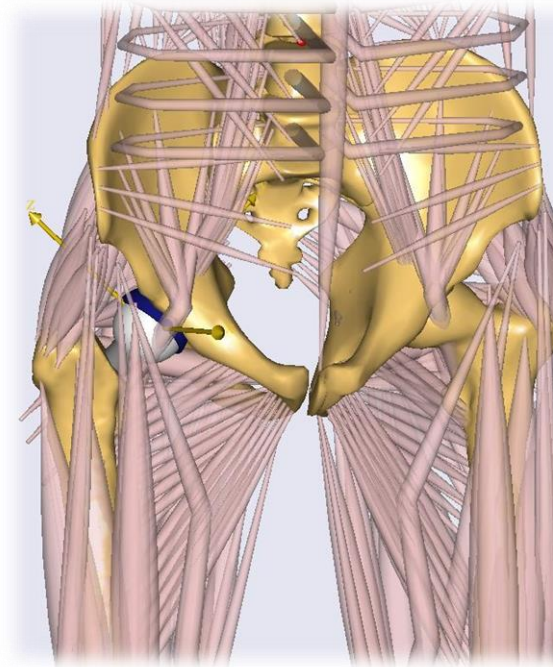
- Prosthesis wear is a patient-specific, biomechanical problem



- “wear of metal-on-metal hip resurfacing arthroplasty is ... influenced by individual patient activity patterns” Mellon et al, Proc IMechE Part H: J Engineering in Medicine 2013

Prosthesis Wear

- Wear is a function of use, not time⁴
 - Knowledge of internal loading needed for:
 - Implant design: wear and fixation
 - Understanding joint biomechanics
 - Surgical planning
 - Rehabilitation intervention
- In vivo measurements^{5,6}:
 - Raise ethical considerations
 - Are difficult to perform
 - Represent a small population sample



4. Schmalzried, TP., et al. Clin Orthop Res 381 (2000): 36-46.
5. Bergmann, G., et al. Journal of Biomechanics 34.7 (2001): 859-871.
6. Bergmann, G., et al. PLoS One 11(5) (2016): e0155612.

Exhaustive Proof Testing

Dauerschwingversuch
ISO 7206-4, 6 und 8



GeometrieKennwerte
ISO 7206-1/2



Kugel Torsionstest
ISO 7206-9



Verschleißversuch
ISO 14242-1



Simulation results allow the definition of more realistic and demanding physical wear tests

Kugel Abzugversuch
ASTM F 2009



Korrosionsversuch
ASTM F1875



Impingement Test
ASTM F 2582



Luxationsversuch
PI-1/2



Bewegungsumfang
ISO 21535

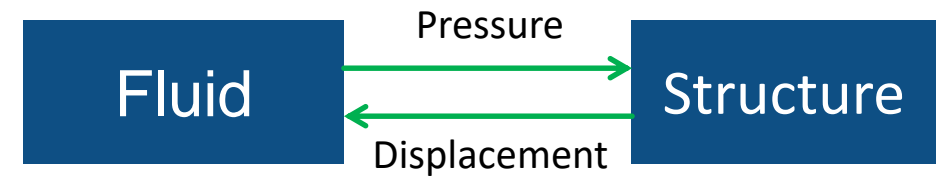
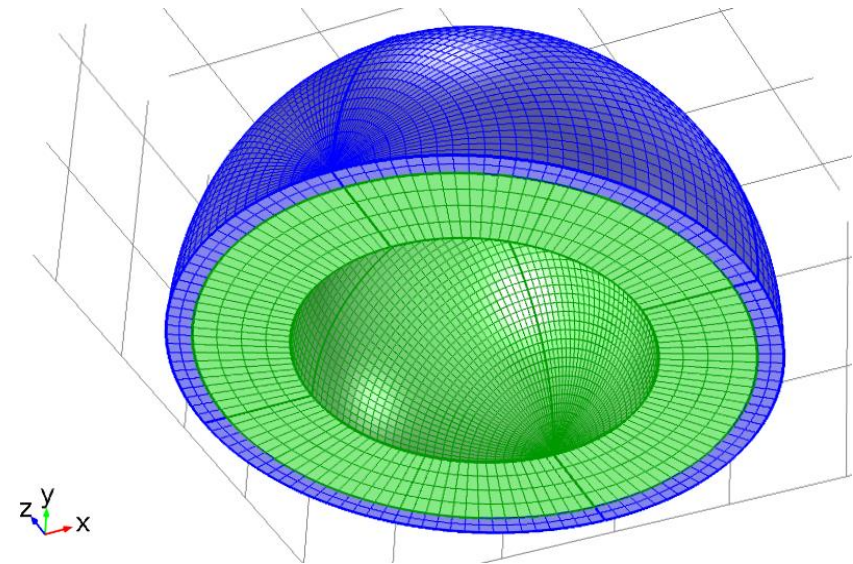


Dauerschwingversuch
Pfanneninserts
PI-11

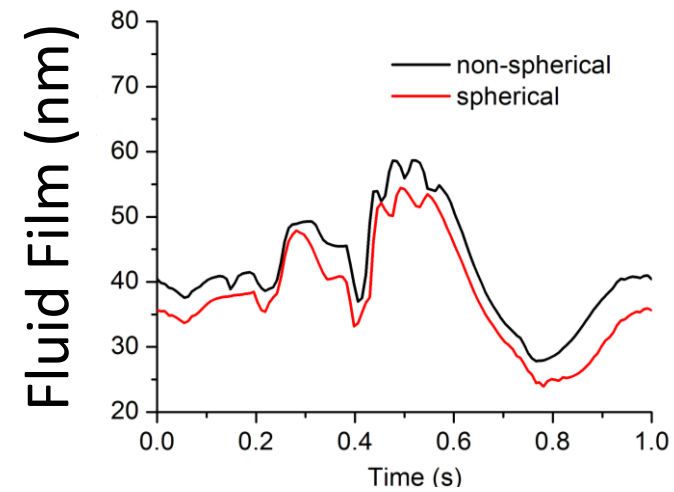
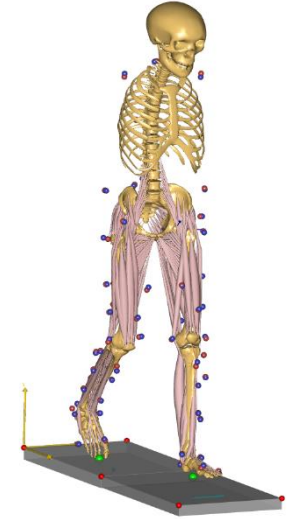
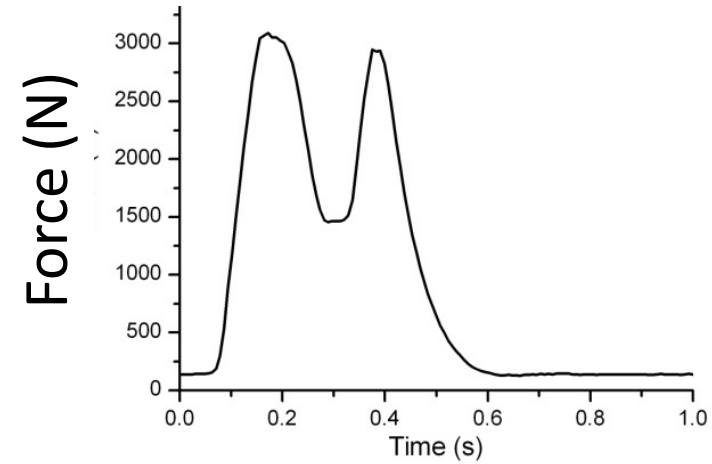
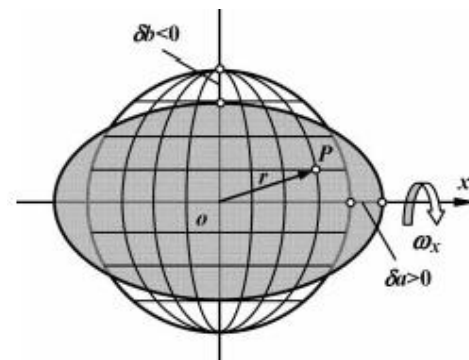
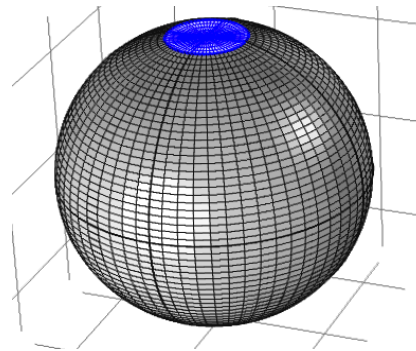
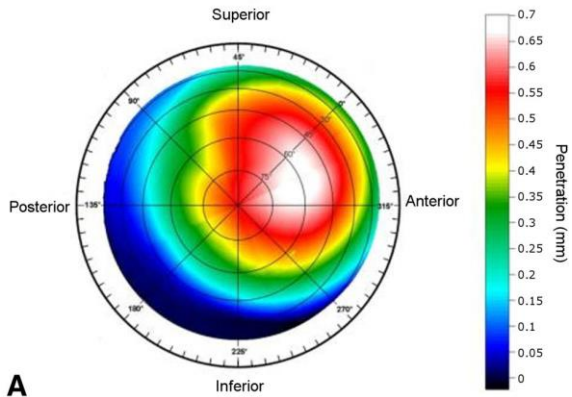


Joint Scale Wear Simulation

- Elastohydrodynamic (EHL) model developed of hip prosthesis
- Ball in socket geometry allows non-sphericity
- Elastic deformation of both cup and head materials



Whole Joint Wear Simulation





AnyBody Model – Development and Validation

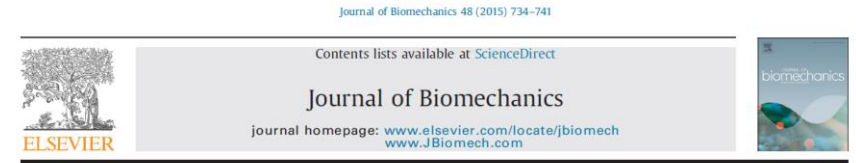
Population Simulations

Model Development

Need for a reliable generic model to predict hip contact forces

TLEM 2.0:

- Detailed dataset of musculoskeletal geometry
- Model implementation not thoroughly tested
- Particularly for applications focusing on hip



TLEM 2.0 – A comprehensive musculoskeletal geometry dataset for subject-specific modeling of lower extremity



V. Carbone^{a,*}, R. Fluit^{a,1}, P. Pellikaan^a, M.M. van der Krogt^{a,b}, D. Janssen^c, M. Damsgaard^d, L. Vigneron^e, T. Feilkas^f, H.F.J.M. Koopman^a, N. Verdonchot^{a,c}

^aLaboratory of Biomechanical Engineering, Faculty of Engineering Technology, MIRA Institute, University of Twente, Enschede, The Netherlands

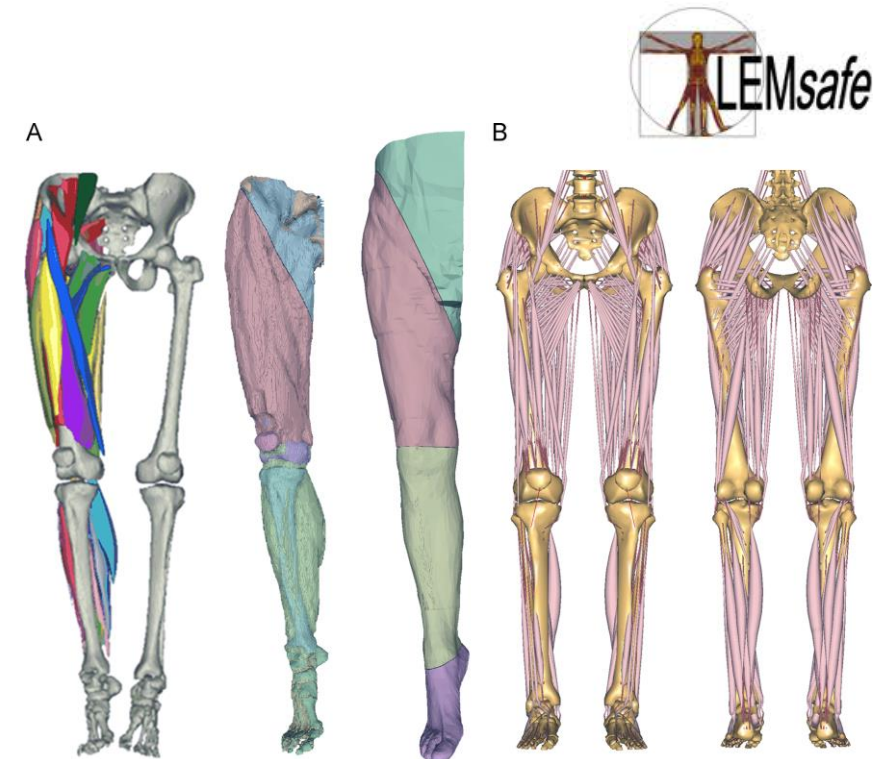
^bDepartment of Rehabilitation Medicine, Research Institute MOVE, VU University Medical Center, Amsterdam, The Netherlands

^cOrthopaedic Research Laboratory, Radboud University Medical Centre, Nijmegen, The Netherlands

^dAnyBody Technology A/S, Aalborg, Denmark

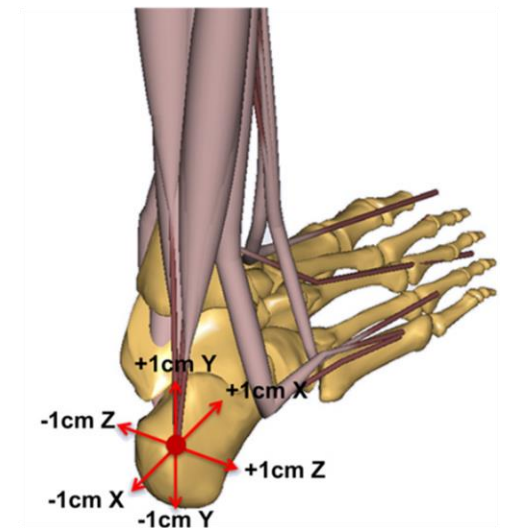
^eMaterialise N.V., Leuven, Belgium

^fBrainlab AG, Munich, Germany



Model Development

- Accuracy in muscle geometry can affect JCF predictions ^{7,8}
 - Models sensitive to muscle attachment points
 - Particularly muscles spanning the hip joint



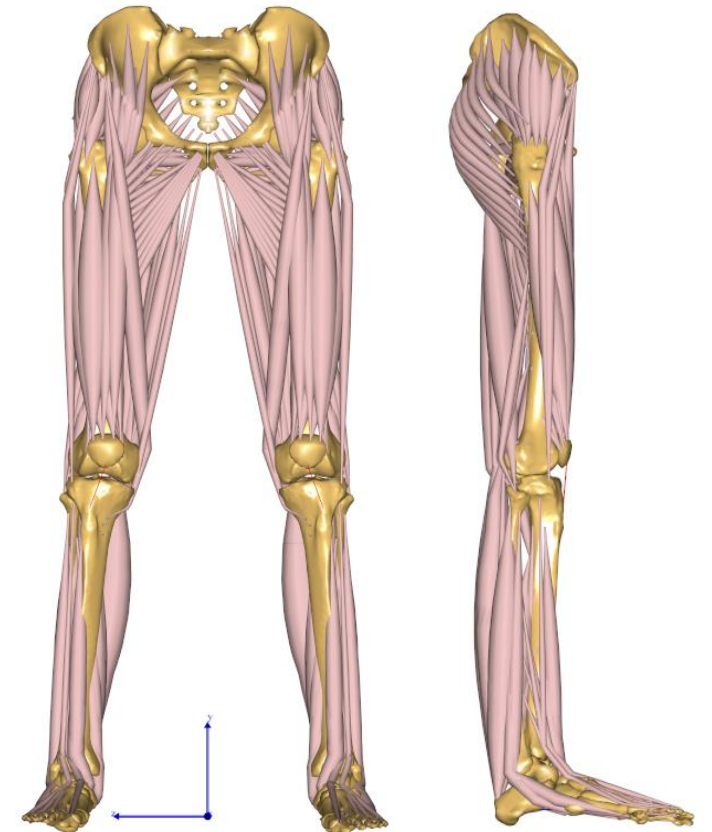
7. Carbone, V. et al

7. Carbone, V., et al. "Sensitivity of subject-specific models to errors in musculo-skeletal geometry." *Journal of Biomechanics* 45.14 (2012): 2476–80.

8. Bosmans, L., et al. "Sensitivity of predicted muscle forces during gait to anatomical variability in musculotendon geometry." *Journal of Biomechanics* 48.10 (2015): 2116–23.

Aims

- Document further development of a lower limb model
- Propose a working logic for identifying features in need of refinement
- Initial quantitative validation against measured hip contact forces



Model Validation

- Validation needed for clinical applications
 - Direct comparison with measured Joint Forces
 - Indirect comparison with EMGs

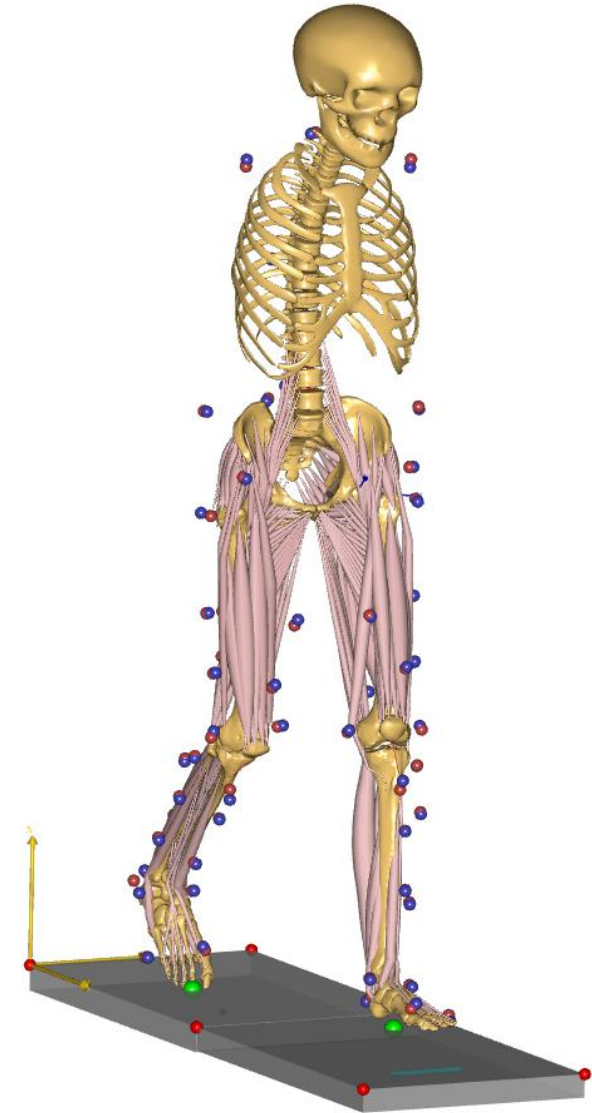
- Release of synchronized MoCap and instrumented HCF data⁹ sample

9. OrthoLoad (2016): 'H2R_150811_2_100_labelled.c3d', retrieved from <http://orthoload.com>, 'Date of access (28/09/2016)'



Model Setup

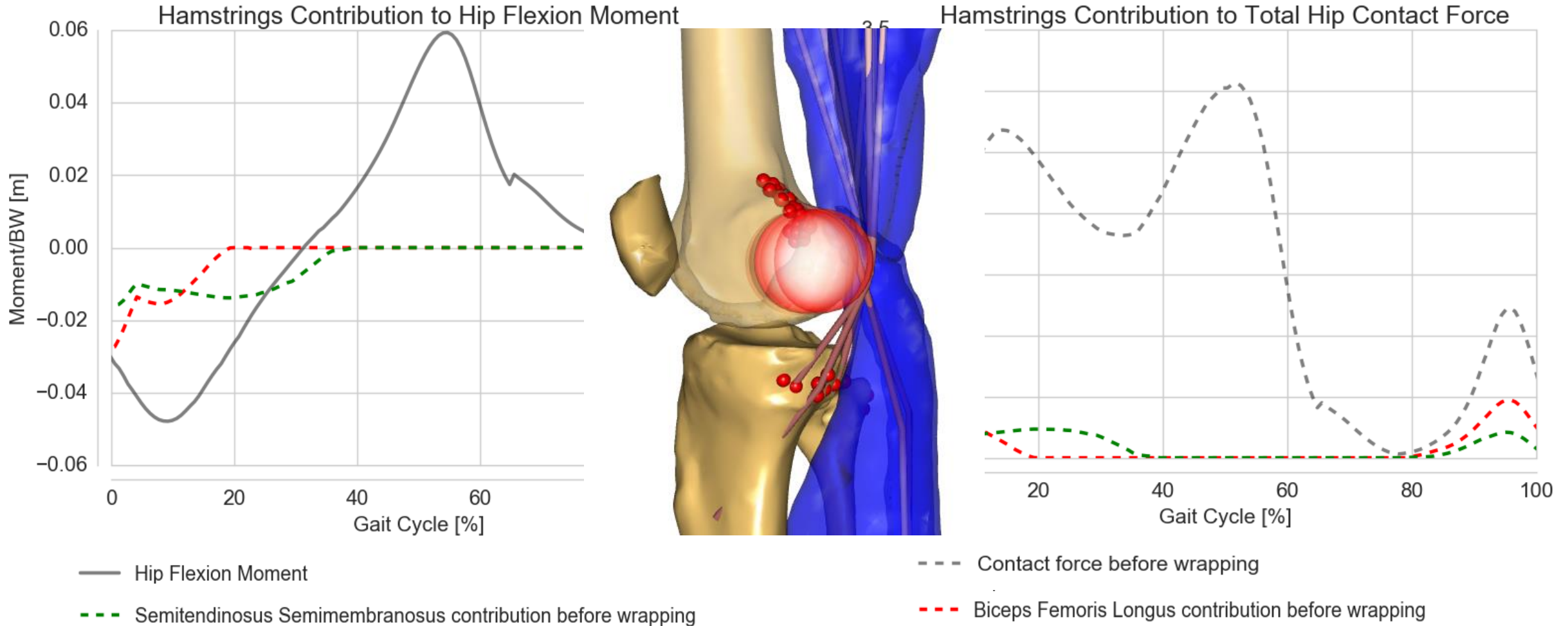
- Lower limb model based on TLEM 2.0 dataset
- 3-DOFs hip joint
- Simple muscle model
- Marker protocol and laboratory set-up (force plates) from Orthoload dataset
- Model linearly scaled (“Length-Mass-Fat” scaling law) and markers position optimized
- Inverse dynamics analysis



