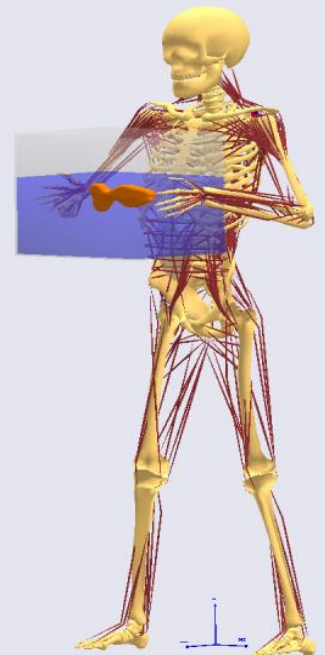
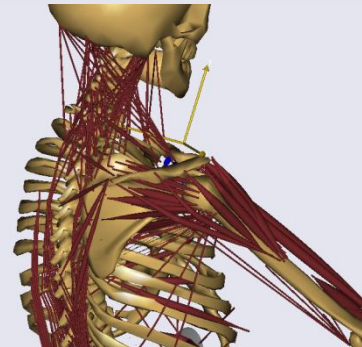
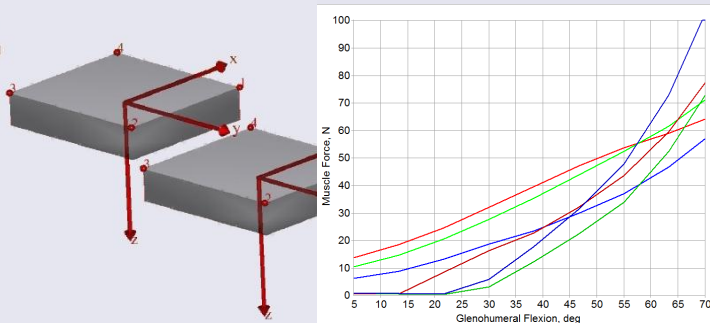
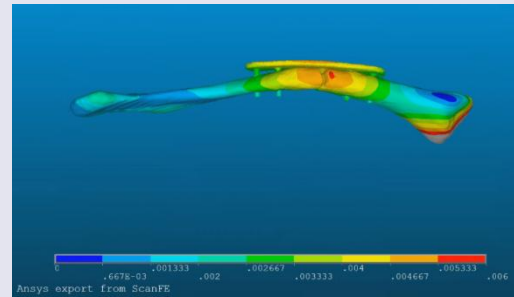
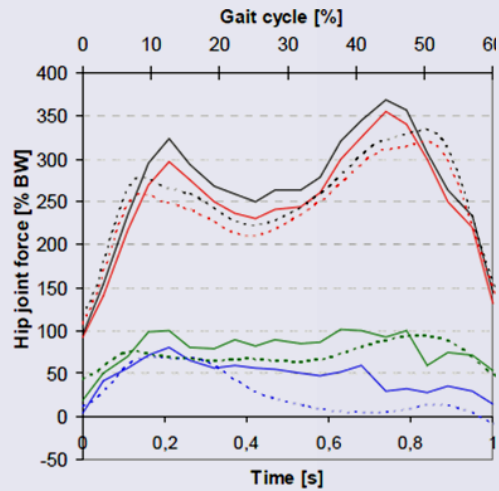
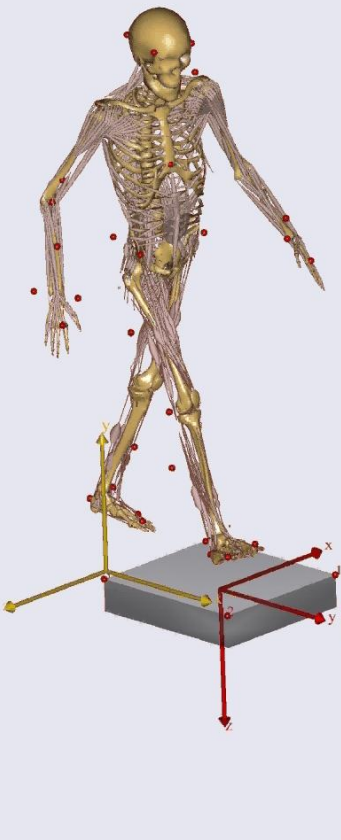


# Features of the new AnyBody Modeling System, version 5.2

Amir Al-Munajjed  
[aa@anybodytech.com](mailto:aa@anybodytech.com)

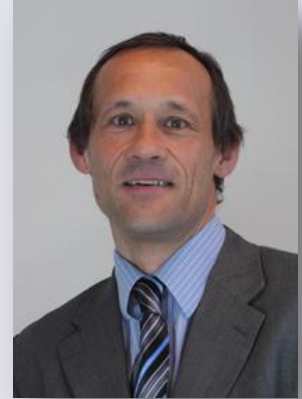
The web cast will start in a few minutes....



