

The webcast will start in a few minutes....

How does human gait respond to muscle impairment in TKA patients?

SIMULATION OF MUSCLE WEAKNESS IN ANYBODY MODELING SYSTEM



Outline

- Introduction by the Host
- Presentation
 - Motivations and goals
 - Model
 - Data analysis
- Final words from the host
- Questions and answers



Marzieh M. Ardestani , PhD Postdoc Fellow, Rush University (Presenter)



Mohammad S. Shourijeh, PhD R&D Engineer, AnyBody Tech. (Host)



Control Panel

The Control Panel appears on the right side of your screen.

Submit questions and comments via the Questions panel.

Questions will be addressed at the end of the presentation. If your question is not addressed we will do so by email.





AnyBody Modeling System

- Simulations of Musculoskeletal systems
 - Multibody kinematics and dynamics analysis

• AnyBody Managed Model Repository

- Special simulation features
 - Reaction force prediction
 - Imaging \rightarrow Patient-specific anatomy
 - Man-machine interaction simulation



Rasmussen et. al. (2011), ORS Annual Meeting







Load Cases for Finite Element Analysis



Surgical Planning and Outcome Evaluation



AnyBody Modeling System





How does human gait respond to muscle impairment in TKA patients?

Dr. Marzieh M. Ardestani Postdoctoral Fellow

Rush University

How human gait responds to muscle impairment in TKA patients?

Simulation of muscle weakness in AnyBody modeling System

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Total knee arthroplasty

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<u>Goals:</u>

Pain relief

□ Restoration of normal alignment

Restoration of function
Mobility
Stability
Gait



Normal gait following TKA

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Muscle weakness

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□ 50-60% strength decline in hamstring and quadriceps (Judd et al., 2012, Stevens-Lapsley et al., 2010)

Muscle weakness

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□ Muscle weakness may persist up to three years after surgery (Schache et al., 2014).

Muscle weakness affects gait ?

□ How much weakness ?

- □ A little ?
- A subtle weakness in an individual muscle can be compensated by additional contribution of other muscles



□ Too much ?

- Severe muscle impairments(postoperative muscle deficits in

TKA patients) will lead to "kinematic" compensations so as to offload the impaired muscles

- Quadriceps avoidance (Andriacchi, 1993)
- knee stiffening strategies (Benedetti et al., 2003)

Research questions

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- How much muscle weakness can be tolerated by TKA patients before demanding any kinematic adaptation?
- **1** How muscle impairment may perturb muscle and joint forces?



Methodology

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AnyBody modelling system Musculoskeletal model



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AnyBody modelling system



AnyBody modelling system Muscle model



AnyBody modelling system Muscle model

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$$Strength = F_0 \left(2\frac{L_m}{\overline{L_f}} - 1 \right) \left(1 - \frac{L_m}{V_0} \right)$$

- ✓ Lf : Neutral fiber length
- ✓ Lm' : Contraction velocity
- ✓ Lm : Current length of the contractile element
- ✓ V0 : Contraction velocity at maximum voluntary contraction
- ✓ F0 : Muscle isometric strength





AnyBody modelling system Muscle re<u>cruitment</u>

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Optimization routine :

(Damsgaard et al., 2006; Rasmussen et al., 2001)

$$Minimize_f G(f^{(M)}) \quad , \quad G(f^{(M)}) = Max(\frac{f_i^{(M)}}{N_i})$$

Subject to : $C \times f = d$ and $0 \le f_i^{(M)} \le N_i$ $i = \{1, ..., n^{(M)}\}$

- ✓ G :objective function
- ✓ f(M) : muscle forces
- \checkmark f(R) : joint reaction forces
- ✓ Ni : Strength of the muscle
- ✓ C : Coefficient-matrix for the unknown forces
- ✓ D : All known applied loads and inertia forces

Methodology- Multi-body dynamic simulation



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□Spatial parameter mapping (SPM)

(Pataky et al, 2011)

□Principal component analysis (PCA)

(Fitzpatrick et al., 2011)

Results- Minimum requirements

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Hip extensor Hip abductor Hip adductor Knee extensor Knee flexor Ankle plantar flexor Ankle dorsi-flexor

65% OF BASELINE 60% OF BASELINE

46% OF BASELINE

50% OF BASELINE

42% OF BASELINE

40% OF BASELINE 25% OF BASELINE

Results- Compensatory mechanisms



Results- Compensatory mechanisms

RUSH UNIVERSITY Vastus 0.5 Weakened hip flexor... Force (BW) **Quadratus femoris** -0.5^L 0.04 20 80 60 40 Time (%) 0.02 20 SPM { t } -0.02^L 0 20 40 60 80 100 t* = 3.612 , p=0.000 Time (%) -20└ 0 10 80 20 40 60 t* = 3.544 , p=0.001 Time (%) SPM { t } 5 -5⊾ 0 20 40 60 80 100 Time (%)

Results- Joint force perturbations

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Results- Sensitivity analysis

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Sensitivity of every joint force component due to the weakness of individual muscles





Limitations

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A full lower limb musculoskeletal model of TKR in AnyBody combing (a) dynamics musculoskeletal models and (b) knee implants with articular contacts and ligaments.



Probabilistic multi-body dynamic analysis to evaluate the minimum strength requirements of muscles and muscular compensatory mechanisms in TKA patients.

Simulation of muscle weakness in AnyBody modeling System

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Webcasts



- New round of webcasts will start after summer 2016
- Check our YouTube channel for previous webcasts
 - Search channels for 'AnyBody Technology'

www.anybodytech.com

• Useful links, events, publication list, ...

www.anyscript.org

• Wiki, Forum





Upcoming Events

- ESB 2016, 22nd Congress of the European Society of Biomechanics, Lyon, France, 10-13 Jul.
 - Free AnyBody Hands-on training workshop Crowne Plaza Lyon-Cité Internationale., 10th Jul 2016, 12:00 – 16:00
 - Come visit us at our booth
- ASB 2016, Annual meeting of the American Society of Biomechanics, Raleigh, USA, 2-5 Aug.
- WeRob 2016, The International Symposium on Wearable Robotics, La Granja, Segovia, Spain, 18-21 October



Time for questions