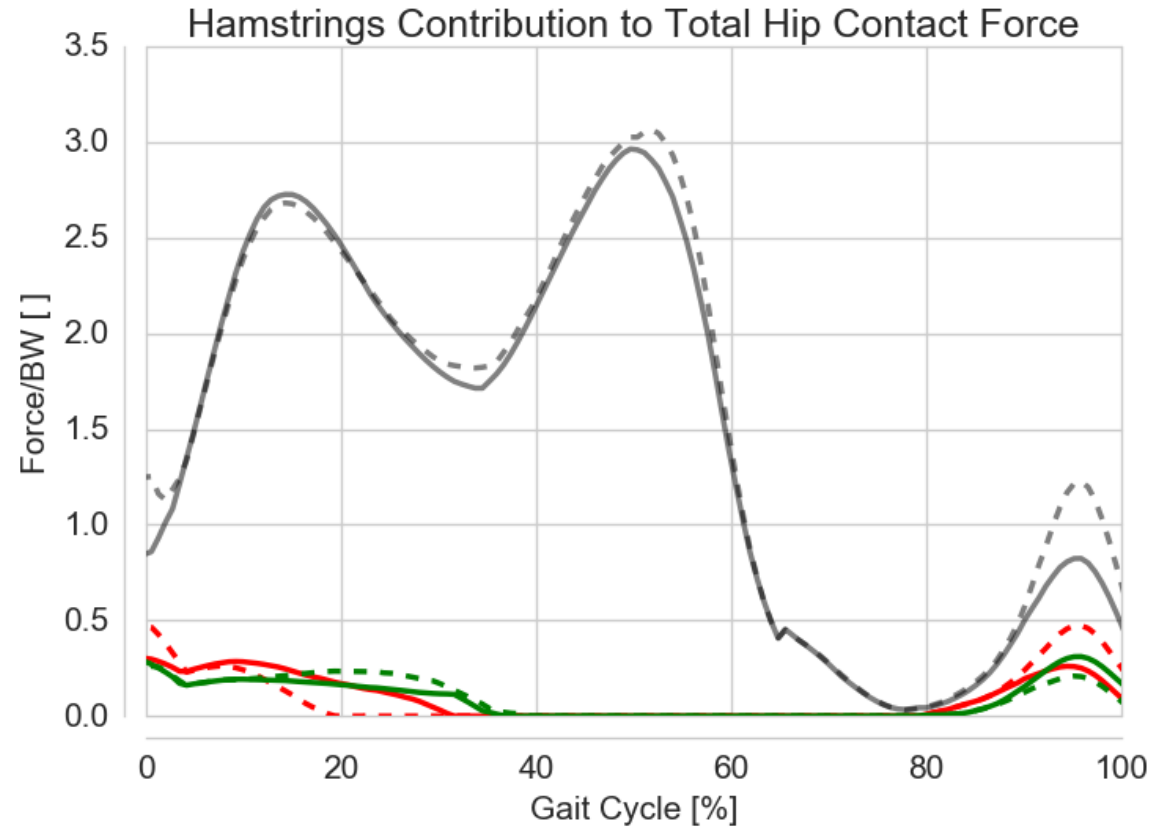
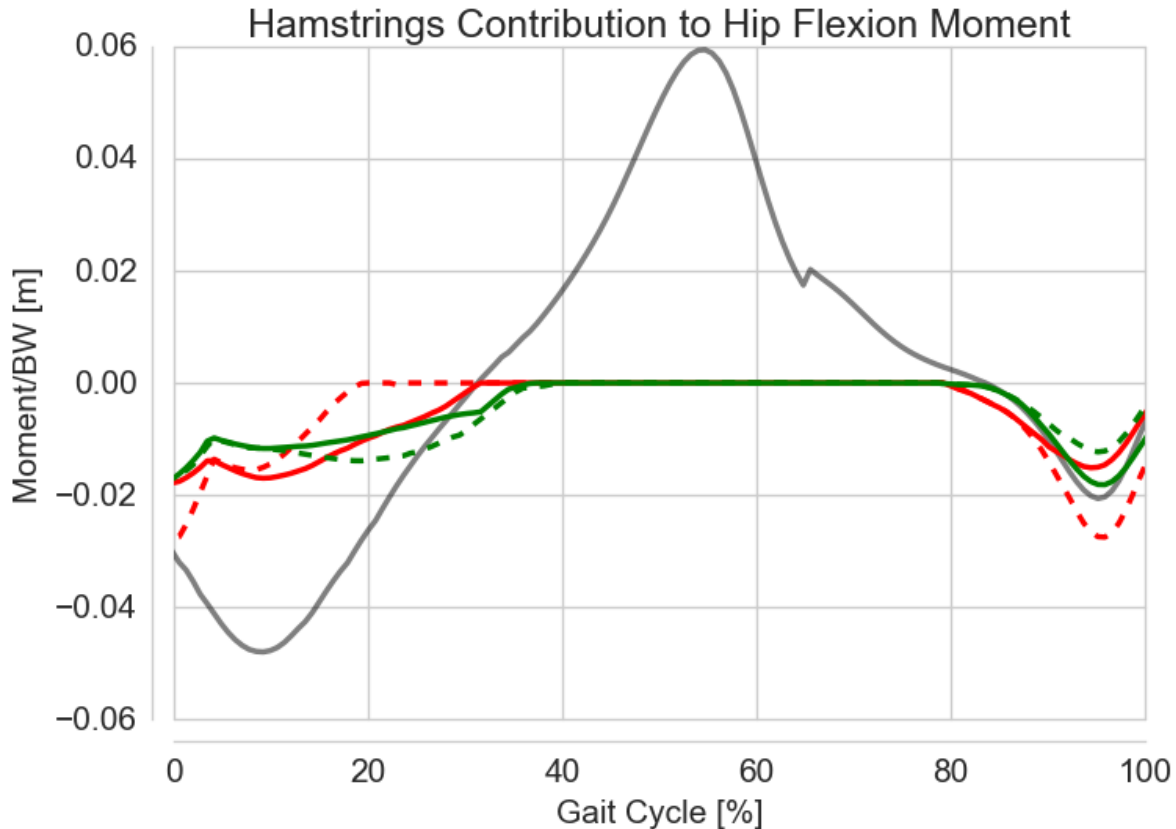
Muscle Contributions

- Evaluate muscle contribution to HCF and hip joints moment
- Identify critical muscle geometries:
 - High HCF contributions but relatively low joint moment contributions
 - Joint moment contributions higher than net moment
- Identified muscles compared to original MRI scans from TLEM 2.0
- Muscle geometry was modified if necessary

Muscle Contributions Example – Hamstrings



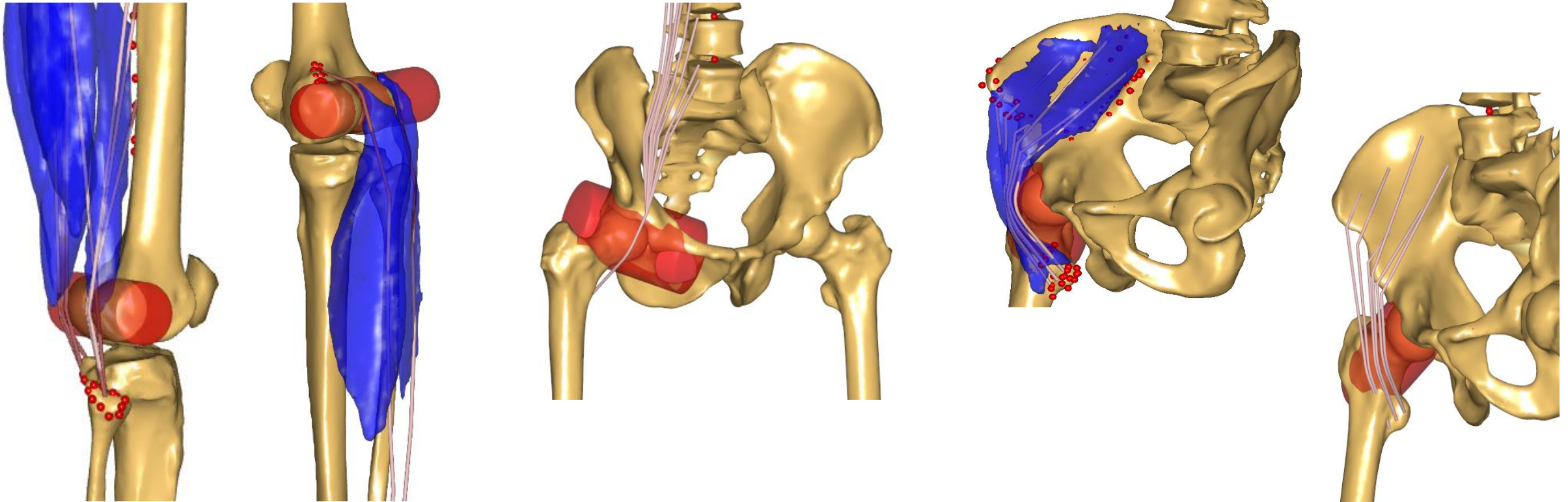
Muscle Contributions Example – Hamstrings



- Hip Flexion Moment
- - - Contact force before wrapping
- Contact force after wrapping
- - - Biceps Femoris Longus contribution before wrapping
- Biceps Femoris Longus contribution after wrapping
- - - Semitendinosus Semimembranosus contribution before wrapping
- Semitendinosus Semimembranosus contribution after wrapping

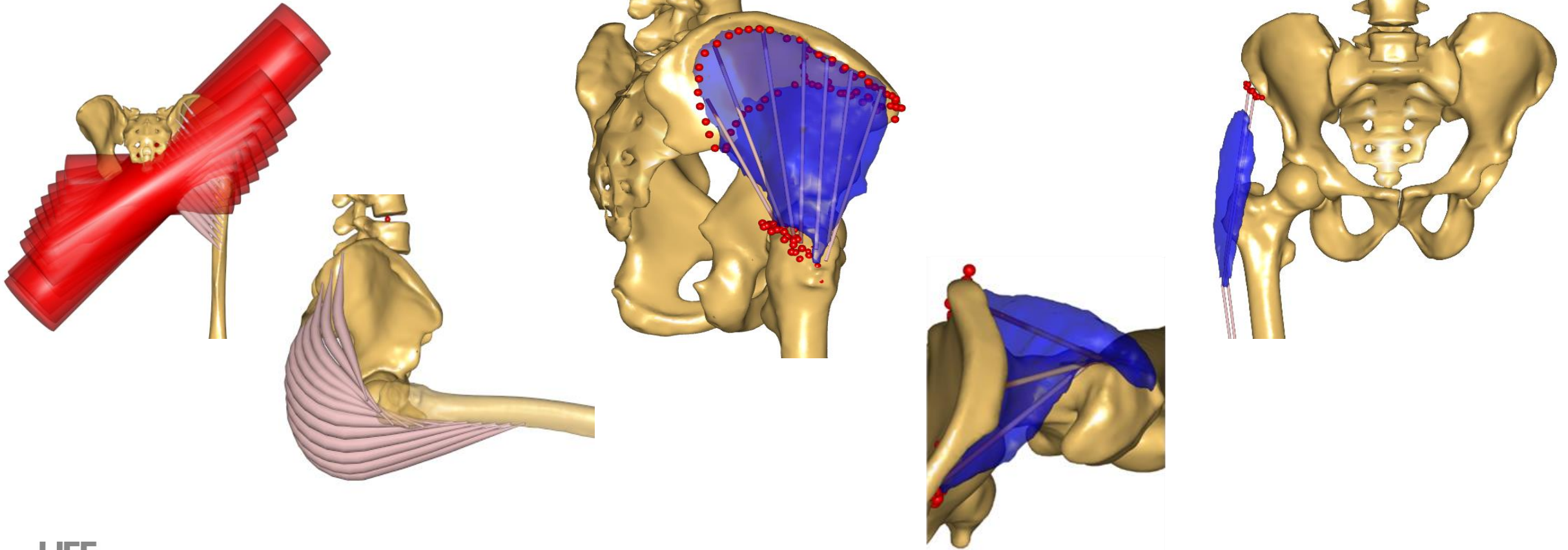
Model Development

- Accurate wrapping of Semimembranosus, Semitendinosus, Rectus Femoris, Gastrocnemius, Iliacus, and Psoas



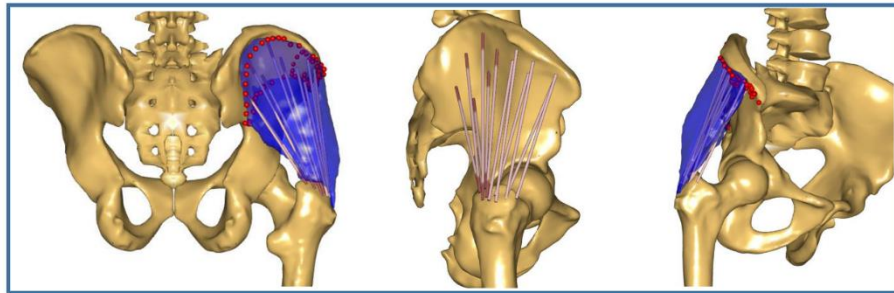
Model Development

- Accurate wrapping of Gluteus Maximus, Gluteus Medius and Minimus, and Tensor Fasciae Latae

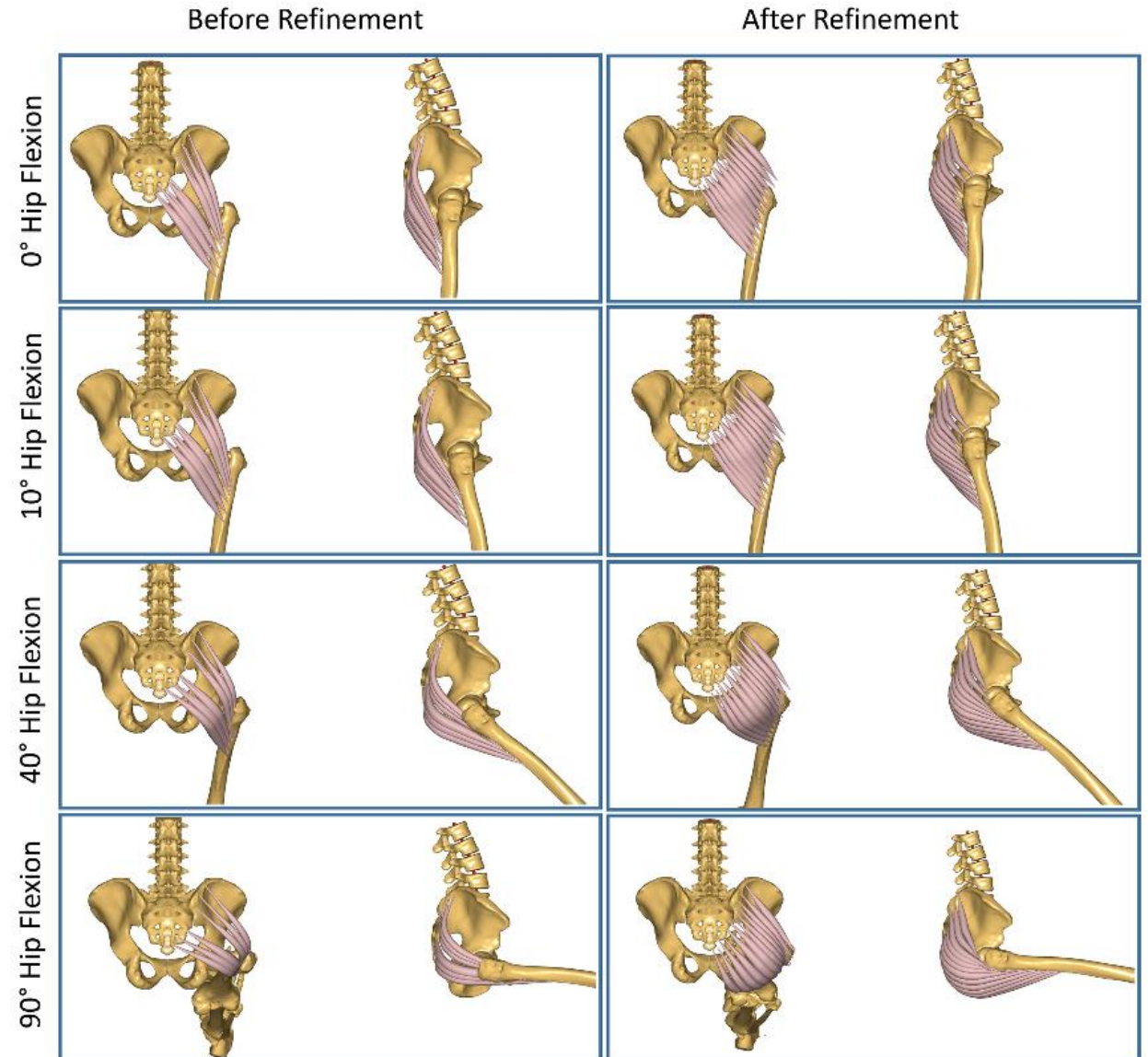
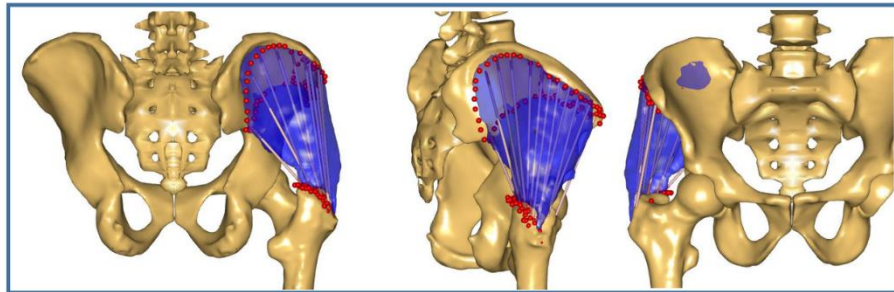


Model Development

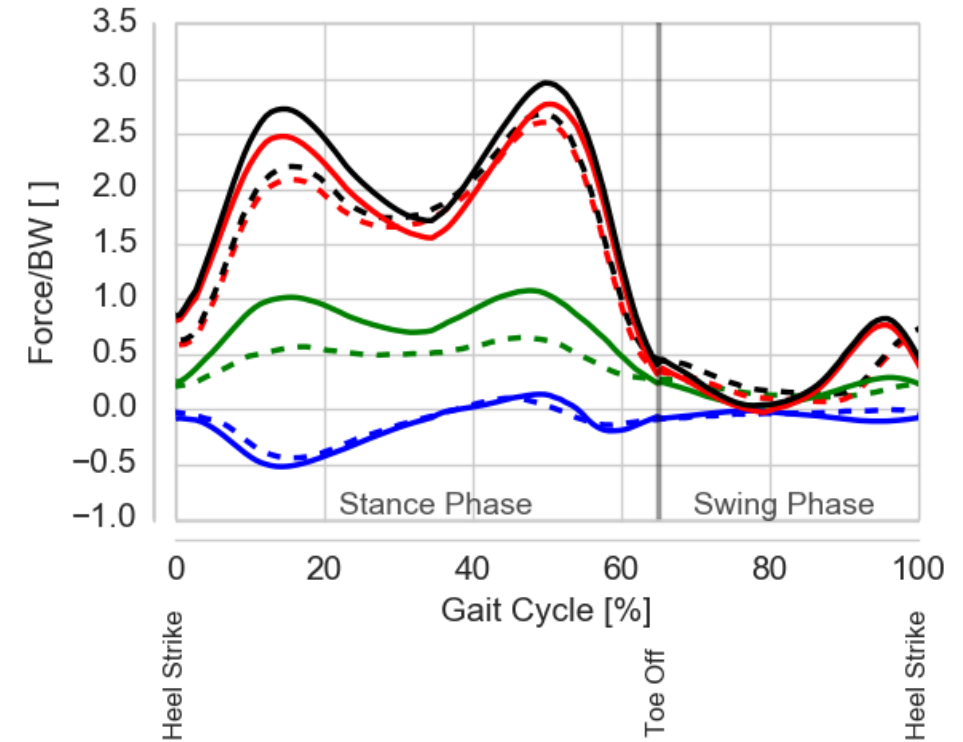
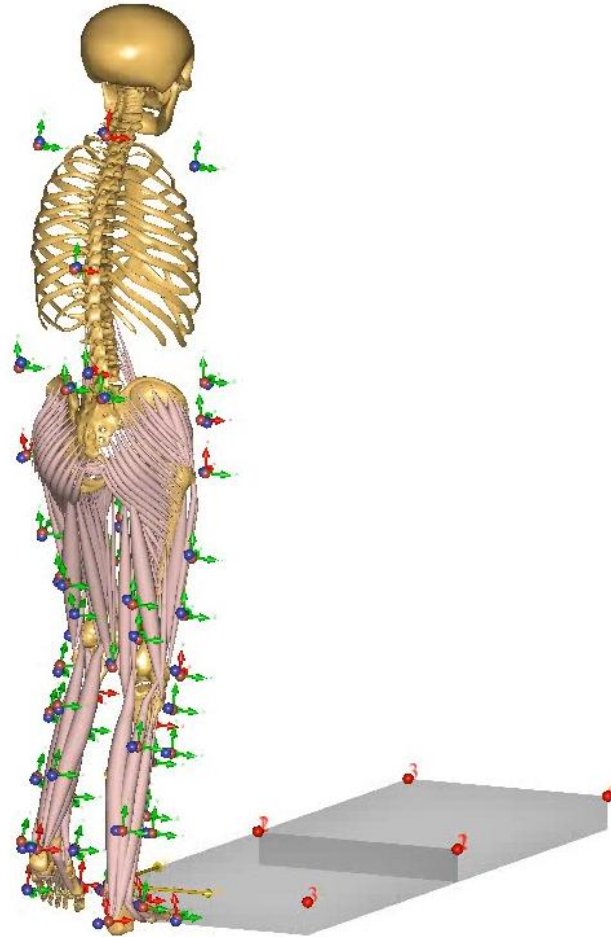
Before Refinement