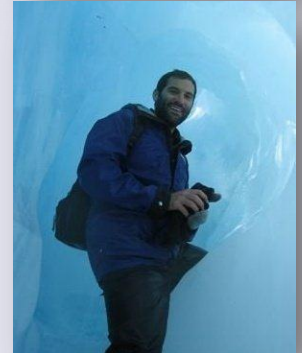
# Agenda & Presenters

- Who is AnyBody?
- AnyBody Modeling System
- AnyBody Model Repository
- AnyBody Applications
  - Ergonomics/Product Design
  - Physiological Loads for FEA
  - Surgical Planning
- Q & A

Arne Kiis  
(Host/Panelist)



Amir Al-Munajjed  
(Presenter)



Søren Tørholm  
(Panelist)



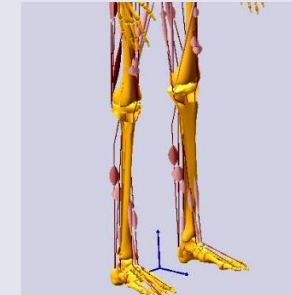
# AnyBody Technology

- Software licenses
- Consulting
- Training
- Support
- US Office
- AnyGait

2002



2006



2010

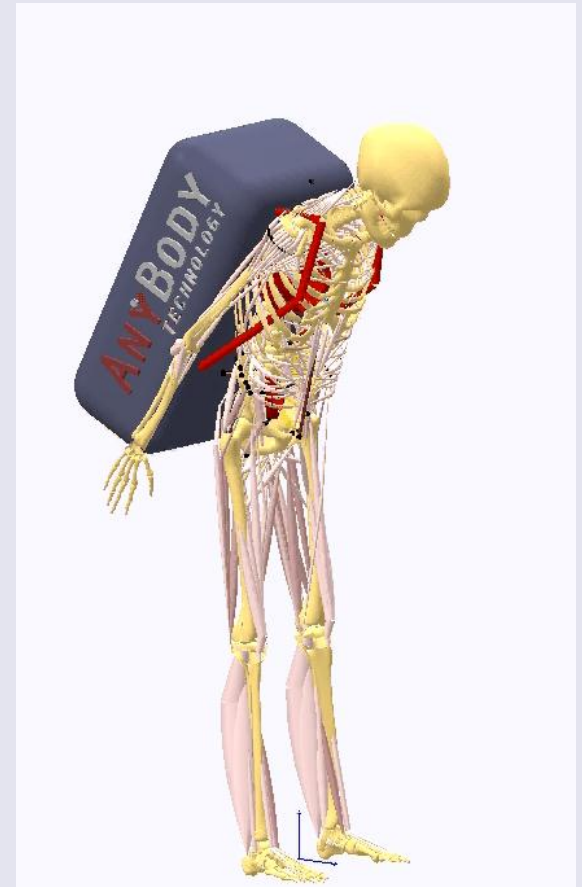


2011

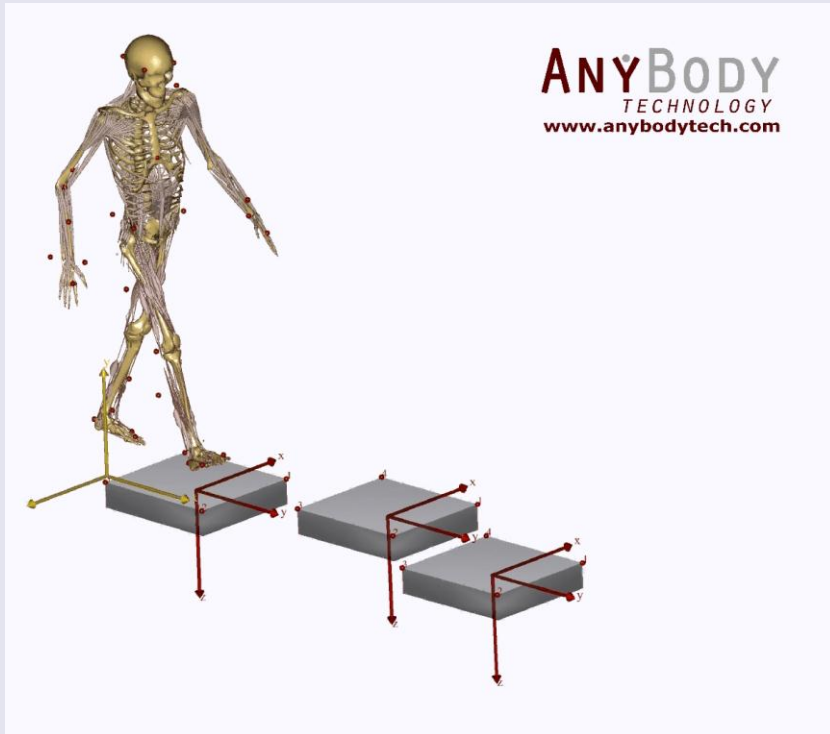
2012

# AnyBody Modeling System

- Developed in-house for musculoskeletal analysis
- Self-contained system
- Interfacing to
  - motion capture
  - image-based bone and muscle data
  - finite-element software
  - office systems
- Open body model
- Broad and deep model validation
- API for imbedded use