After Refinement



Model Validation

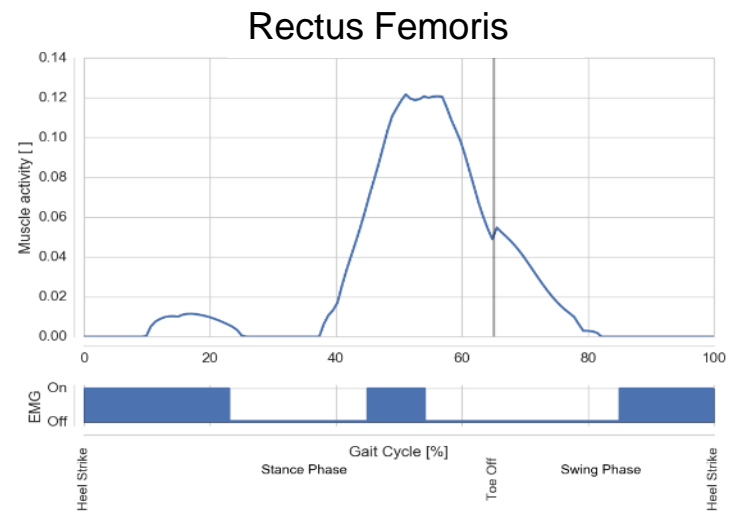
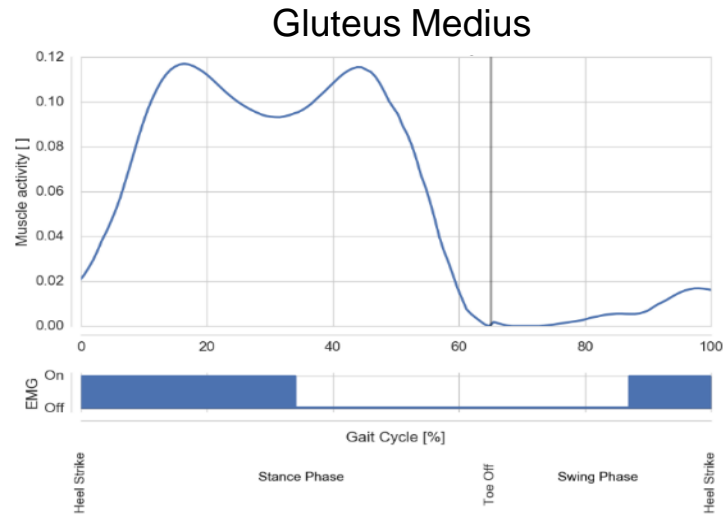
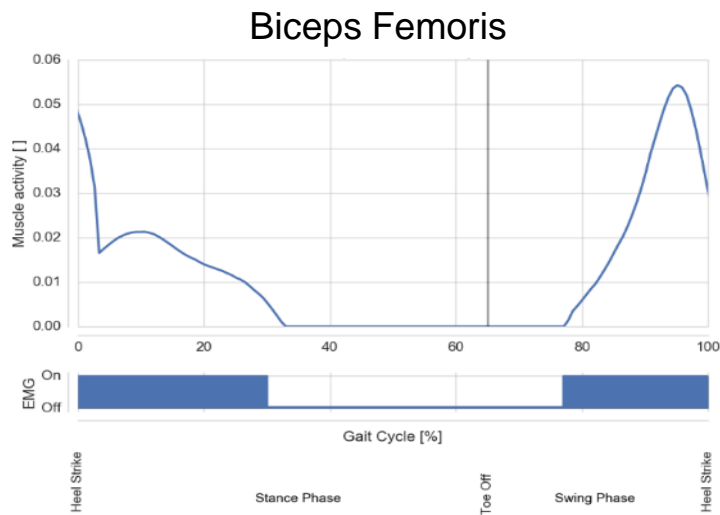
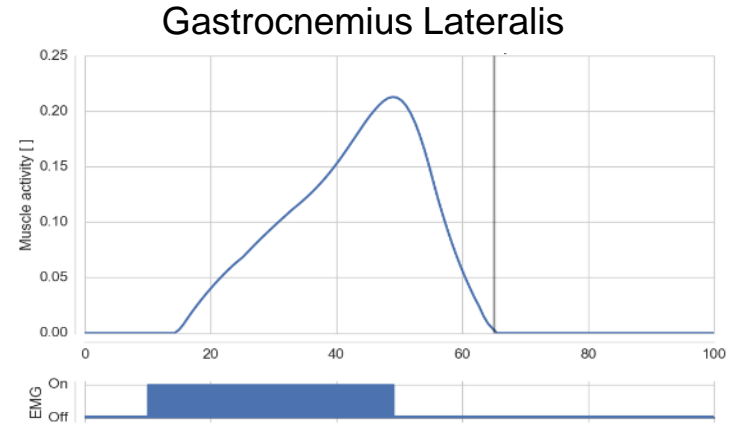
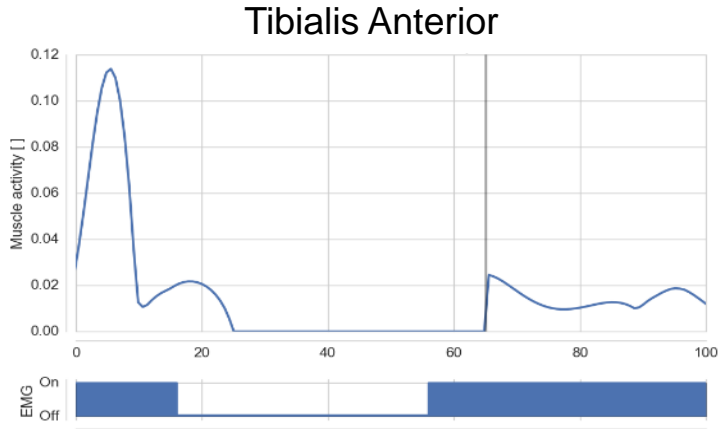


- Measured Hip Medio Lateral Force
- Measured Hip Antero Posterior Force
- Measured Hip Proximo Distal Force
- Total Measured Hip Force
- Predicted Hip Medio Lateral Force
- Predicted Hip Antero Posterior Force
- Predicted Hip Proximo Distal Force
- Predicted Total Hip Force

Good agreement with measured HCF

$$\text{RMSE} = 0.298 \cdot \text{BW} \text{ (228 N)}$$

Predicted Muscle Activity vs EMG Timing

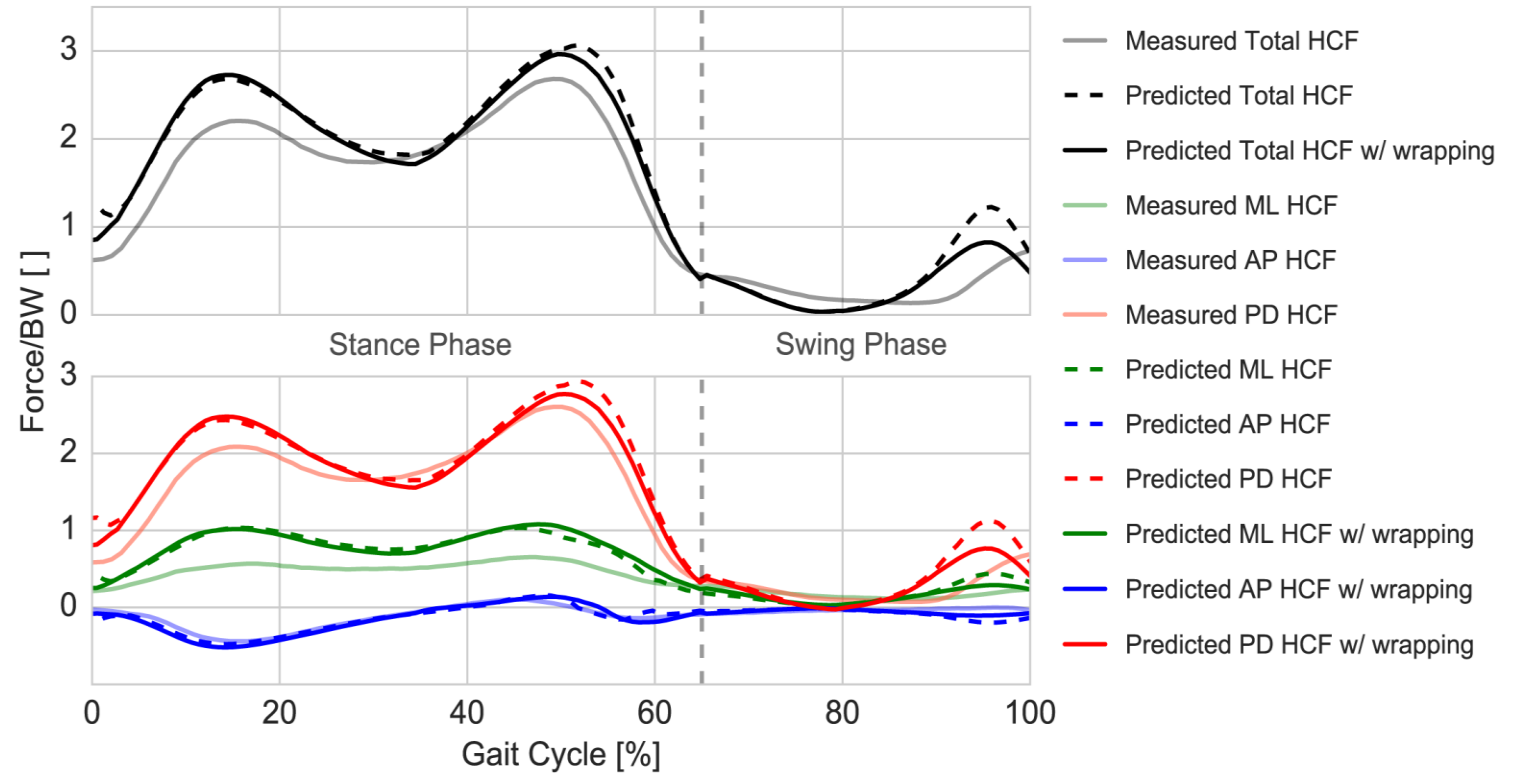


10. Agostini, V., et al. "Gait parameters and muscle activation patterns at 3, 6 and 12 months after total hip arthroplasty." Journal of Arthroplasty 28.7 (2014): 762-9.

Discussion

■ Muscle Refinement

- RMSE reduced by 17%
(max. error reduction 56%)



- Good agreement with measured HCF
 - Some over-prediction persists

- Good agreement with average EMG timing from literature

Limitations

Model Development

- TLEM 2.0 based on single cadaver
- Simple muscle model and knee kinematics
- No subject specific bone geometry

Quantitative Validation

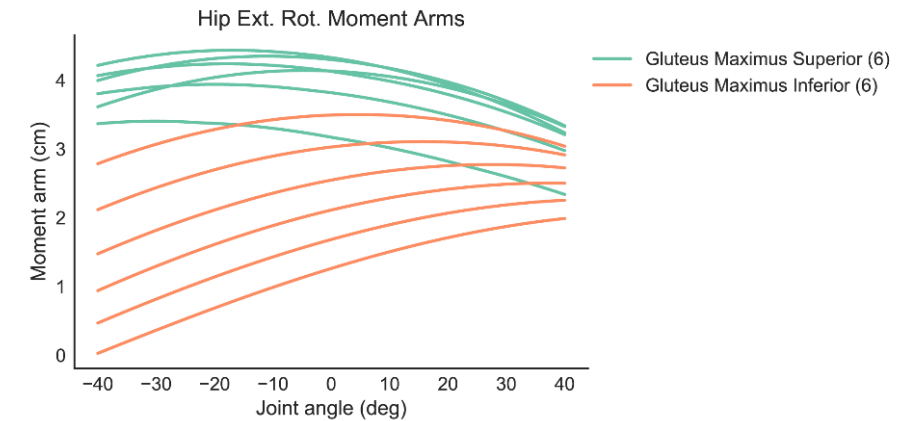
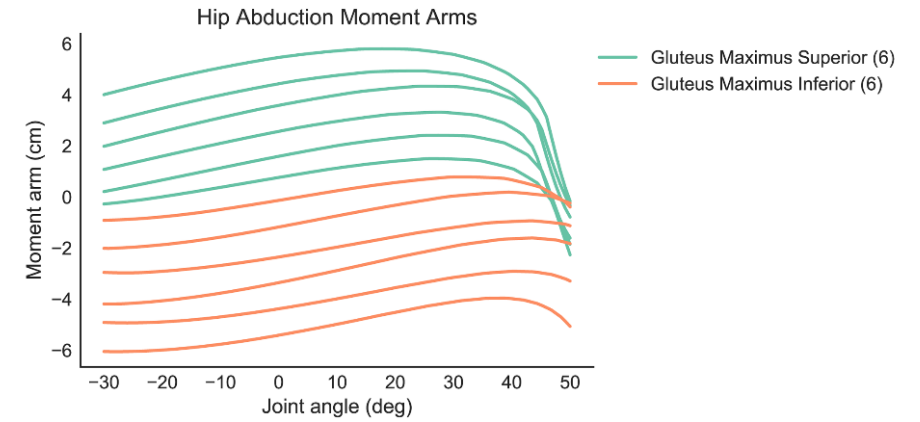
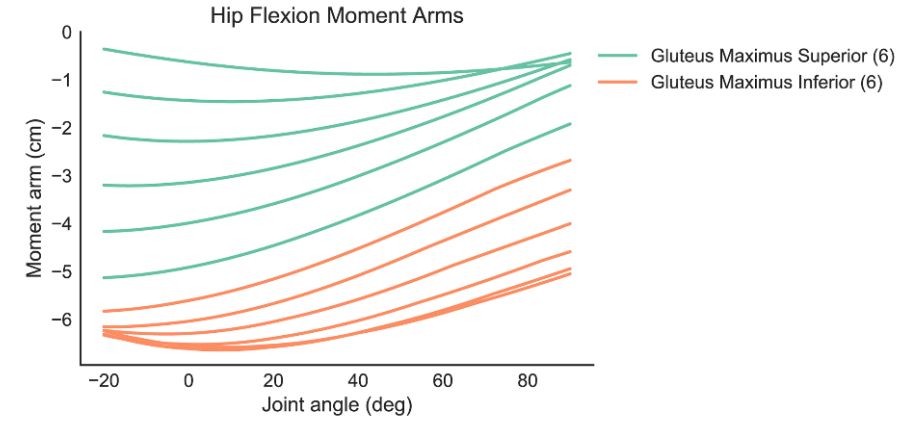
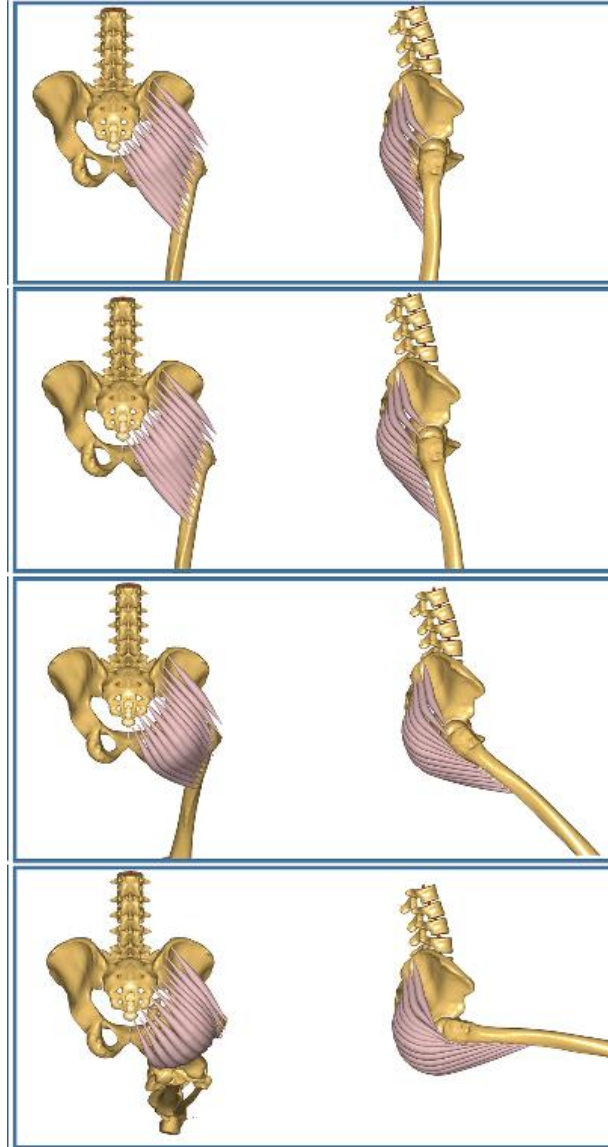
- Performed against a single trial from a single subject
- No variability in anatomy nor kinematic inputs

Additional release of sample data would be beneficial

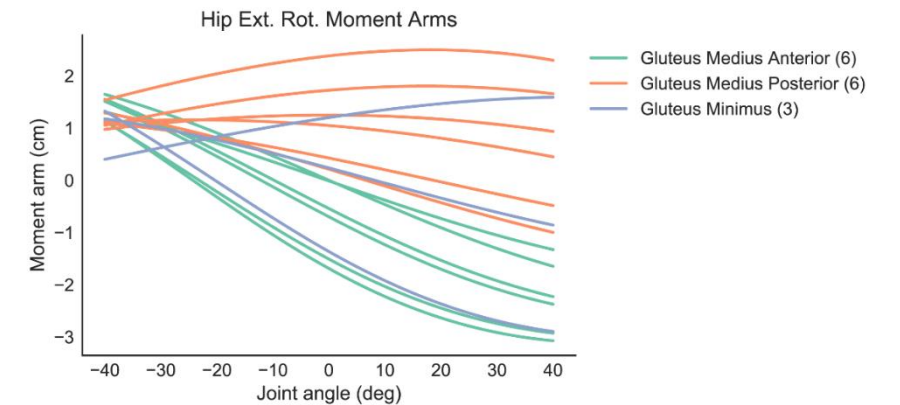
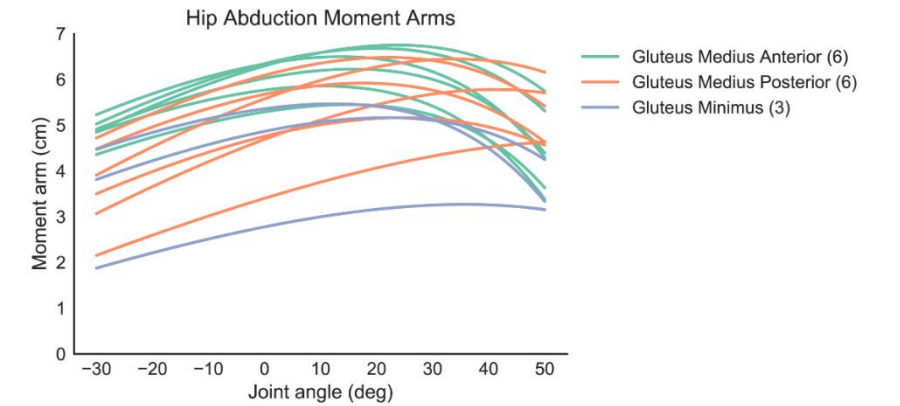
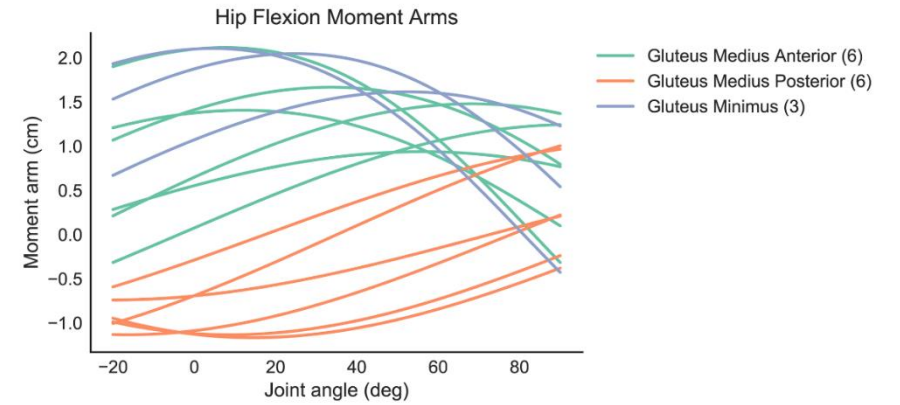
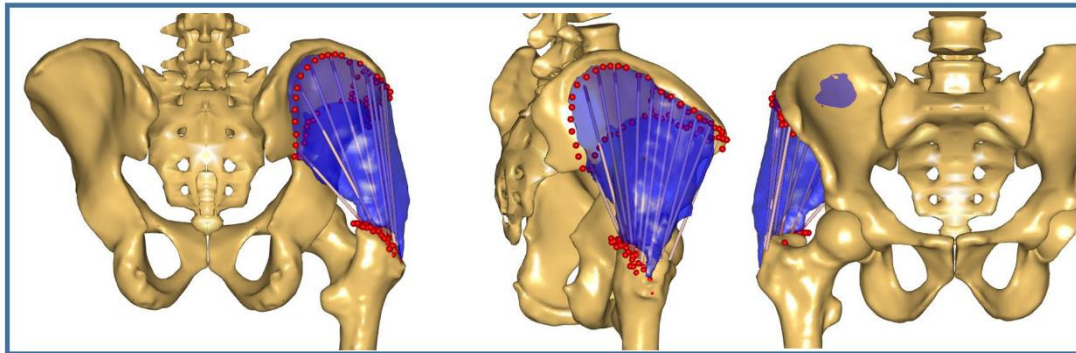
Conclusion