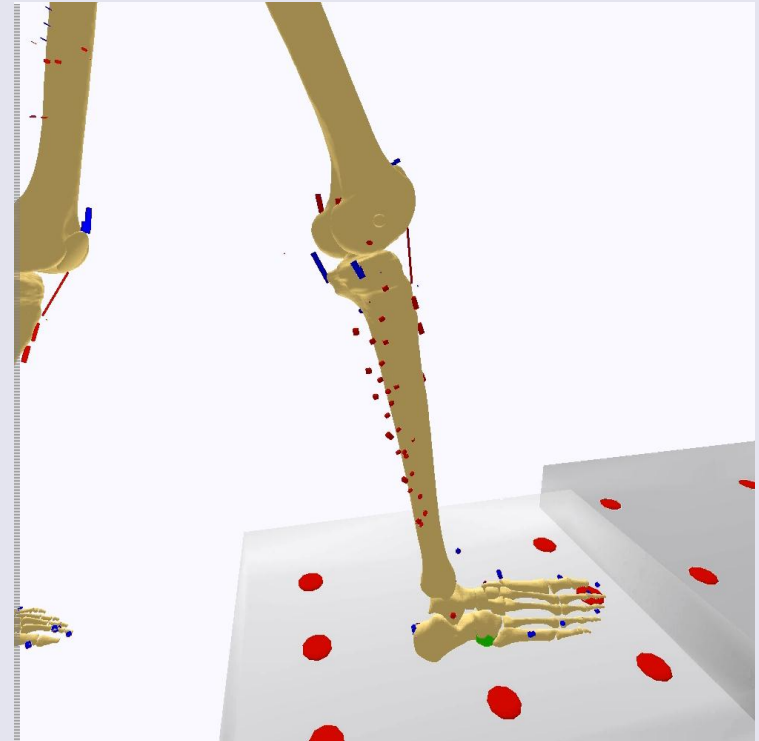


# AnyBody Modeling System



Motion & ext Forces as Input:

- Motion Capture (Vicon, Qualisys, ...)
- Joint Angle Input

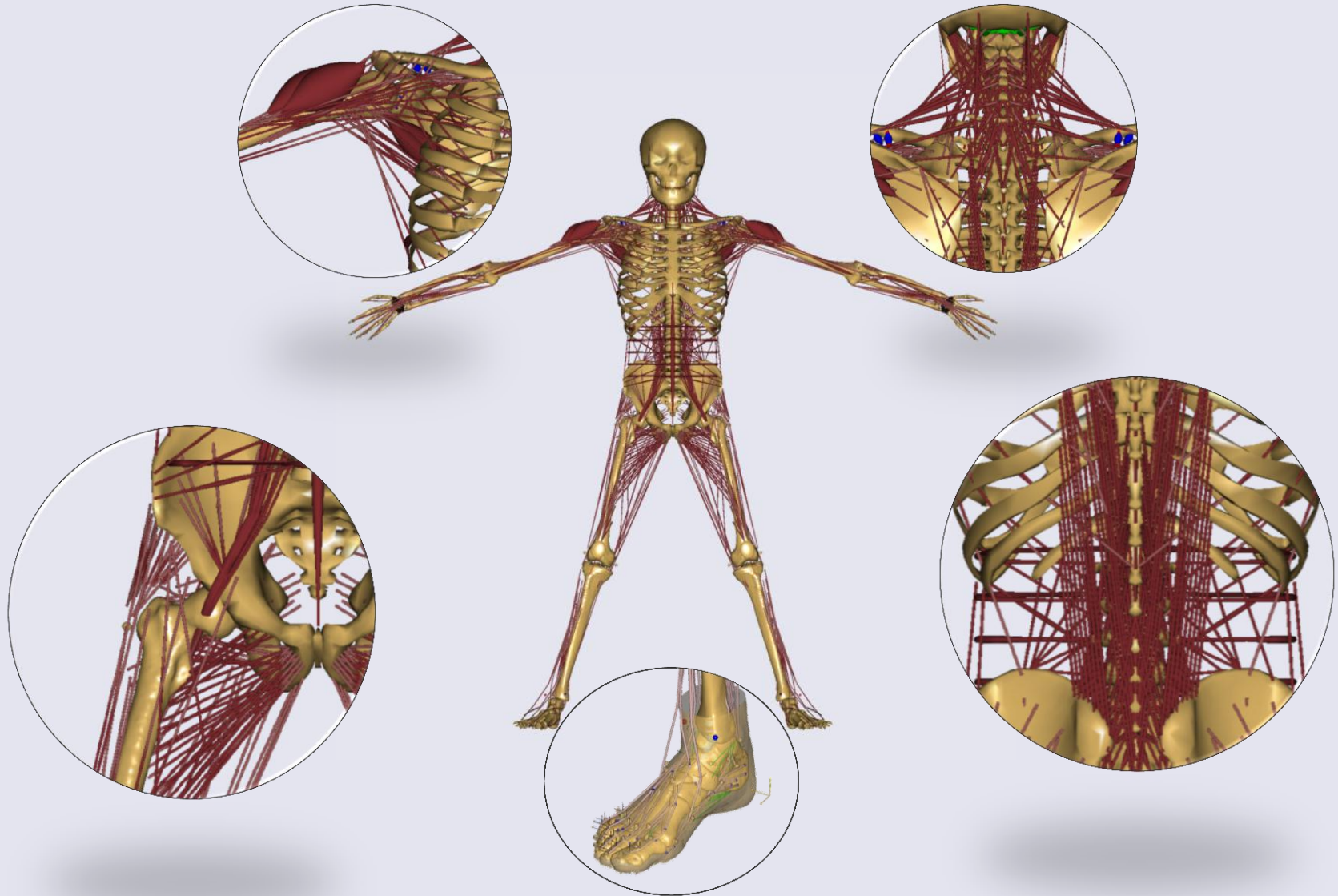


Forces as Output:

- Muscle Forces (activations)
- Joint Reaction Forces



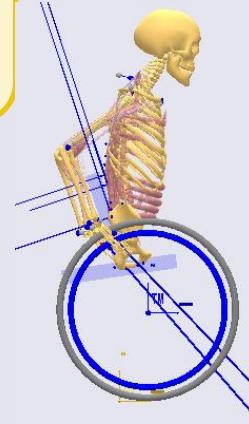
# Model Repository





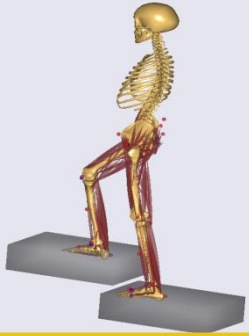


Product Design  
Optimization

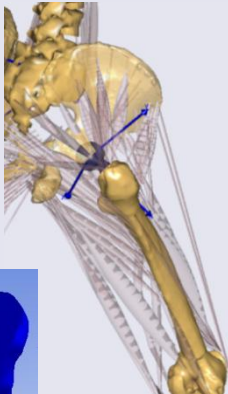
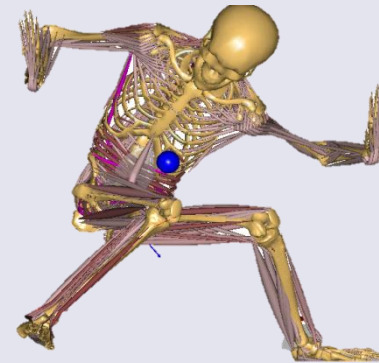


Ergonomic  
Analysis and  
Documentation

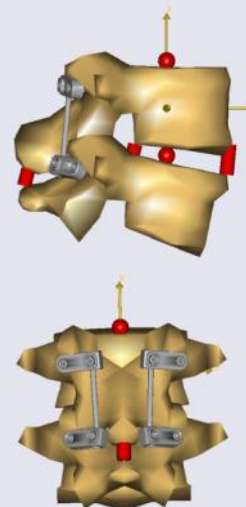
Gait Application  
AnyGait



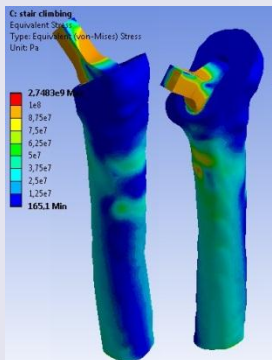
# ANYBODY Modeling System



Surgical Planning, -  
Evaluation & -Failure  
Analysis



Physiological Load  
Cases for Finite  
Element Analysis





# AnyGait

The screenshot displays the AnyBody software interface. On the left, a 3D model of a human skeleton is shown in a walking posture, standing on a grey platform with a coordinate system (X, Y, Z). Below the model, a diagram shows a sequence of three grey rectangular blocks representing a gait cycle, with red arrows indicating the direction of movement and the position of the feet.

The main window is titled "ANYBODY TECHNOLOGY" and shows a "Current Project: Test" window. A red circle highlights the "Project" folder in the left-hand "Projects" tree. A red rectangle highlights the "Main" task tree in the center, which includes the following items:

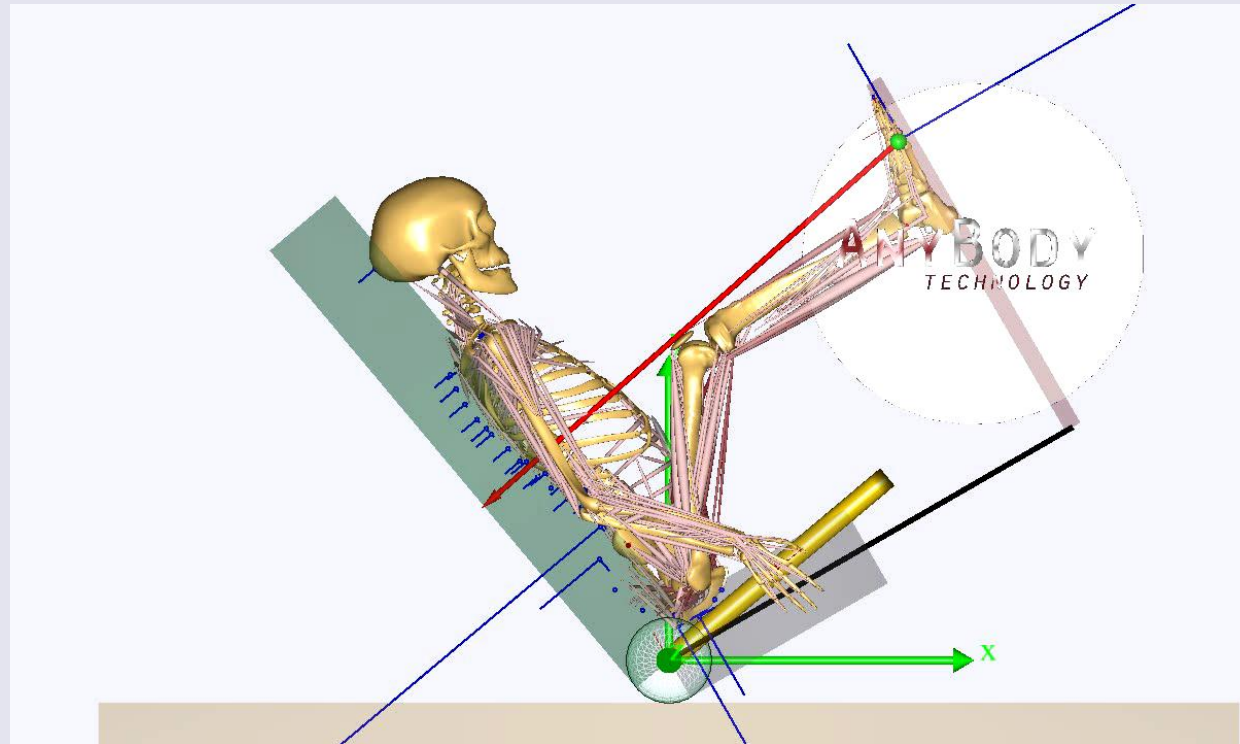
- Project
- Tasks
  - Setup
  - PreProcessing\_Load
  - PreProcessing\_Run
  - Processing\_Load
  - Processing\_Run
  - ChangeProject
- Views
- Files
- Autos
- Output