- Satisfactory level of geometrical accuracy achieved
 - Improved HCF predictions
- Initial step in the validation process
- Model has to be continuously validated for new applications
 - Important for activities other than gait
- Muscle moment arms can provide indication for potential limitations

Muscle moment arms ranges



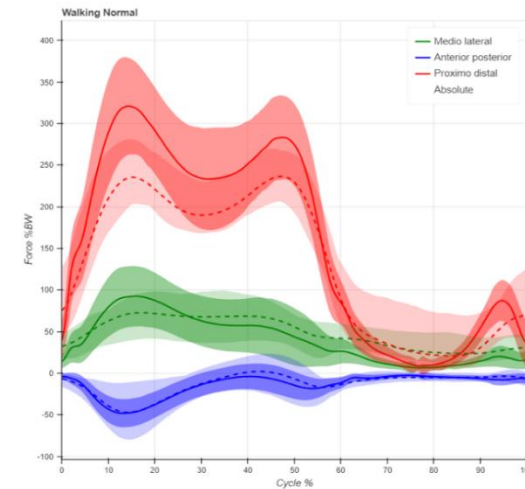
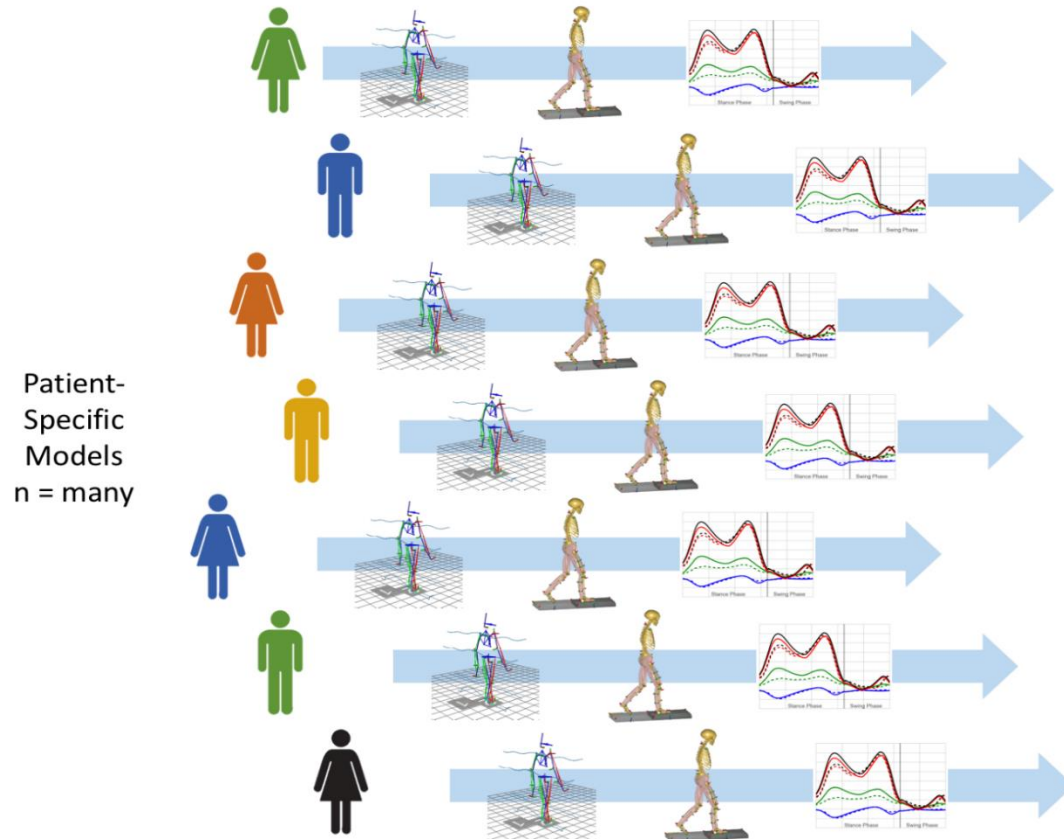
Muscle moment arms ranges



Development of a generic musculoskeletal model ✓


Submitted to PLOS One

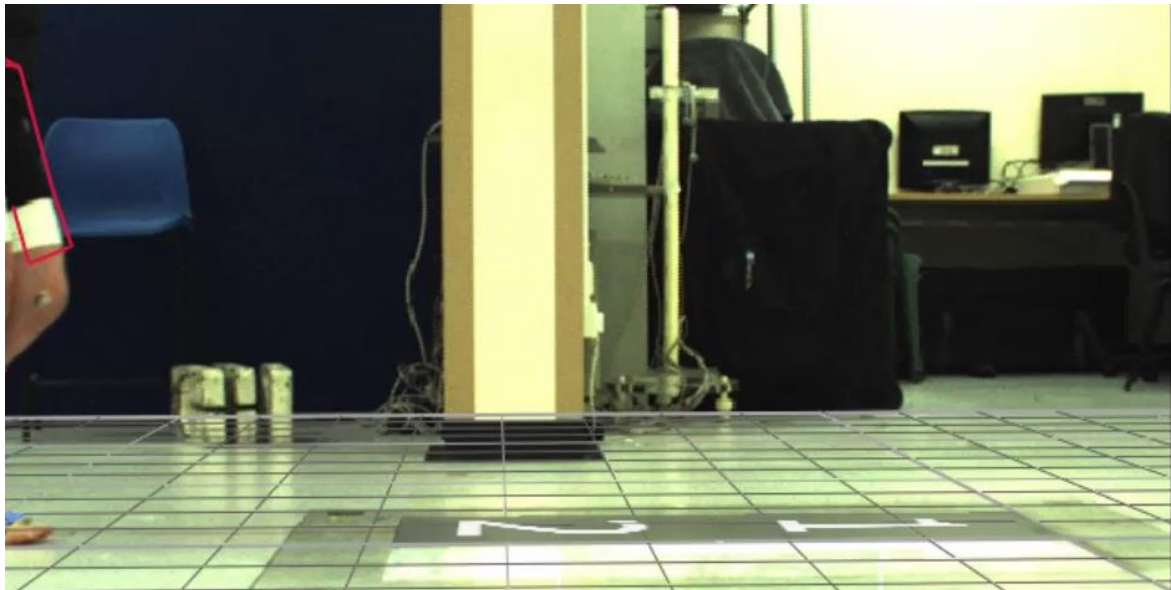
Virtual Patient Population



Population Simulations across different Activities of Daily Living

- Important to address variability in overall population
- **LLJ Patients Dataset**
 - MoCap measurements carried out at Leeds Teaching Hospitals
 - Large patient cohort (137 patients)

The Leeds Teaching Hospitals 
NHS Trust

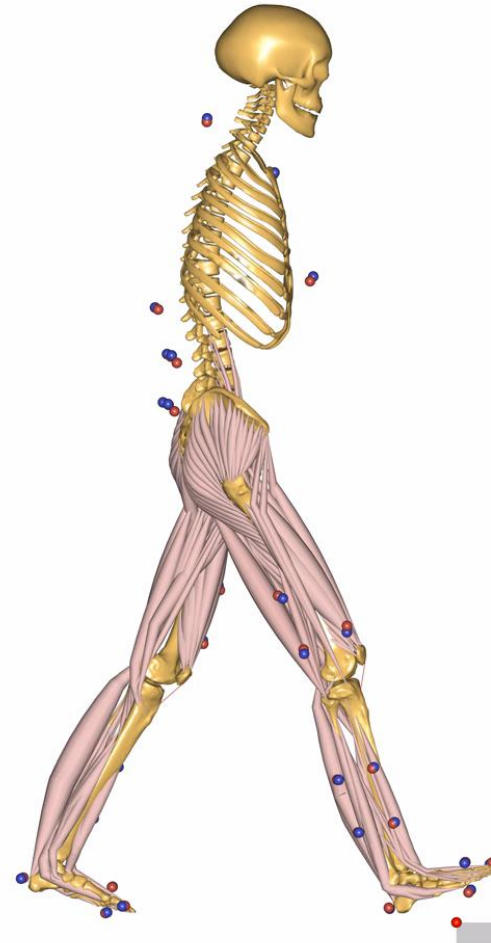
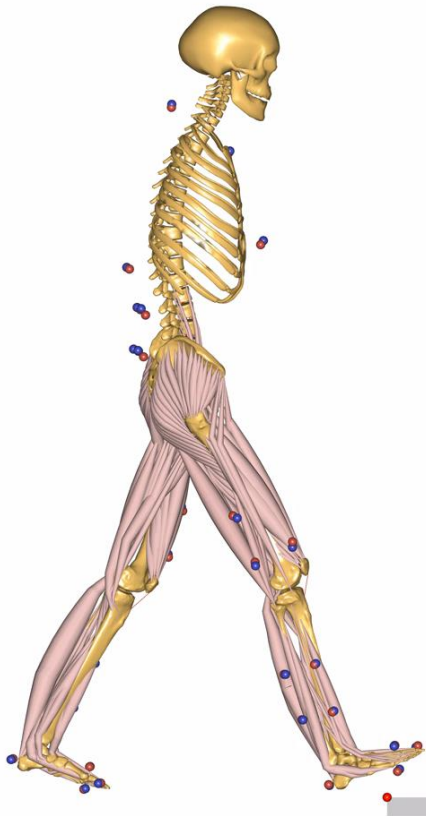


Previous webcast:

**LIFE
LONG
JOINTS**

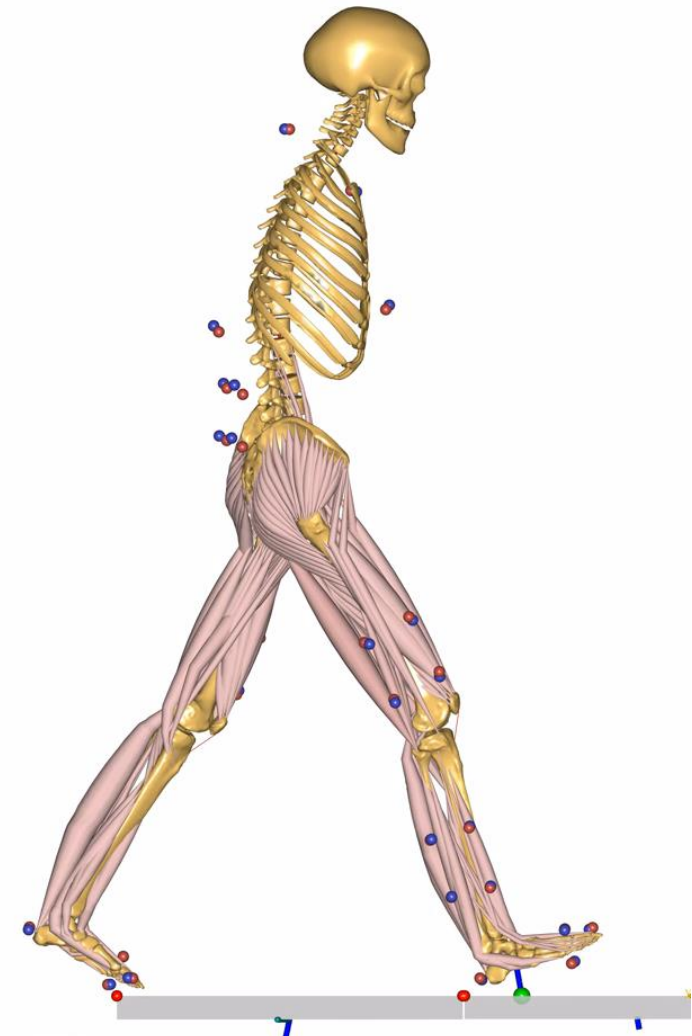
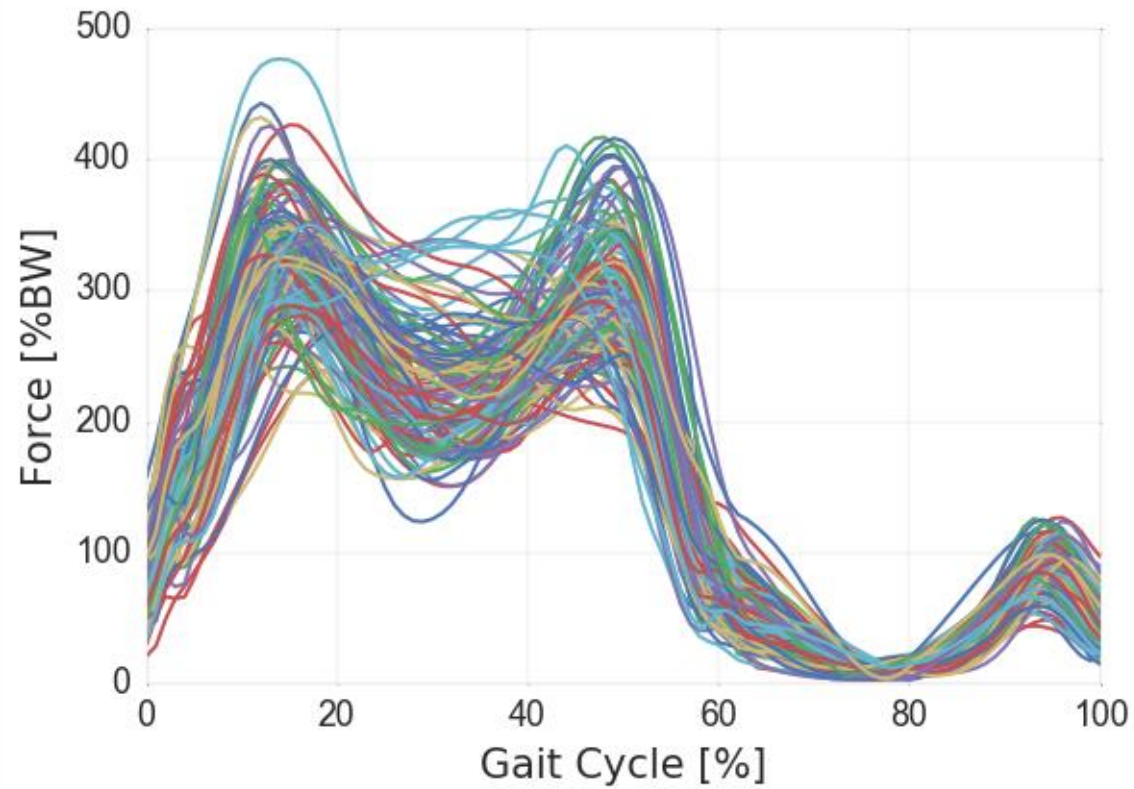
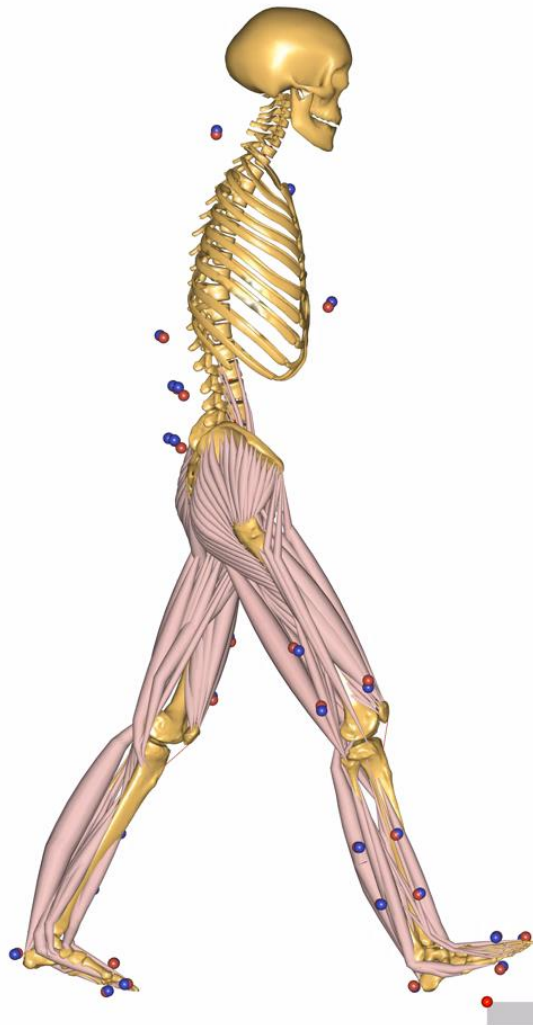
**Large Dataset for assessment
of joint replacements**

AnyBody - Batch Processing

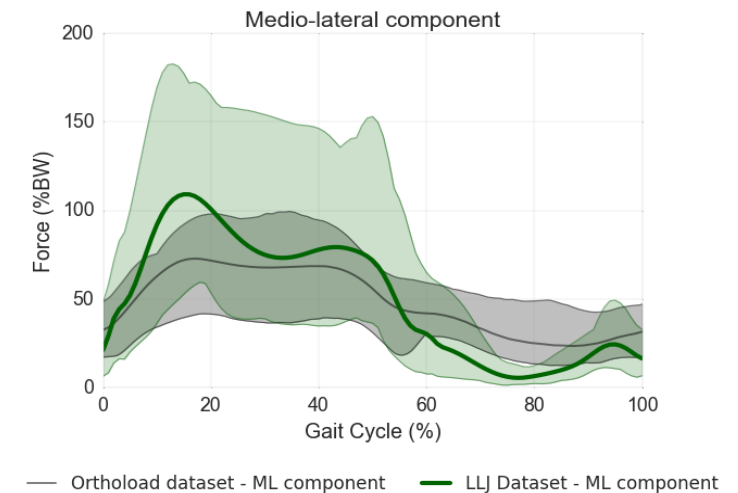
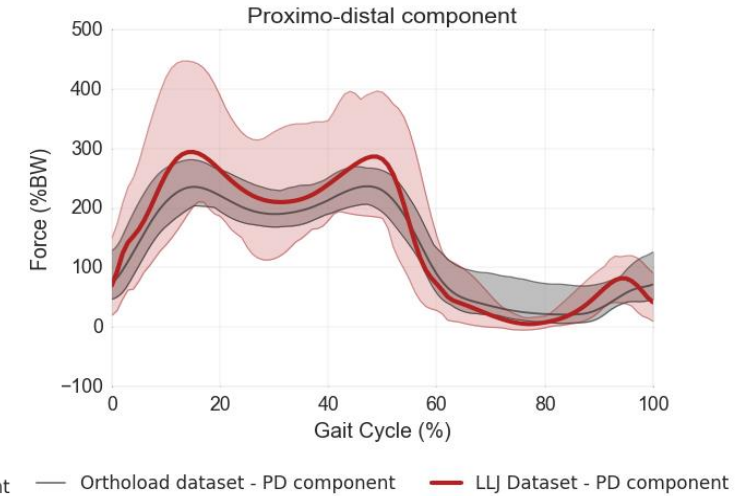
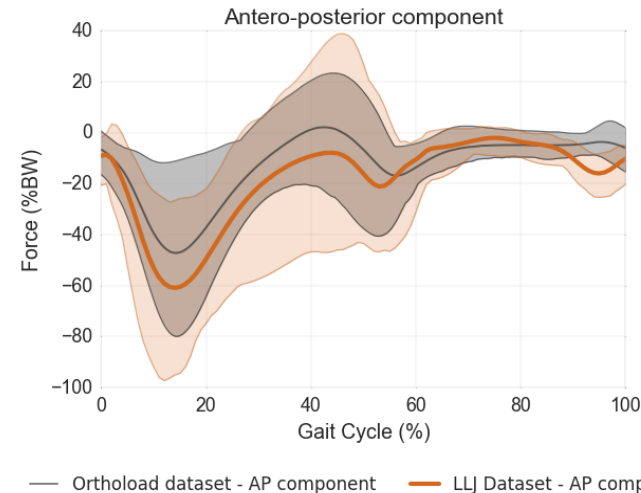
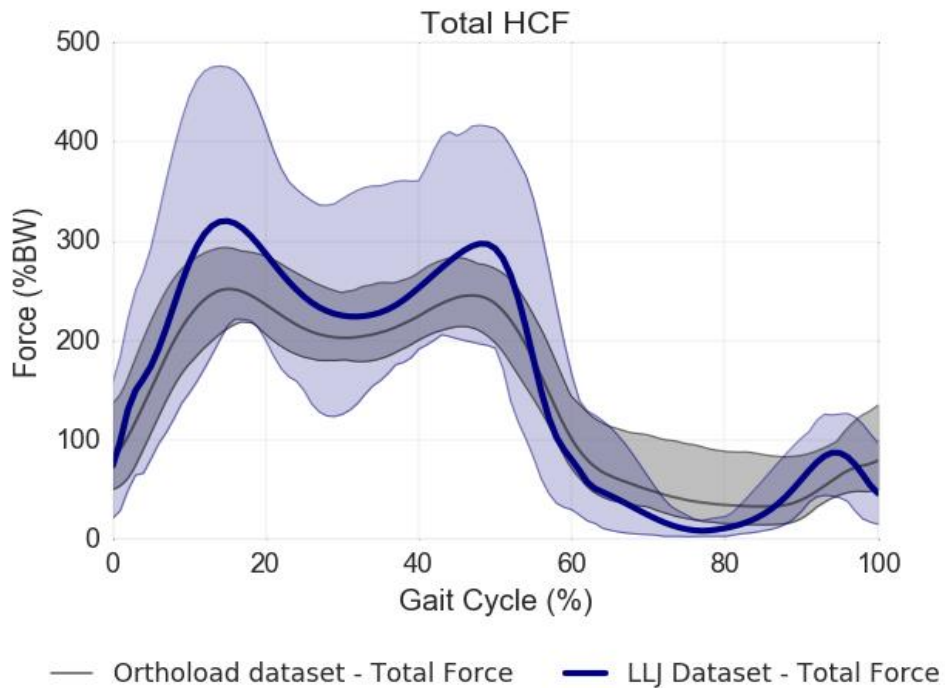