On the right side of the interface, there is a "Project Task" panel with input fields for values like 75 and 1.75, and "Browse..." buttons. Below this is a "Save Values" link. The bottom of the window features a console window with a status bar showing "Elapsed Time: 0:17:000".

see previous Webcasts on AnyGait from:  
- Amir Al-Munajjed  
at [www.anybodytech.com](http://www.anybodytech.com)

# Product Design Optimization

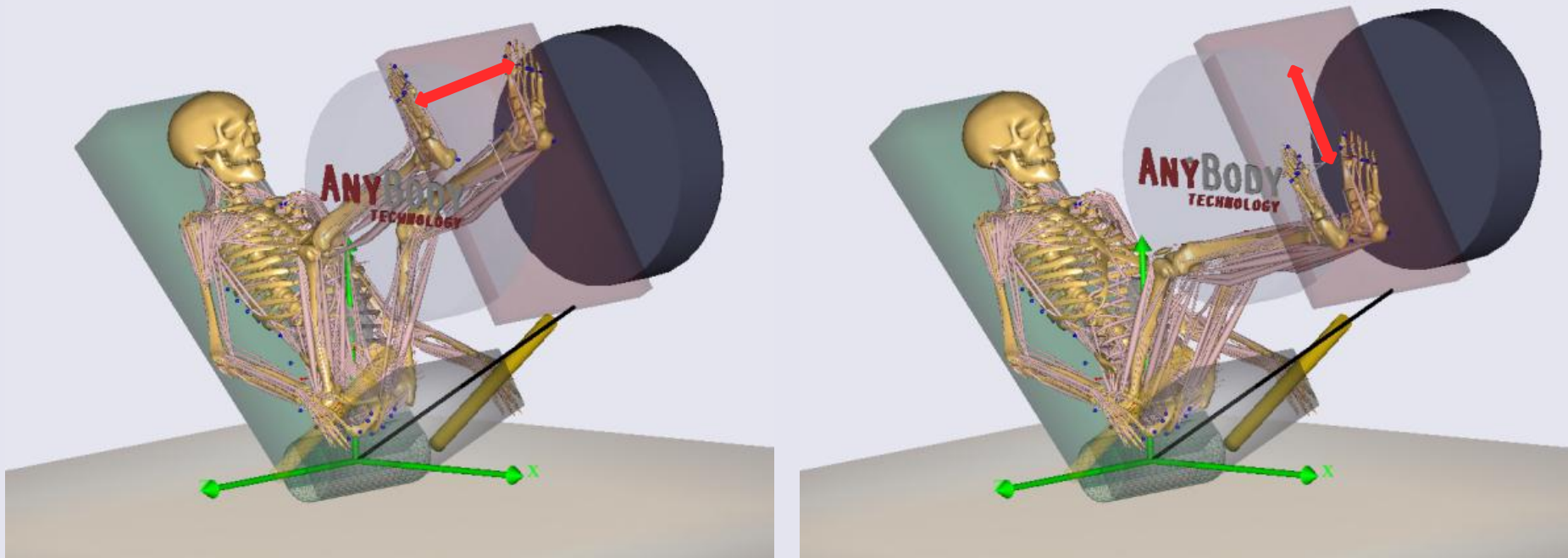
LegPressMachine for Ergonomics and Product Design Optimization



What is the optimal position for the foot?

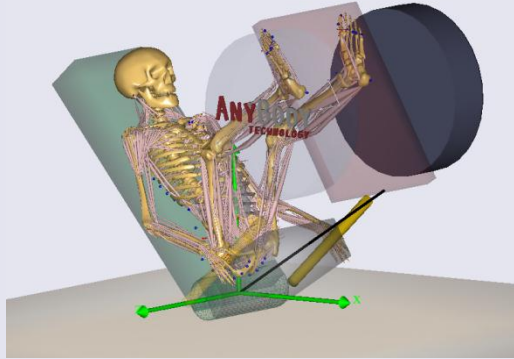
What is your target function?

# LegPressMachine

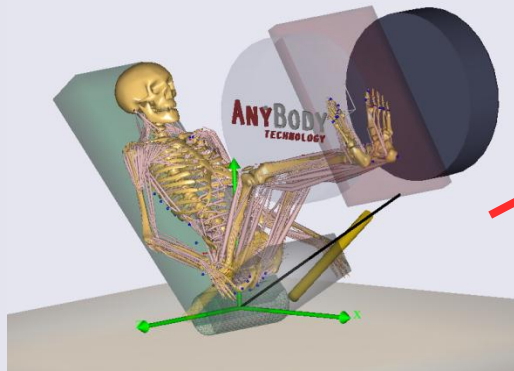
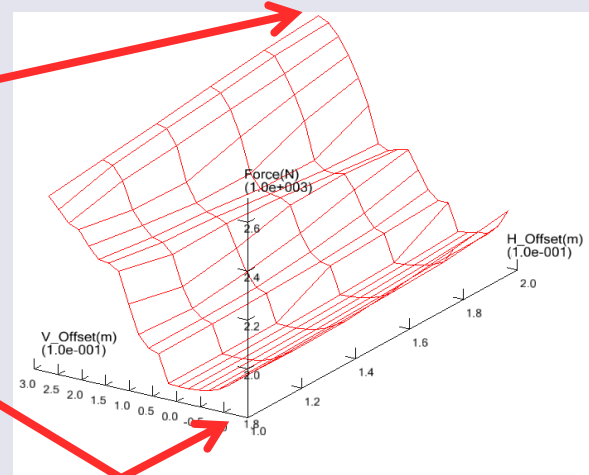