HCF variability during gait

- 132 patients
- 494 gait trials at self-selected speed

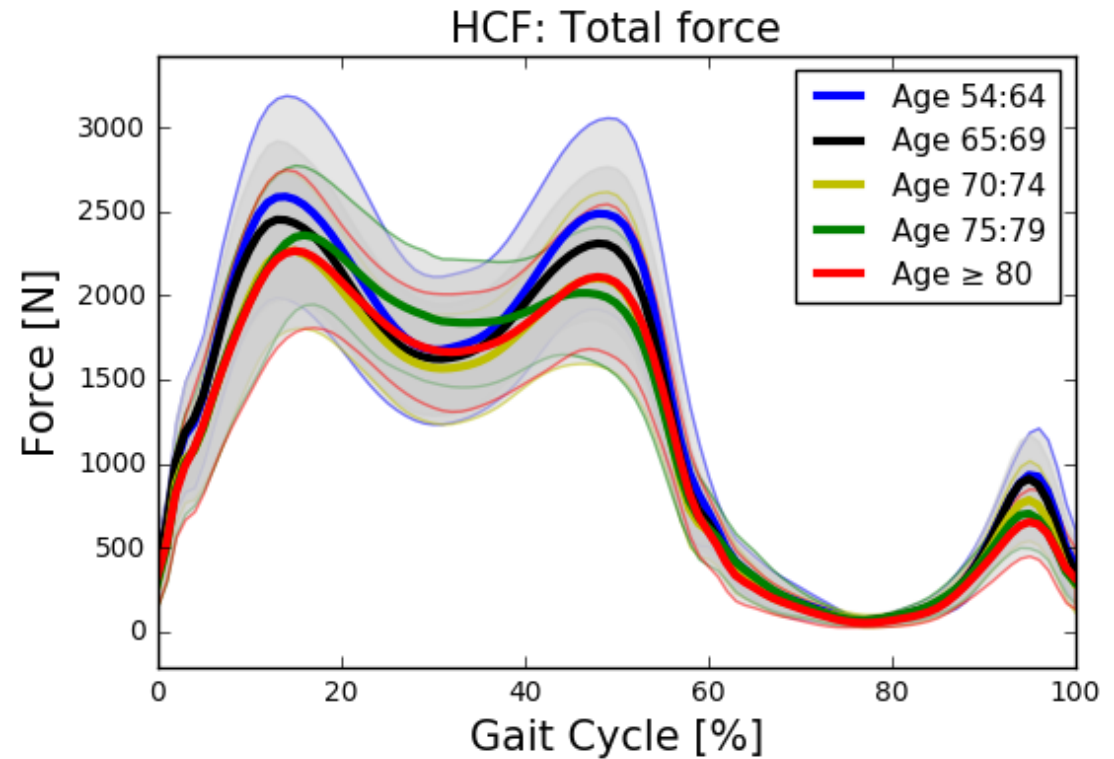
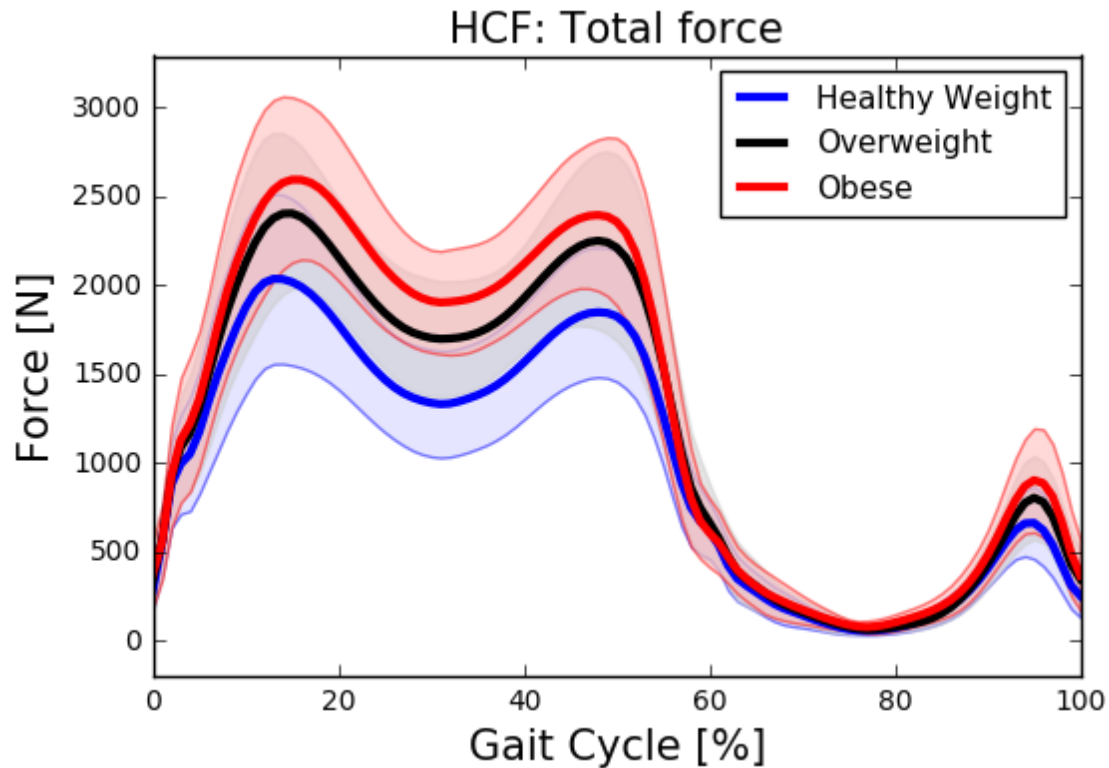


Qualitative comparison against Orthoload dataset



- Predictions' mean within Orthoload dataset range
- Larger variability

Effect of Patients' Characteristics on HCF



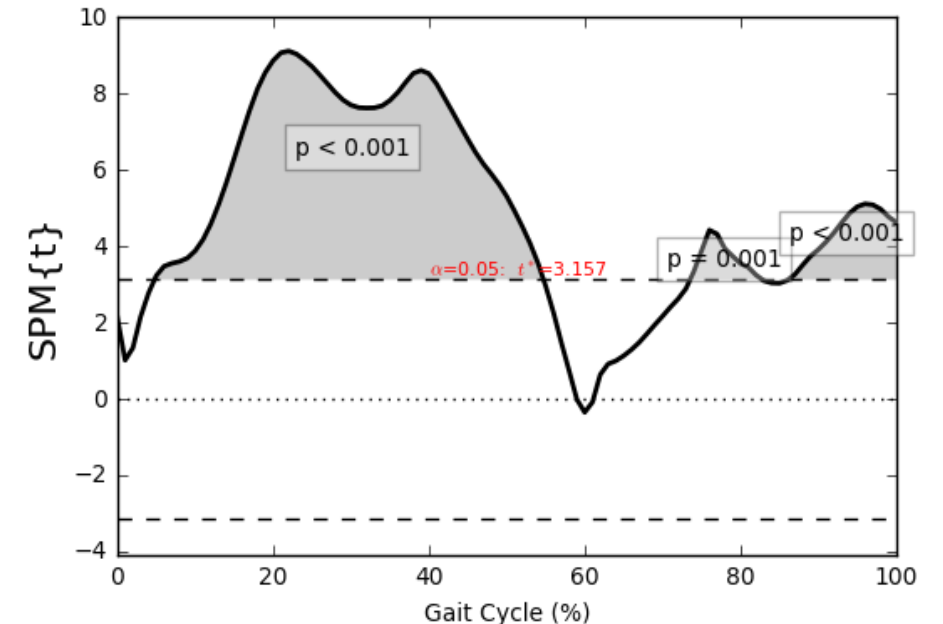
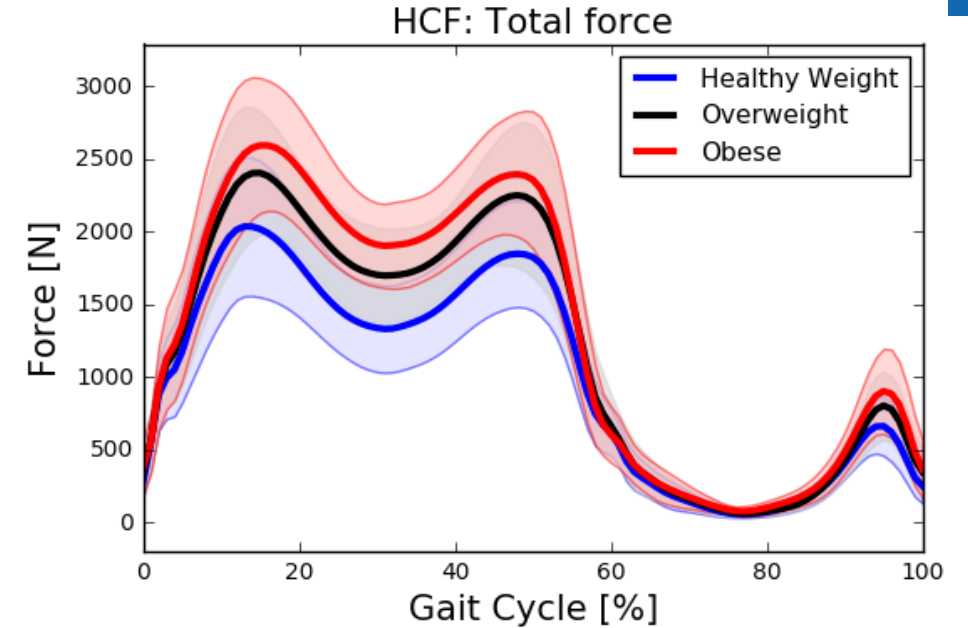
Population Stratification using Statistical Parametric Mapping (SPM)

There are significant differences in HCF, whether we stratify them BMI, age, or gait speed

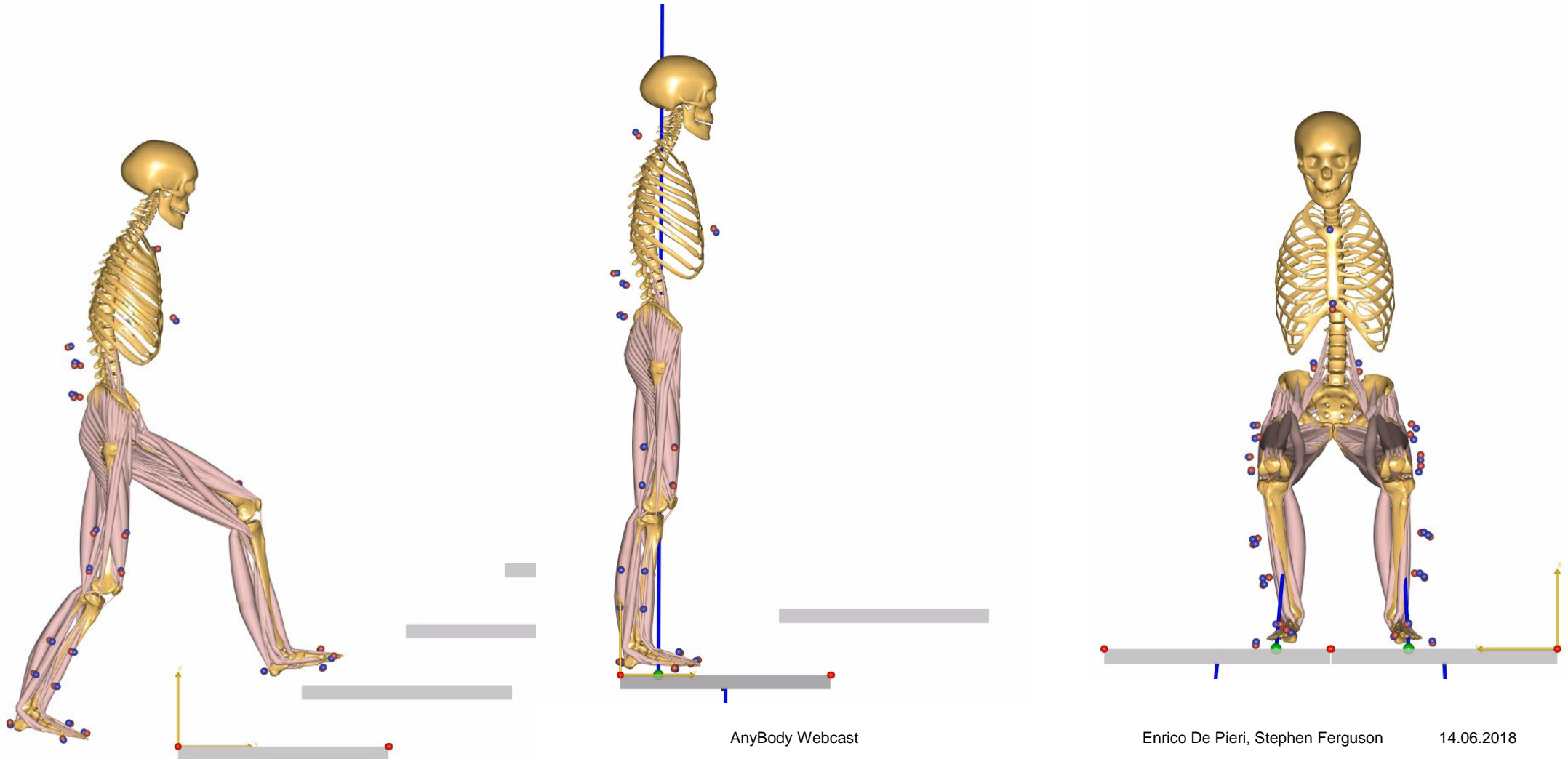


**8th World Congress
of Biomechanics**
8-12 July 2018
Dublin, Ireland

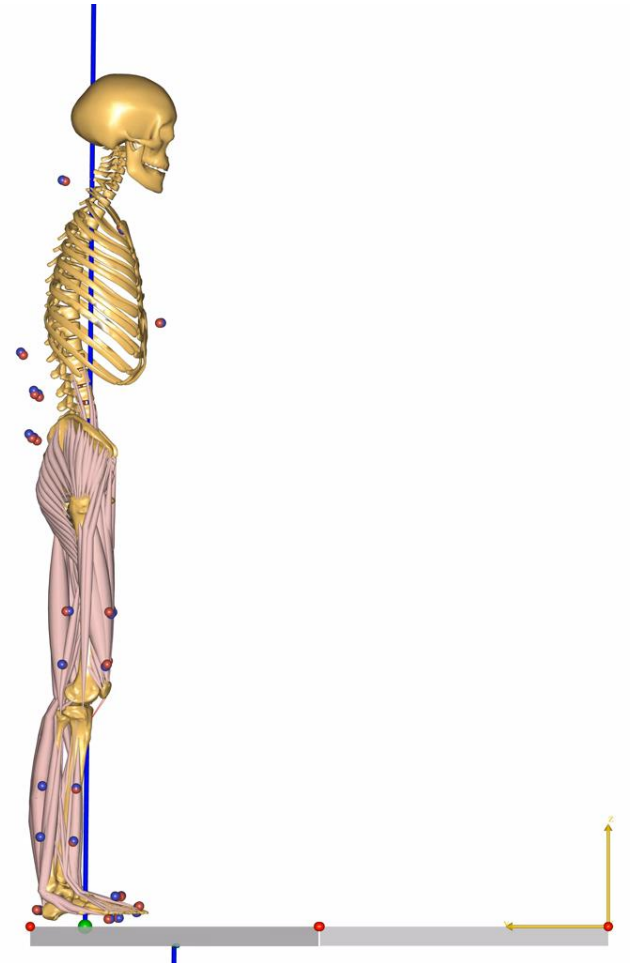
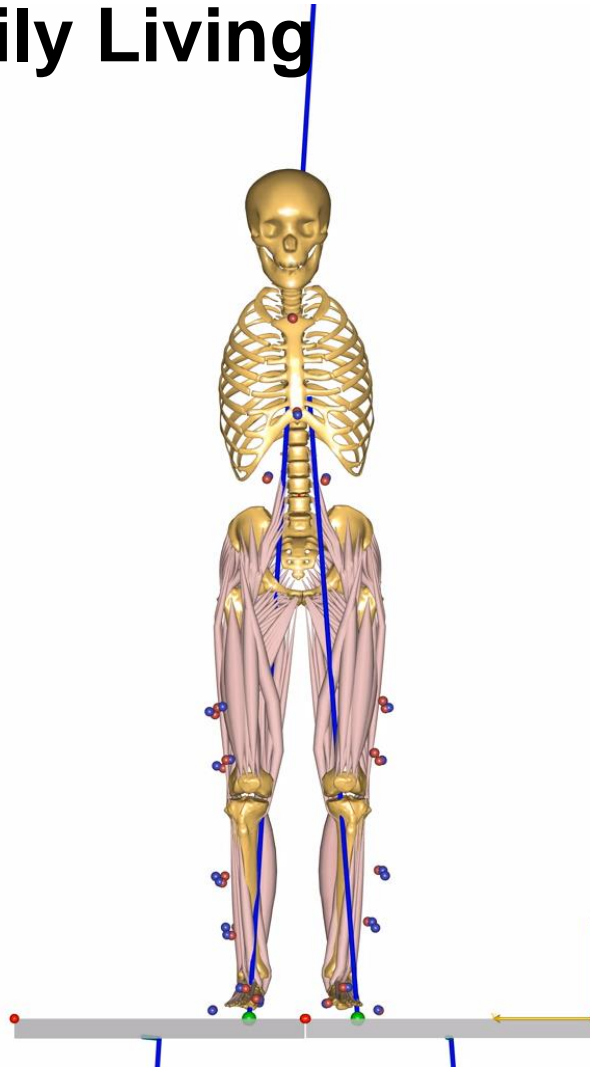
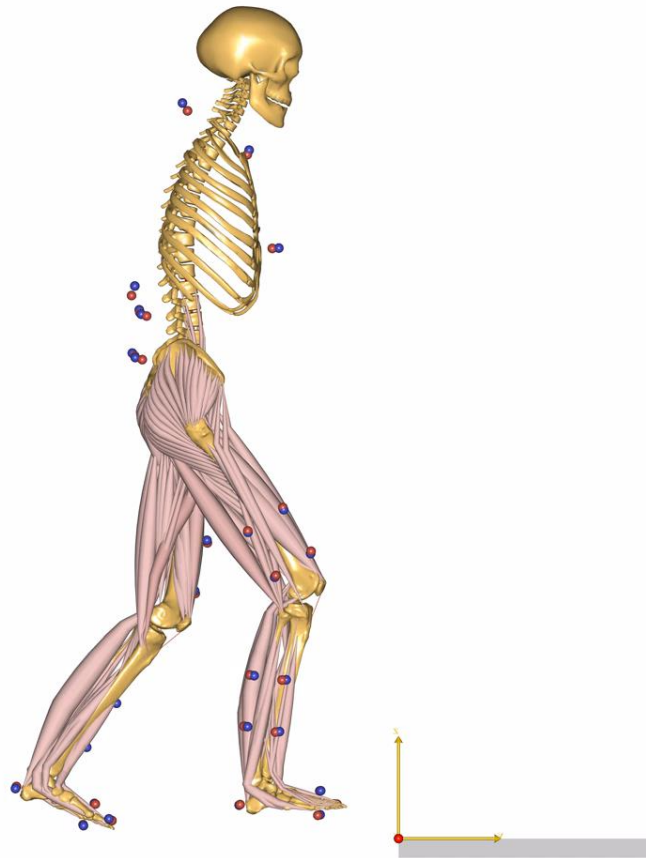
**Preliminary schedule:
Monday 9th July, 15:00 – 16:30**



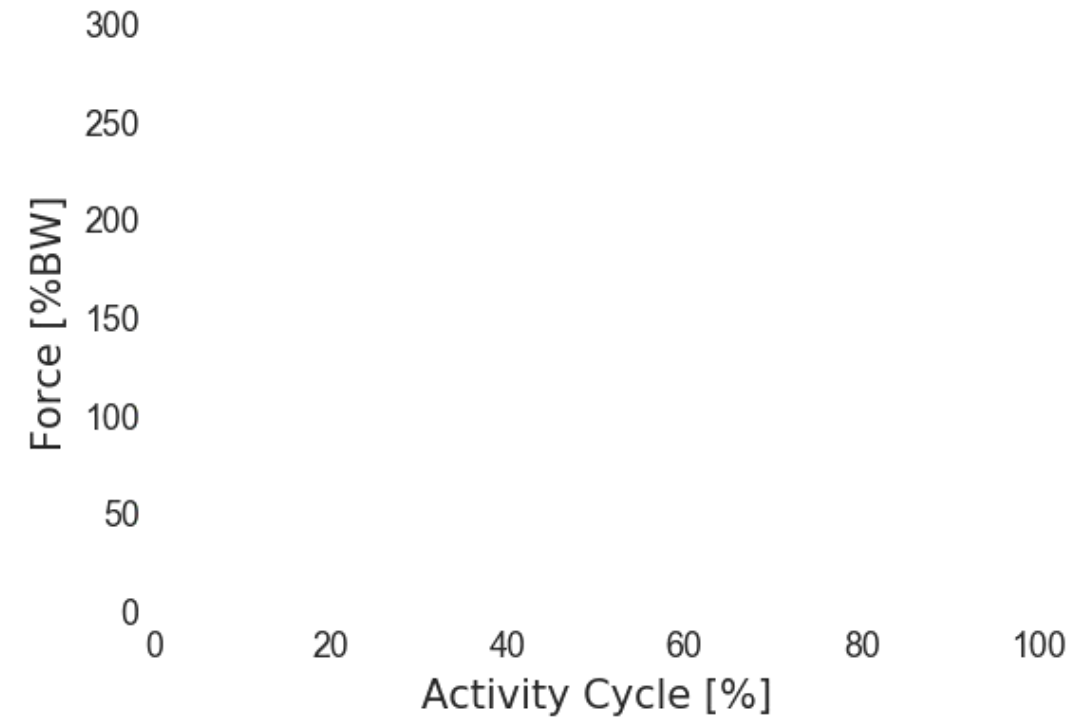
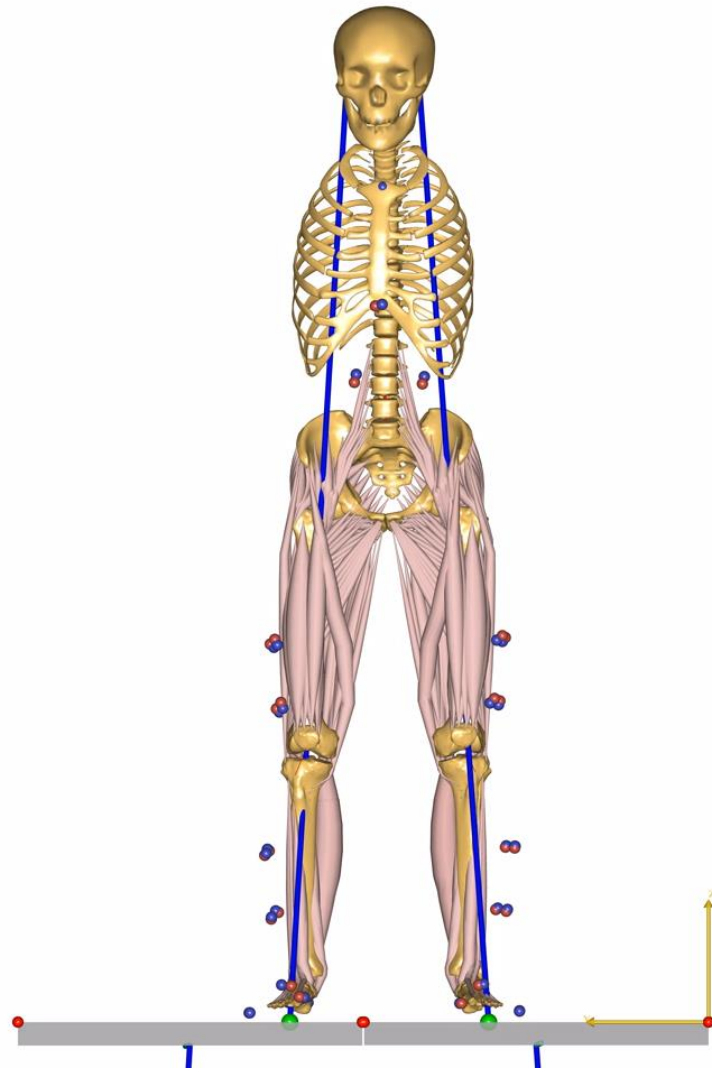
Routine Activities of Daily Living



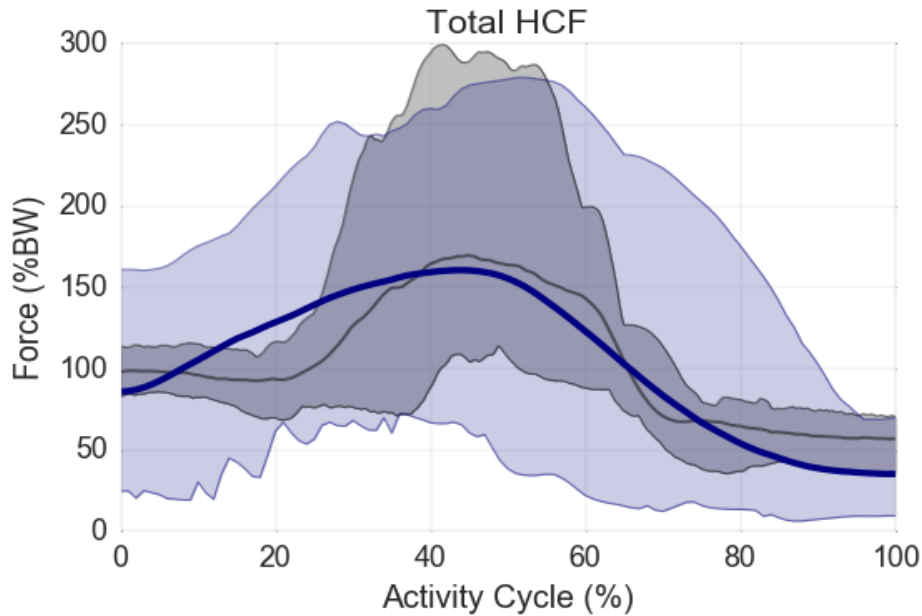
Adverse Activities of Daily Living



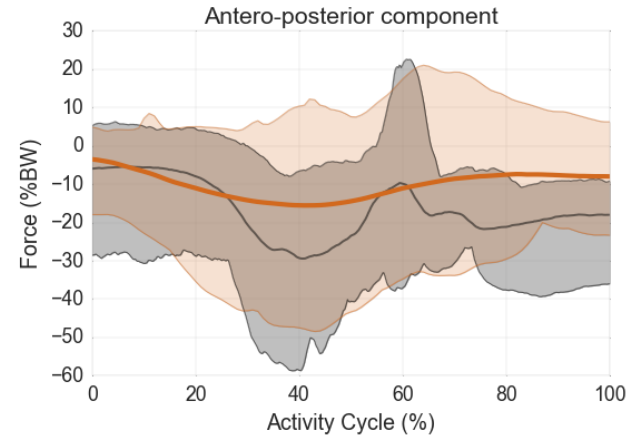
Activities of Daily Living – Sit Down



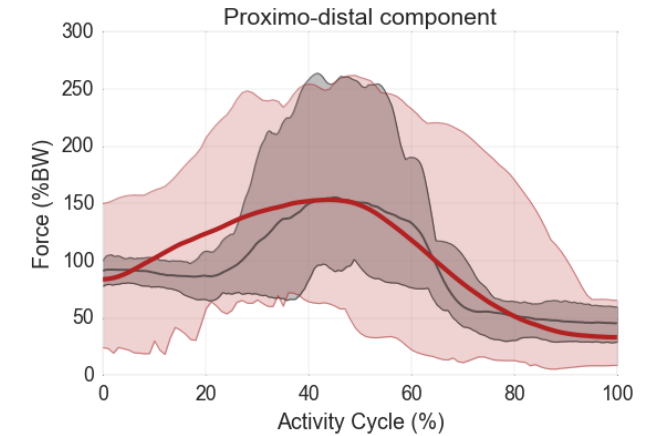
Qualitative comparison against Orthoload dataset – Sit Down



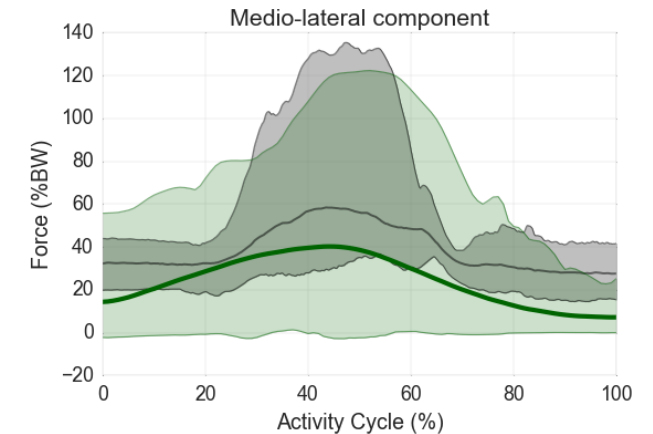
— Orthoload dataset - Total Force — LLJ Dataset - Total Force



— Orthoload dataset - AP component — LLJ Dataset - AP component



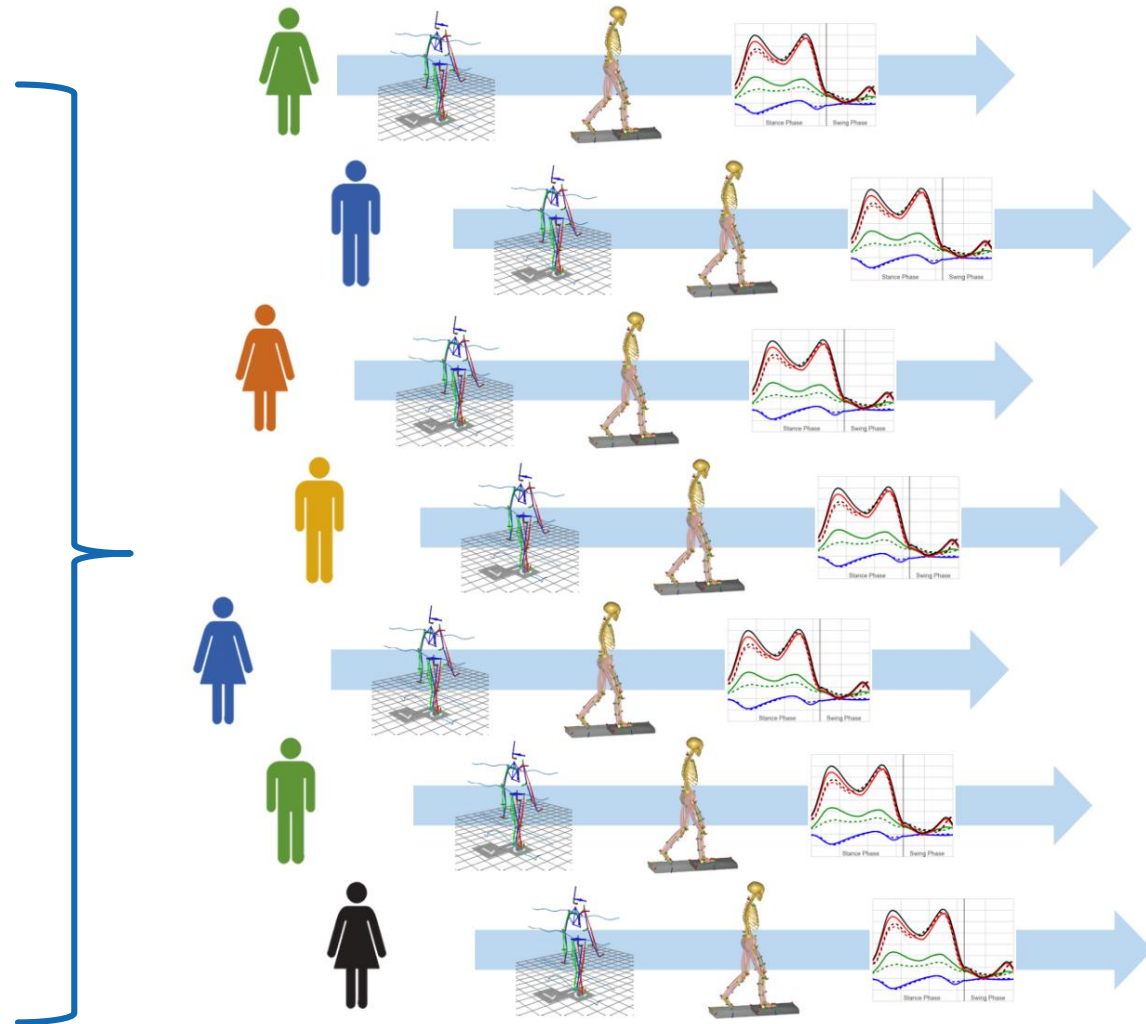
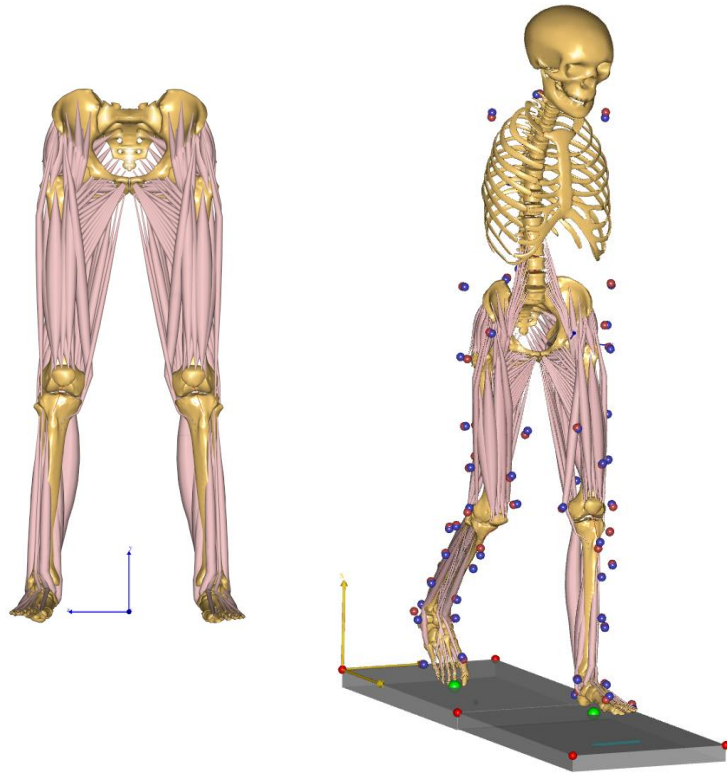
— Orthoload dataset - PD component — LLJ Dataset - PD component



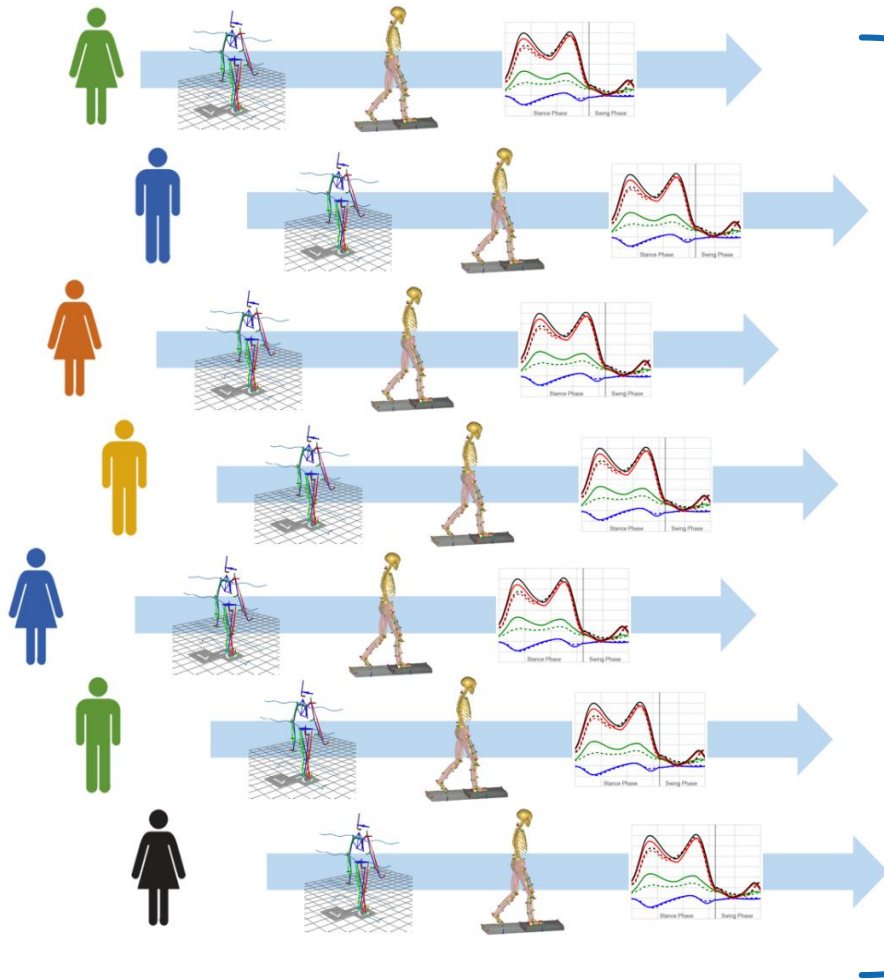
— Orthoload dataset - ML component — LLJ Dataset - ML component

- Predictions' mean within Orthoload dataset range

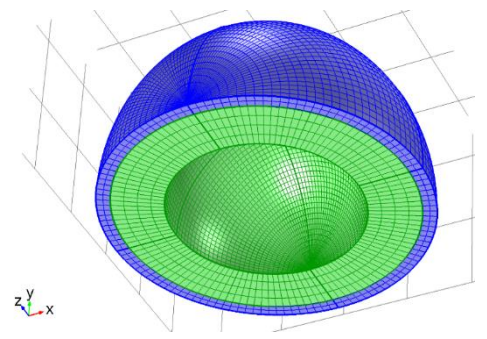
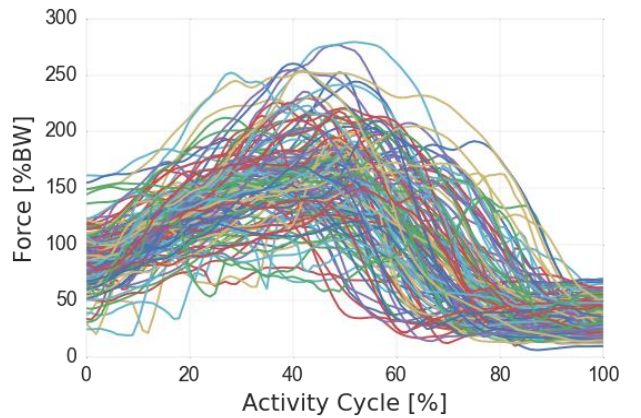
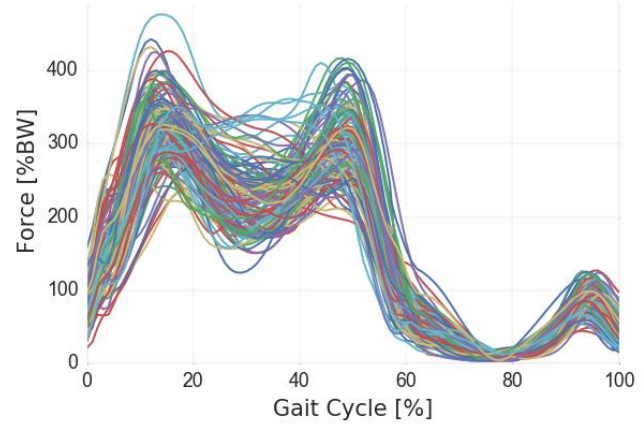
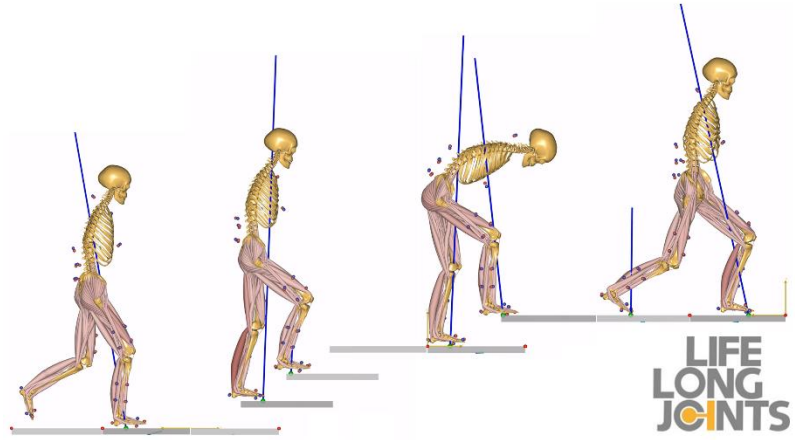
Conclusion



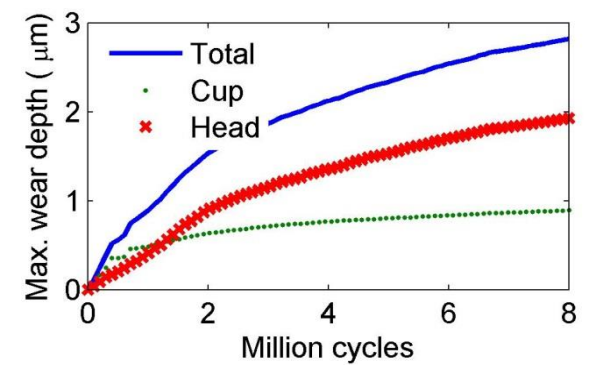
> 130 patients



> 130 patients




Wear Modelling



Thank you for your attention!