Knee Reaction Force & Leg Muscle Activation Envelope

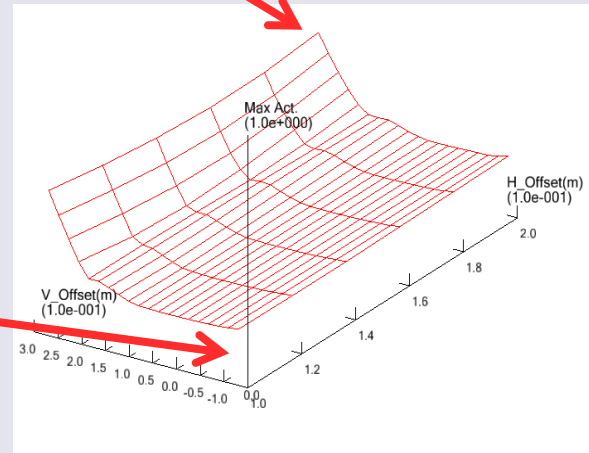
# LegPressMachine



High knee force & leg muscle activation



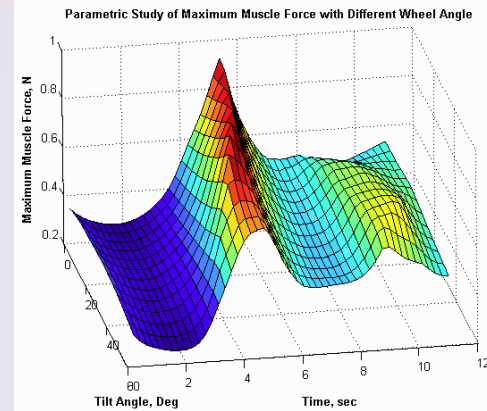
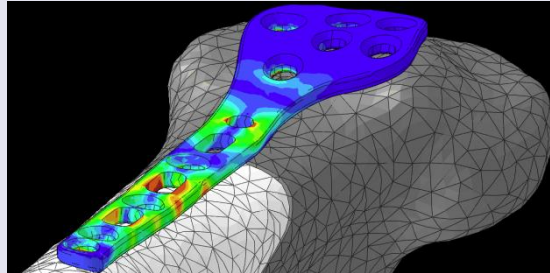
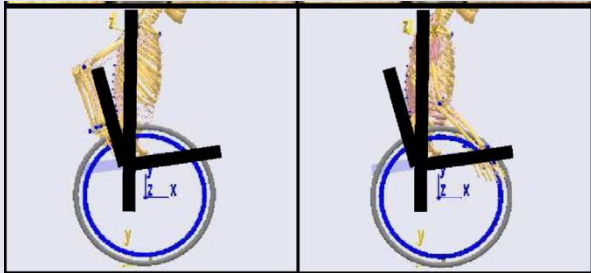
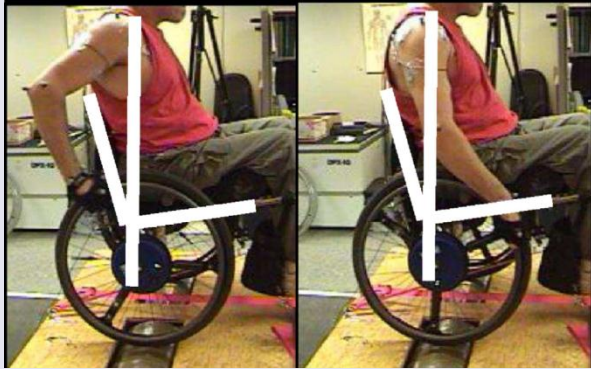
Low knee force & leg muscle activation



New 5.2: Advanced Optimization Solver



# Optimization Examples

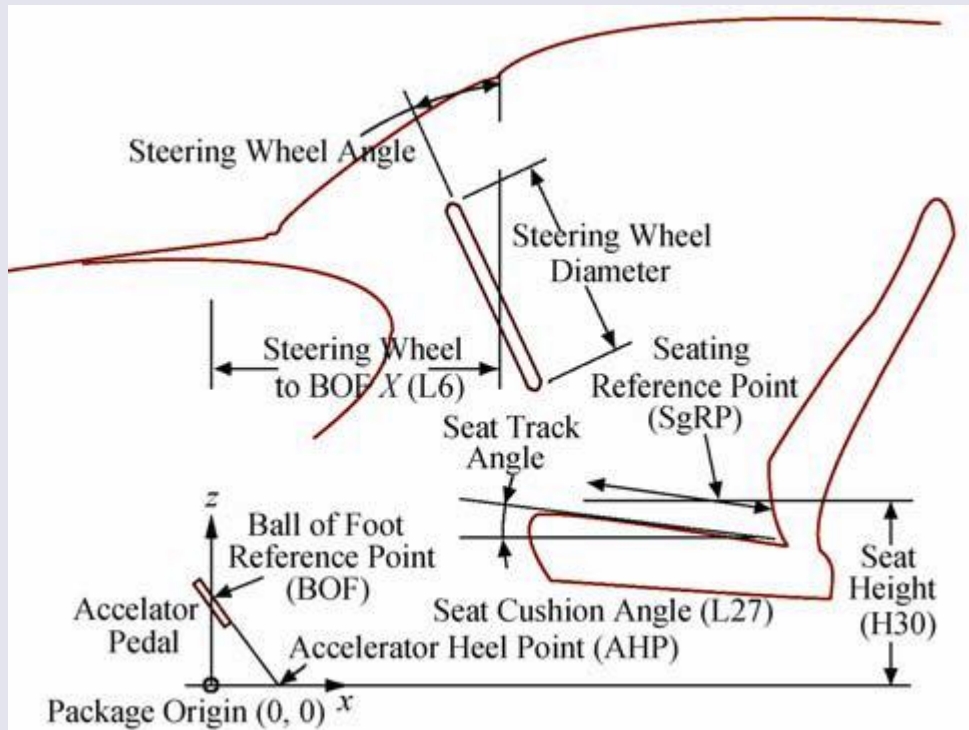


Dubowsky et al., 2008

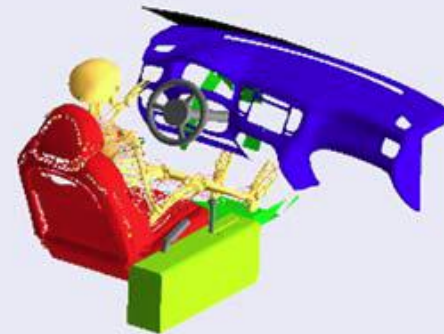
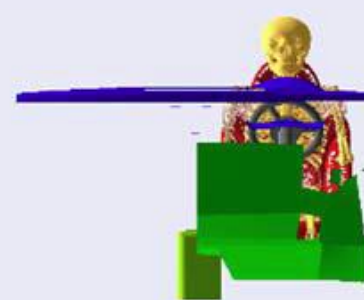
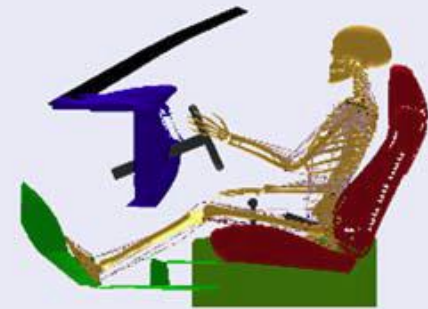
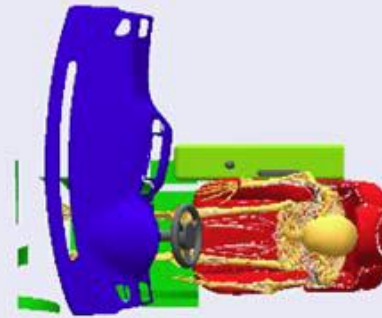
Grujicic et al., 2010