Acknowledgments:

Morten E. Lund
Anantharaman Gopalakrishnan
Kasper P. Rasmussen

The Leeds Teaching Hospitals 
NHS Trust

David E. Lunn
Anthony Redmond

 ANYBODY
TECHNOLOGY

Financial support:

7th Framework Programme
Life Long Joints project

 LIFE
LONG
JOINTS

Released: Leeds LifeLongJoints Model

<https://github.com/AnyBody/Leeds-LifeLongJoints-Model>

AnyBody / Leeds-LifeLongJoints-Model

Model for processing the Leeds LLJ MoCap dataset

18 commits 2 branches 2 releases 1 contributor

Commit	Message	Time
melund	update DOI to use the one for the newest verison	Latest commit cf5d216 an hour ago
	C3D-files	Add git ignore file 2 months ago
	Model	This should hopefully improve the robustness of the solvers 14 days ago
	Output/tmp	Update parameter optimization files an hour ago
	Subjects	Update trials with changes from Cribsheet 8 days ago
	LICENSE.txt	Initial commit 2 months ago
	README.md	update DOI to use the one for the newest verison an hour ago
	batch-processing.ipynb	Add simple batch processing notebook 2 months ago
	libdef.any	Update folder name for new processing files 2 months ago

Leeds LifeLongJoints Model

DOI [10.5281/zenodo.1254286](https://doi.org/10.5281/zenodo.1254286)

This is the model used in an FP7 European Commission project called Lifelongjoints (<https://lifelongjoints.eu/>). The model was used to investigate hip loads using a large dataset collect at Leeds Teaching Hospital NHS Trust.

Data from *Leeds LLJ dataset* goes into “C3D-files/”

Leeds-LifeLongJoints-Model-v1.1

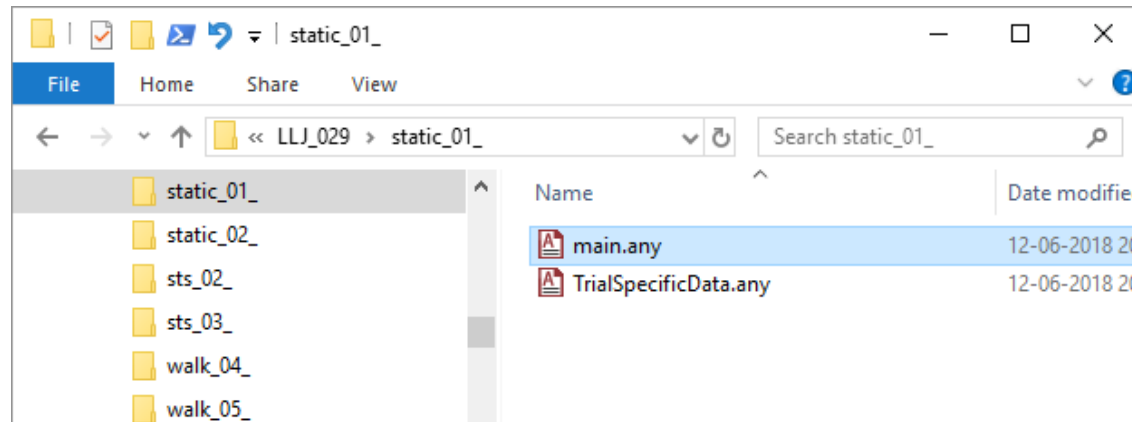
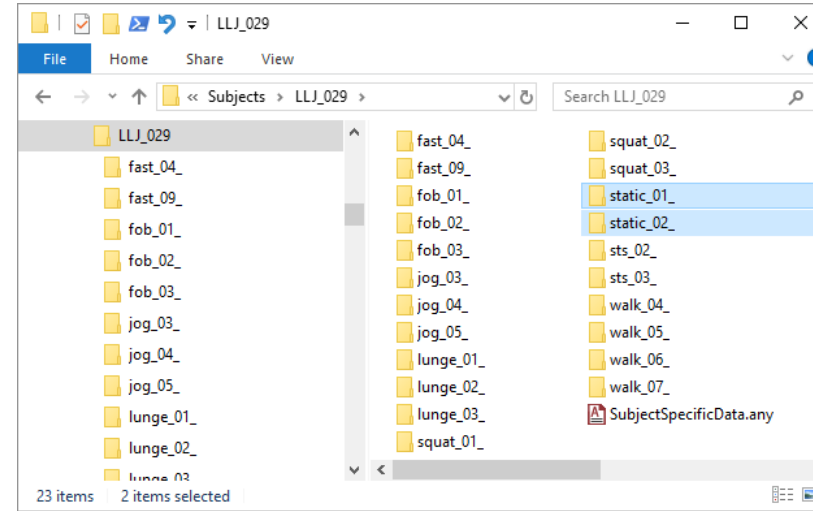
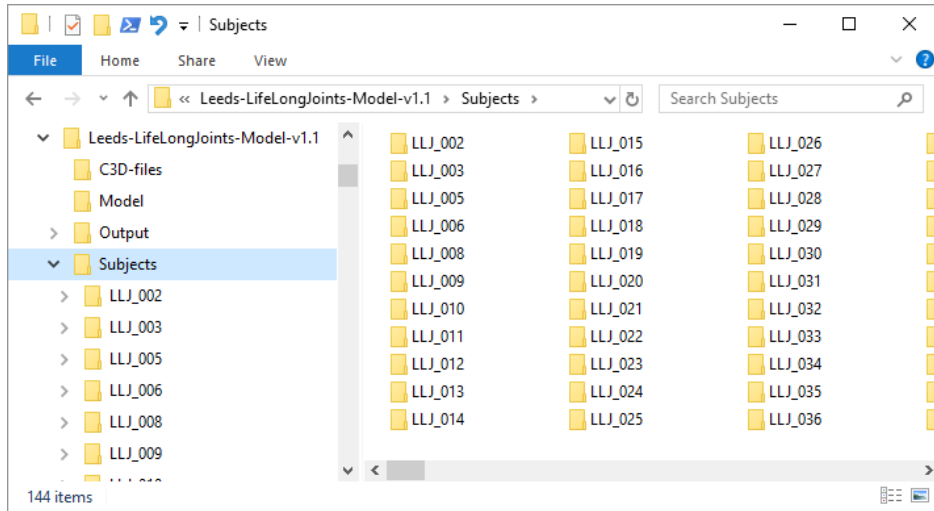
- C3D-files
- Model
- Output
- Subjects
- LLJ_002
- LLJ_003
- LLJ_005
- LLJ_006
- 111000

8 items | 1 item selected

Notice: Data must be downloaded separately...

<https://doi.org/10.5518/345>

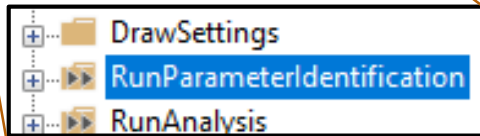
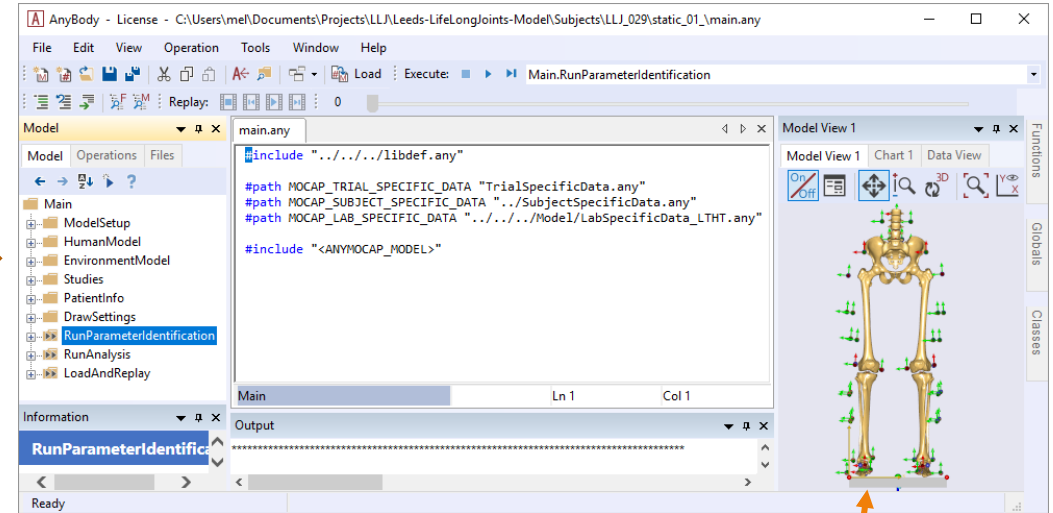
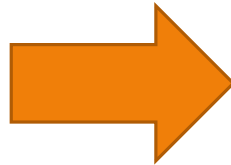
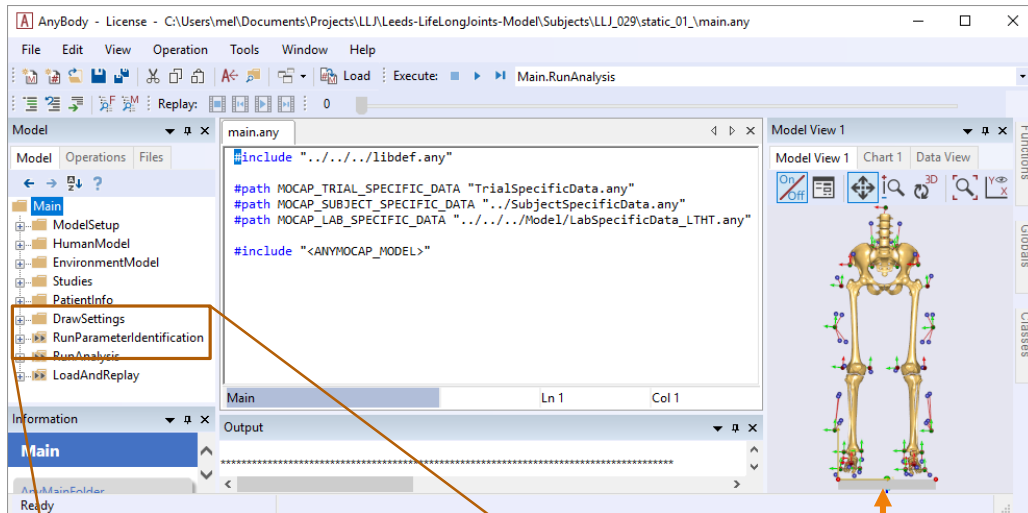
Released: Leeds LifeLongJoints Model



trial	Activity
static	Standing reference
fast	Fast gait
walk	Normal gait
lunge	Lunge
sts	Sit to stand/stand to sit
squat	Squat
fob	Foot on bench
jog	Jogging

Released: Leeds LifeLongJoints Model

Must run for all 237 trials.... Not a manual task.



Model is not scaled
Markers not located correctly

Segment length and marker
positions are optimized

The console application and macros

- The AnyBody Modeling System without the graphical user interface (GUI)

AnyScript Macros commands

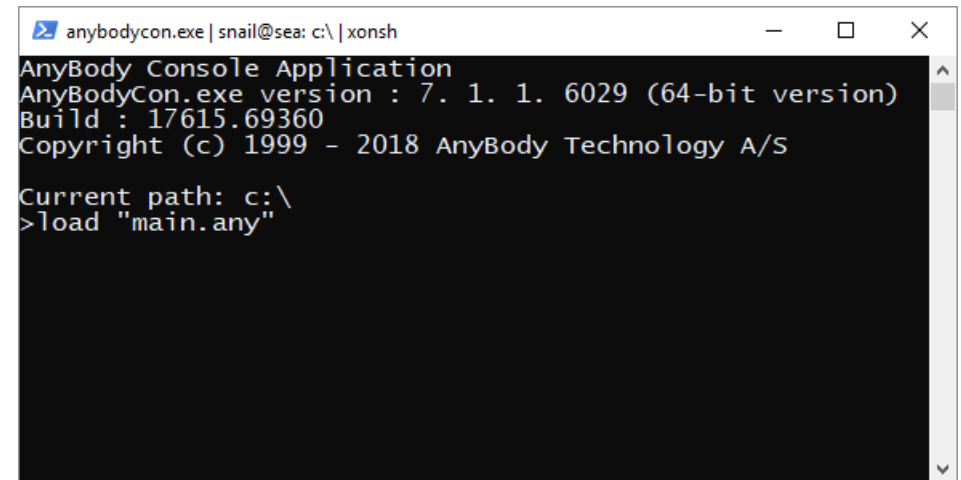
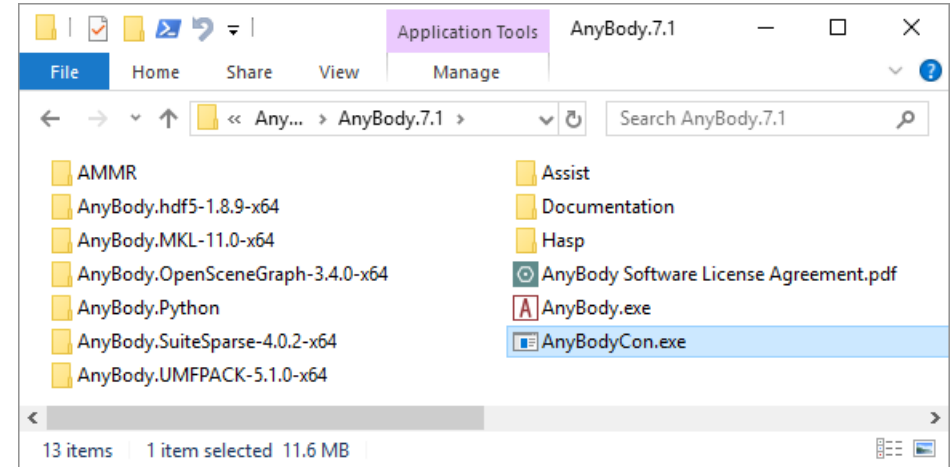
```
load <"file name"> [arg]
```

```
operation <opr_name>
```

```
run
```

```
classoperation <obj> <cmd> [arg]
```

```
exit
```



The console application and macros

- The AnyBody Modeling System without the graphical user interface (GUI)

AnyScript Macros commands

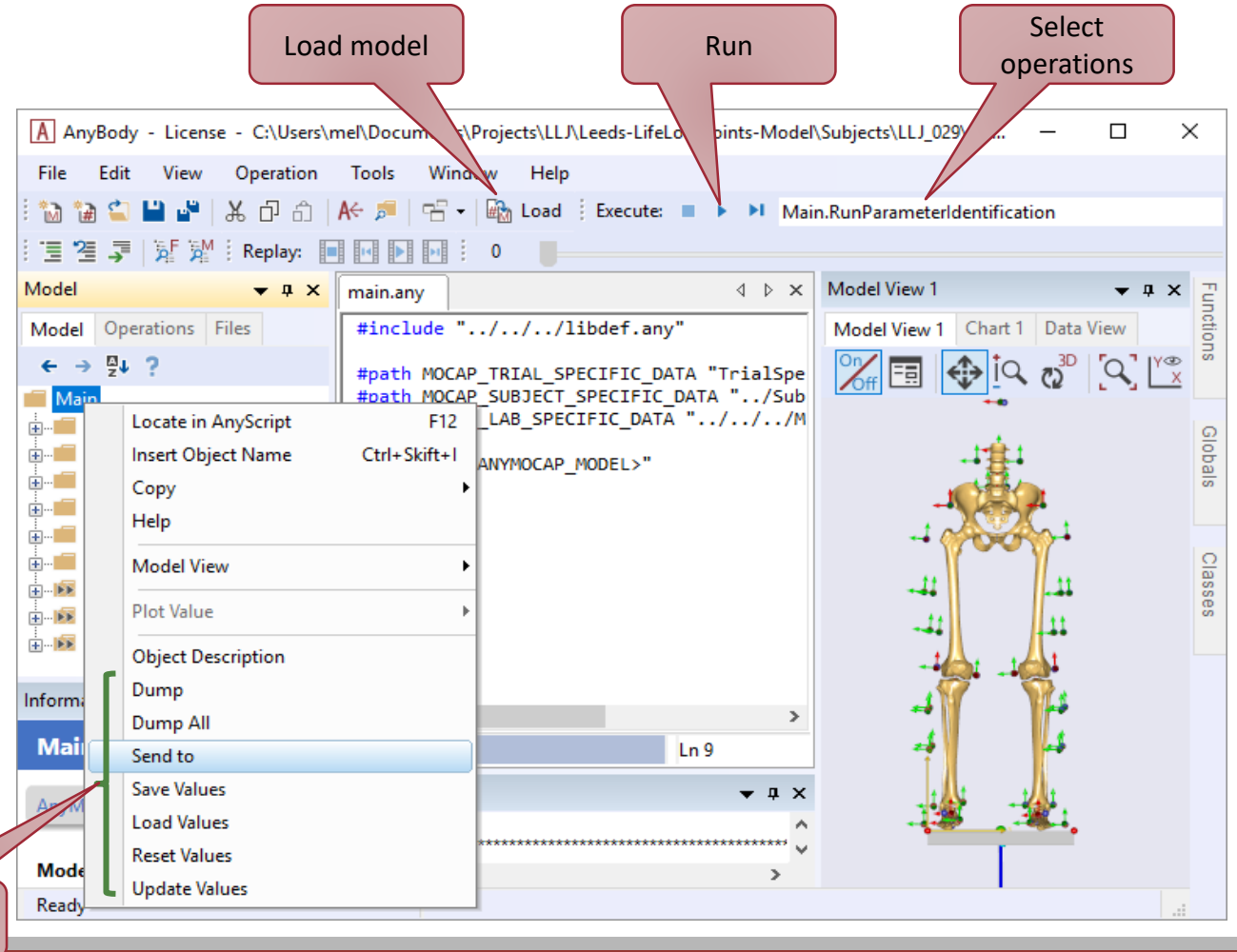
```
load <"file name"> [arg]

operation <opr_name>

run

classoperation <obj> <cmd> [arg]

exit
```



Batch processing with Python

- Running macro is easily automated with the *AnyPyTools* library.

```
In [1]: from anypytools import AnyPyProcess
        from anypytools.macro_commands import Load, OperationRun, Dump
```

```
In [2]: app1 = AnyPyProcess(num_processes=2)

        macro = [
            Load('main.any'),
            OperationRun('Main.RunParameterIdentification')
        ]
```

```
In [ ]: results = app1.start_macro(macro, search_subdirs='(static).*main.any')
```

14 of 237



More on batch processing

Complete example with the Leeds-LifeLongJoints-Model:

The screenshot shows a GitHub repository for 'AnyBody / Leeds-LifeLongJoints-Model'. The file 'batch-processing.ipynb' is open, displaying a Jupyter notebook with the following content:

Leeds Hip Loads model
This notebook shows how to run a very simple batch processing on the LeedsHipLoads model. Please ensure you have installed the [AnyPyTools library](#). See the [install instructions](#).

```
In [ ]: from anypytools import AnyPyProcess, macro_commands as mc
```

Run standing reference trials

```
In [ ]: app1 = AnyPyProcess(num_processes=2, return_task_info=True)

macro = [
    mc.Load('main.any'),
    mc.OperationRun('Main.RunParameterIdentification')
]
```

```
In [ ]: results = app1.start_macro(macro, search_subdirs='(static).*main.any')
```

Run all dynamics trials

```
In [ ]: app2 = AnyPyProcess(num_processes=2, return_task_info=True)

macro = [
    mc.Load('main.any'),
    mc.OperationRun('Main.RunAnalysis.LoadParameters'),
    mc.OperationRun('Main.RunAnalysis.MarkerTracking'),
    mc.OperationRun('Main.RunAnalysis.InverseDynamics'),
    mc.Dump('Main.Studies.InverseDynamicStudy.Output.BodyModel.SelectedOutput.Right.Leg.JointReactionForce.Hip_ProximodistalForce')
]
```

<https://github.com/AnyBody/Leeds-LifeLongJoints-Model>

How to install and use AnyPyTools:

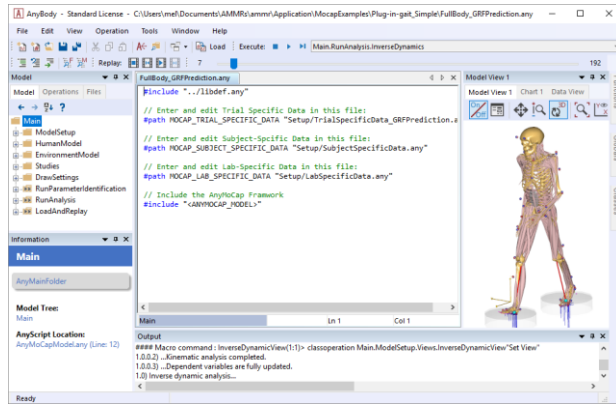
The screenshot shows the 'AnyPyTools' documentation website. The page title is 'AnyPyTools' documentation!'. The main content area features the AnyPyTools logo and a 3D anatomical model of a human torso. The text describes the tool's purpose: 'AnyPyTools is a toolkit for working with the AnyBody Modeling System (AMS) from Python. Its main purpose is to launch AnyBody simulations and collect results. It has a scheduler to launch multiple instances of AMS utilising computers with multiple cores. AnyPyTools makes it easy to do parameter and sensitivity and many other things which is not possible directly within the AnyBody Modeling System.'

The page includes a 'Page contents' sidebar with links to 'Installation', 'Guides', 'Documentation', 'Development', and 'Usefull links'. There is also a 'Quick search' field and a 'Go' button.

<https://anybody-research-group.github.io/anypytools-doc>

New releases are online:

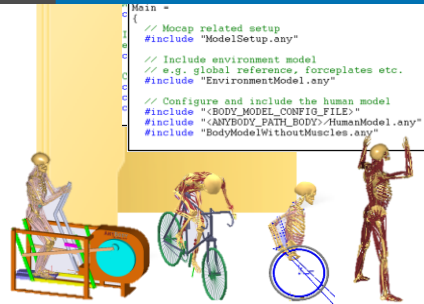
ANYBODY Modeling System 7.1.2



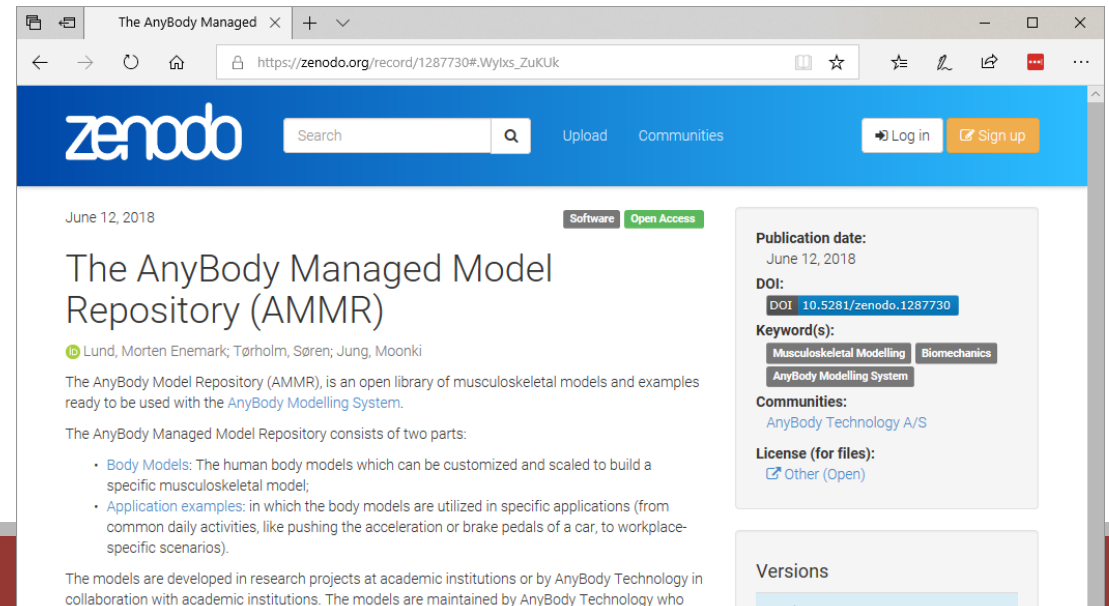
Minor release:
Smaller changes and bug fixes.

Model Repository (AMMR 2.1.1)

DOI 10.5281/zenodo.1251274

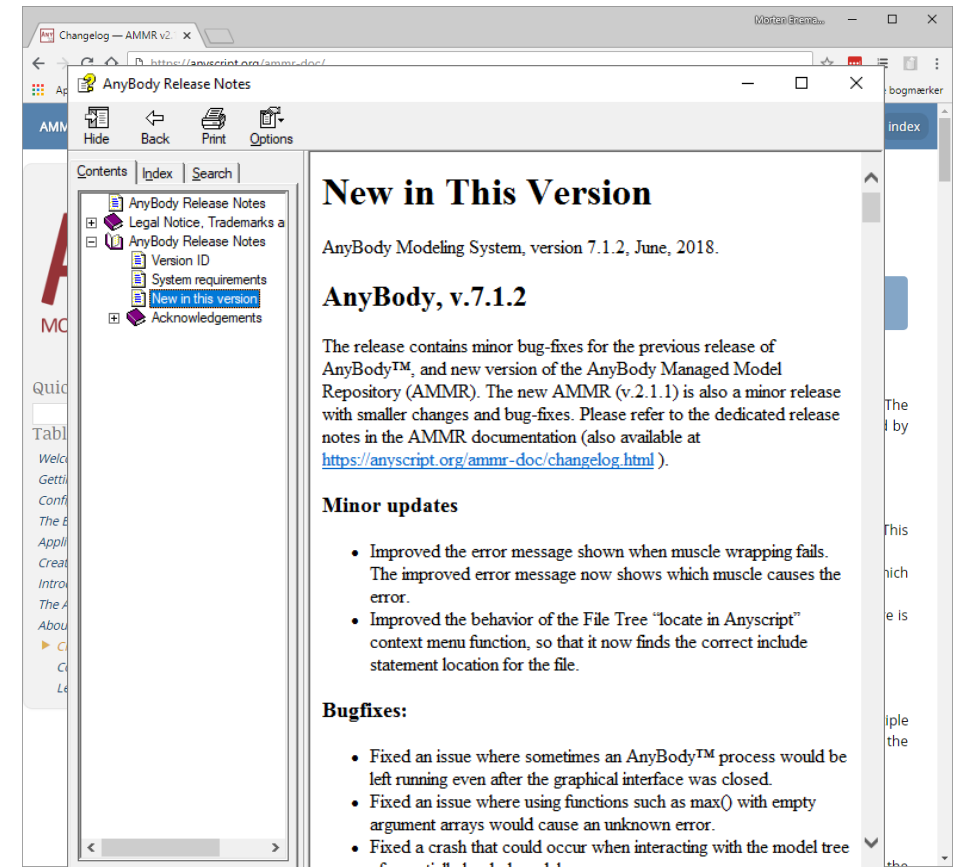
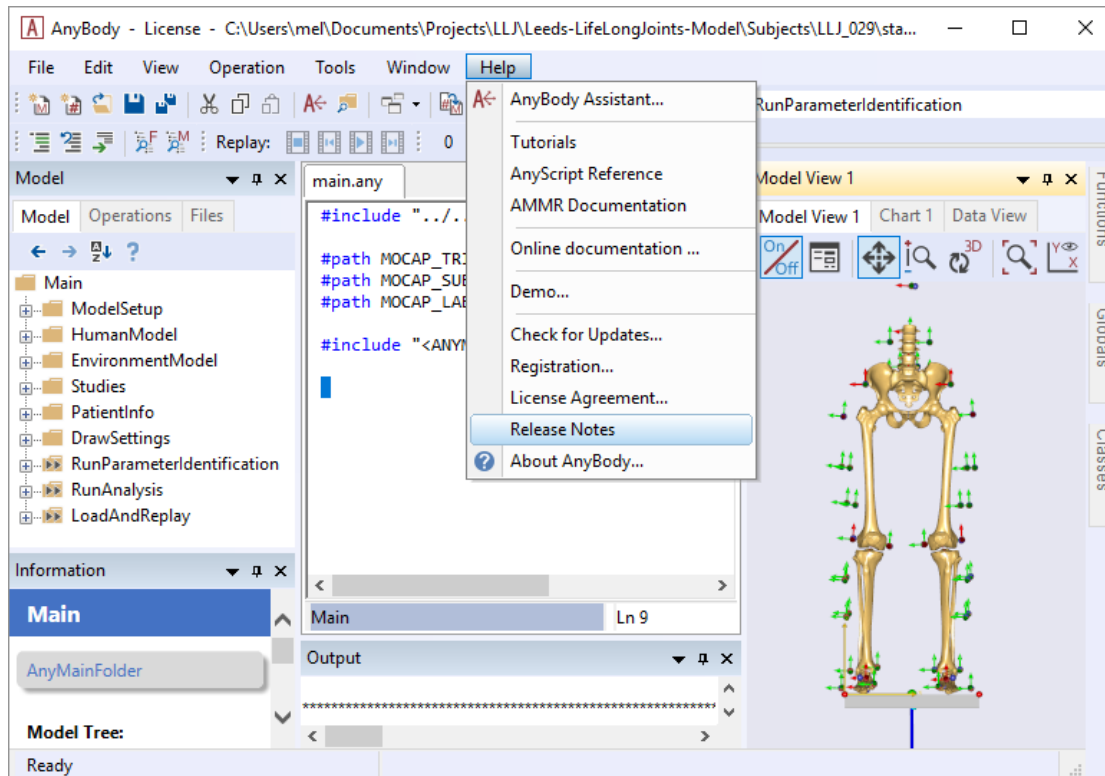


Open Science platform hosted at CERN



Check release notes:

<https://anyscript.org/ammr-doc/changelog.html>



www.youtube.com/anybodytech

- Previous webcasts

www.anybodytech.com

- Events, dates, publication list, ...

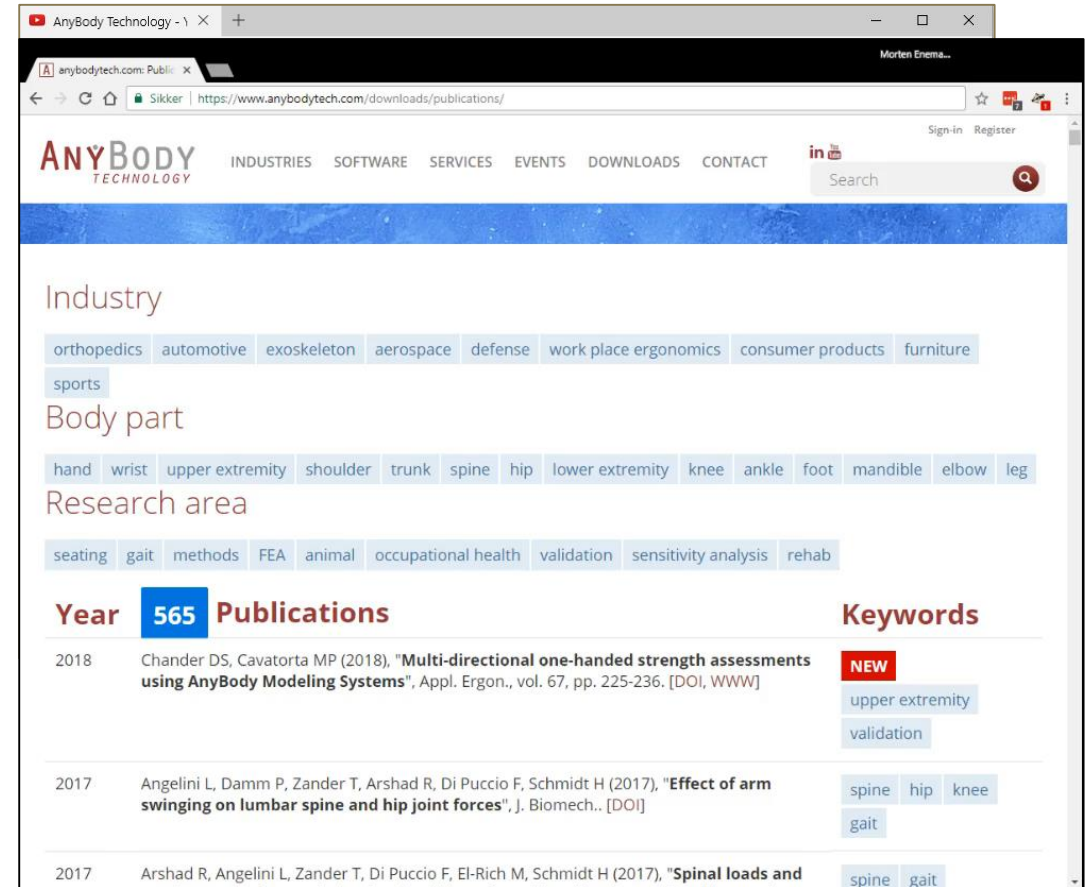
Events:

8-12 Jul: WCB in Dublin, Ireland.

See you on booth #42 at and for our session with Xsens

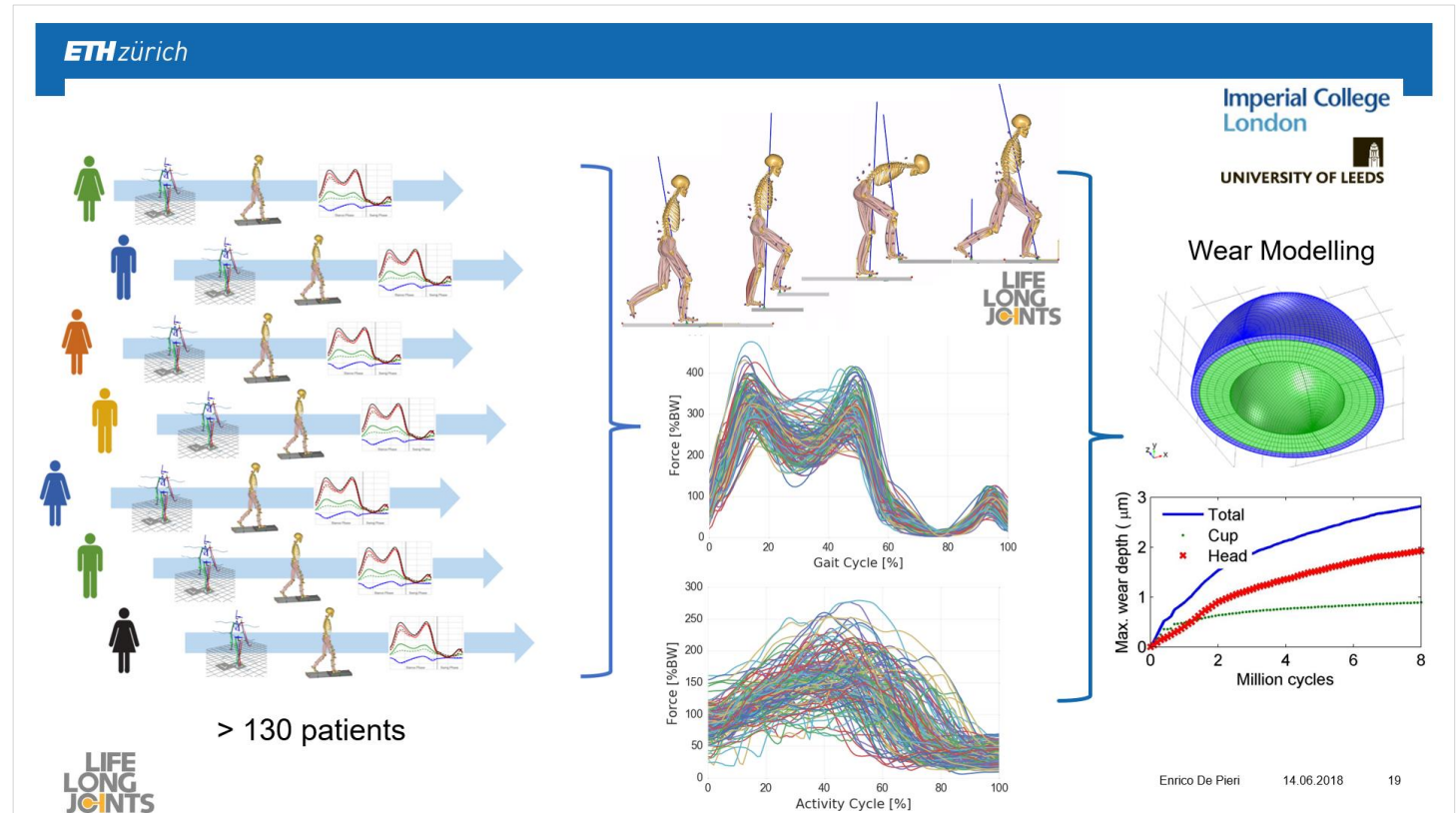
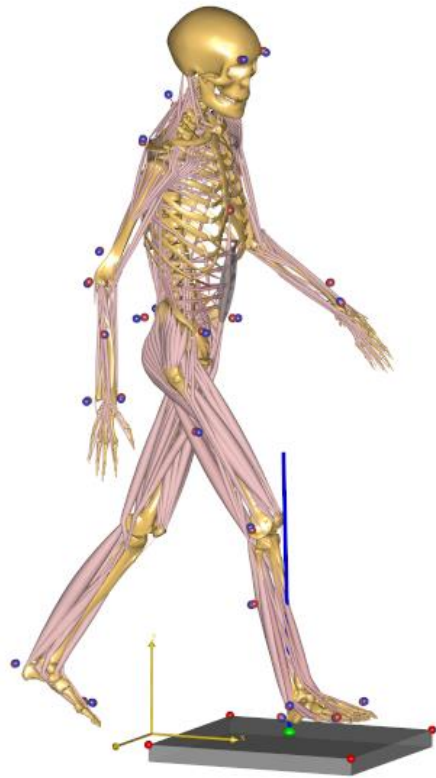
We are hiring:

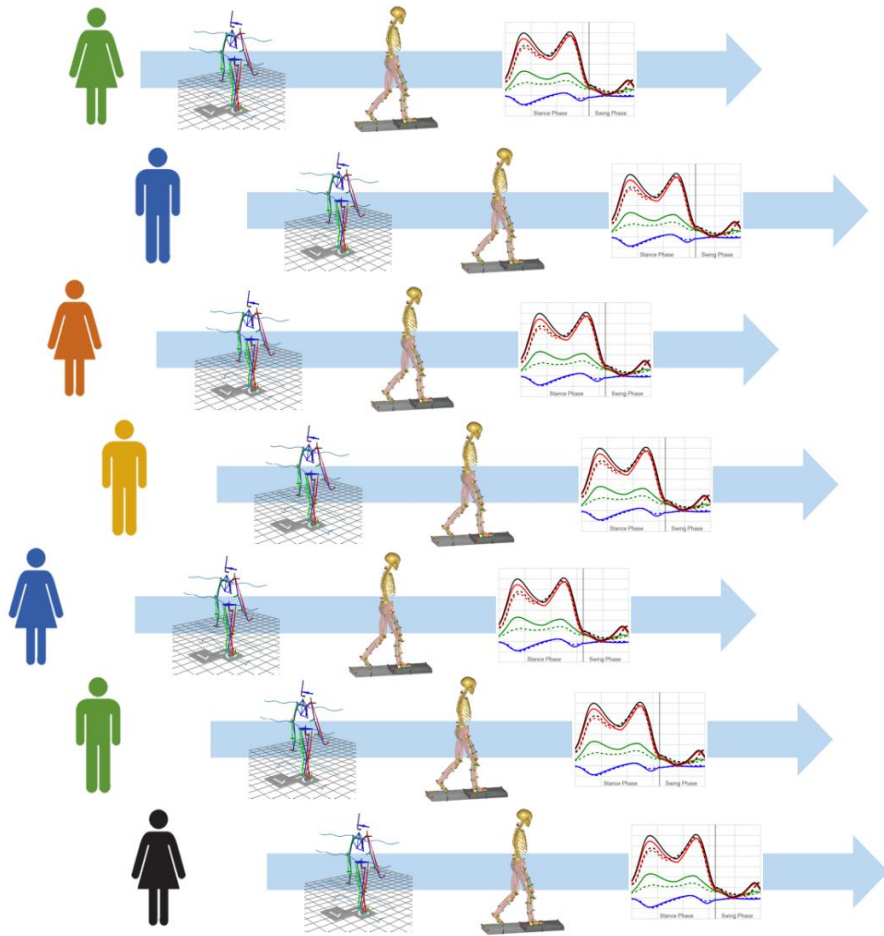
- Biomechanics Specialist and Simulation Core Developer



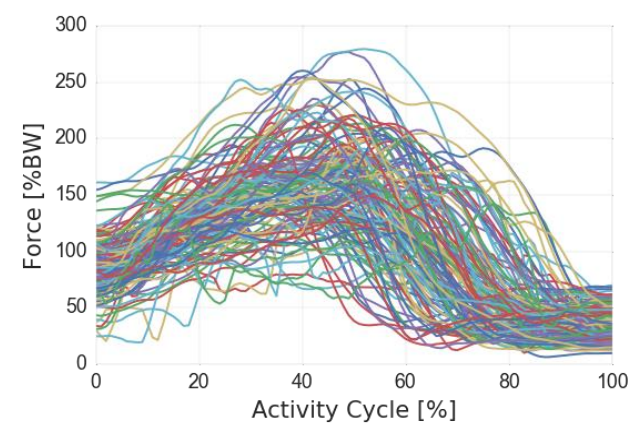
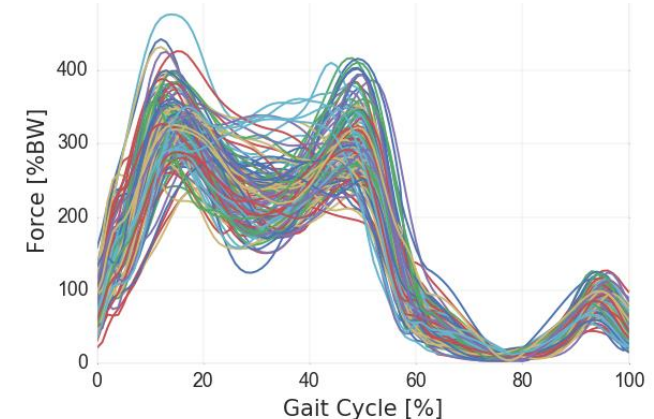
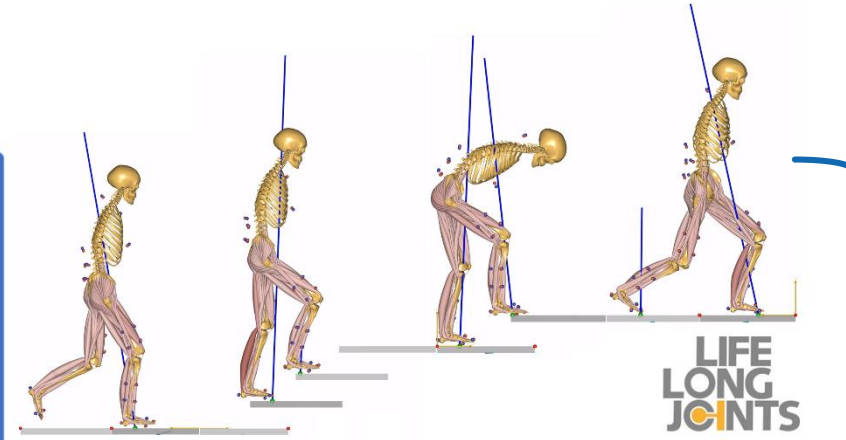
 **Meet us?** Send email to sales@anybodytech.com

Time for questions:





> 130 patients



Wear Modelling