Lee et al., 2009

# Package Design & Optimization



Jung et al., 2009



New 5.2: Moving Ref Frame

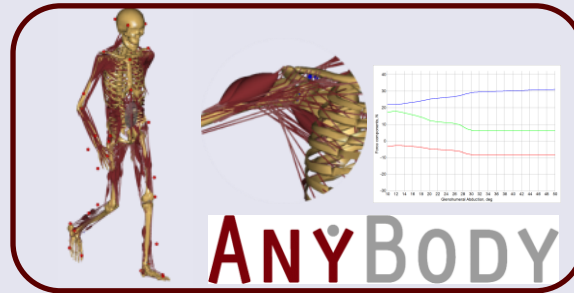
# AnyBody – Finite Element Workflow

Daily Activities



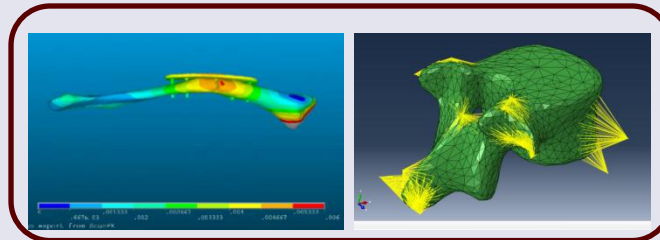
Motion

AnyBody  
Modeling System



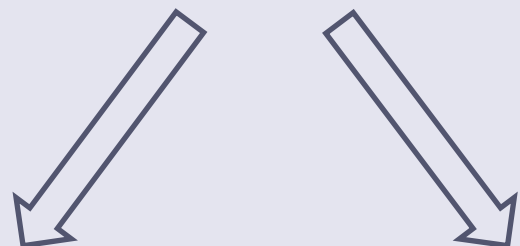
Load Case

Finite Element  
Analysis



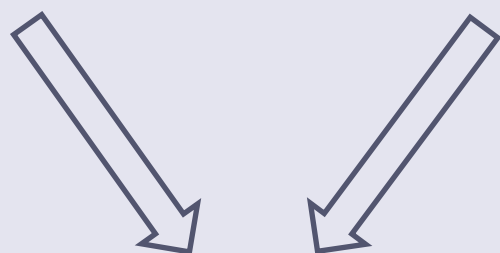
# Subject - Specific Modeling

Standard avg.  
European Male

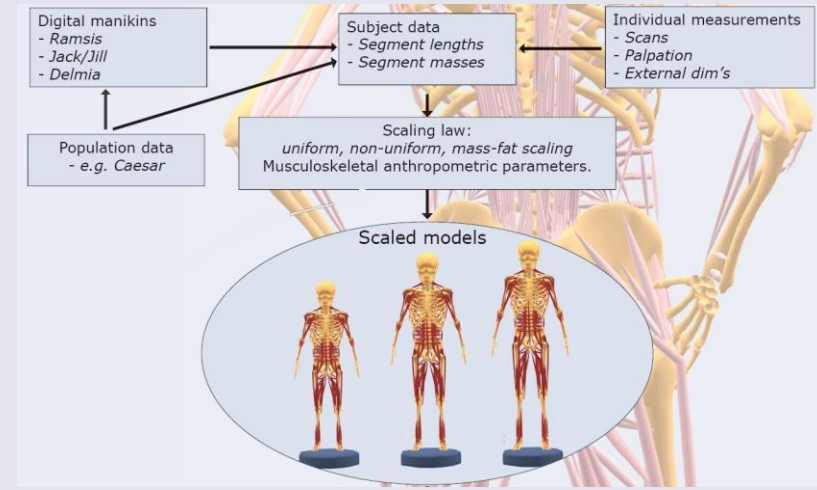


Anthropometric  
Scaling

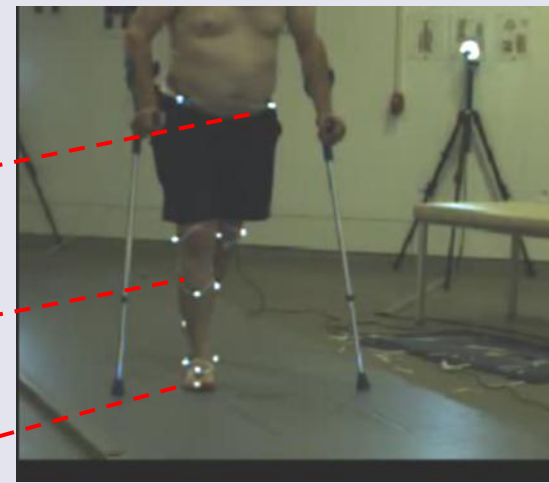
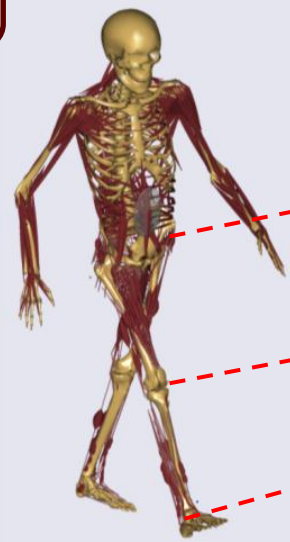
Kinematic Scaling:  
Dynamic or Static



Morphing:  
Subject Specific  
Bone Geometry



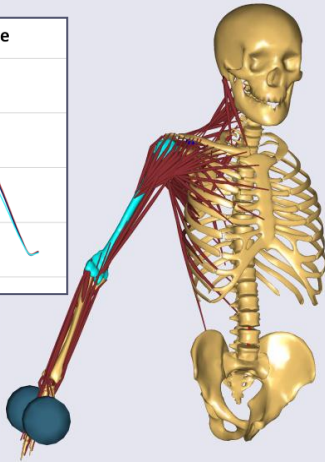
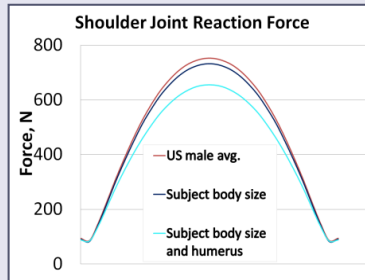
See previous Webcast on Anthro Scaling  
Rasmussen et al. 2005



Andersen et al, 2010a/b & 2012

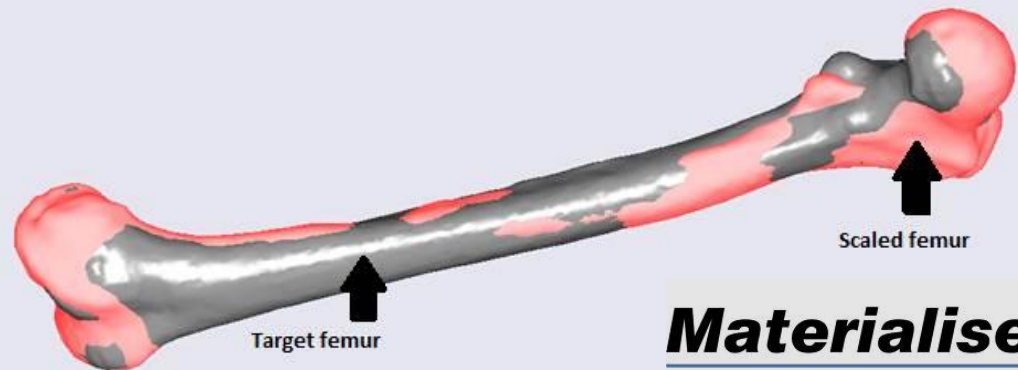
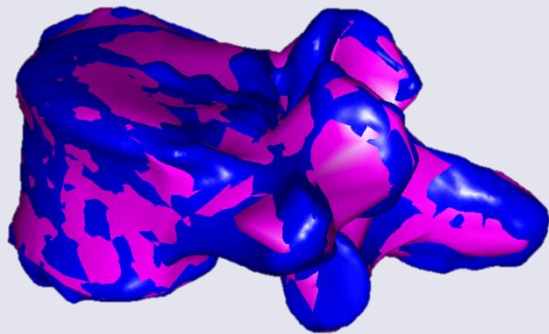


# Patient Specific Scaling



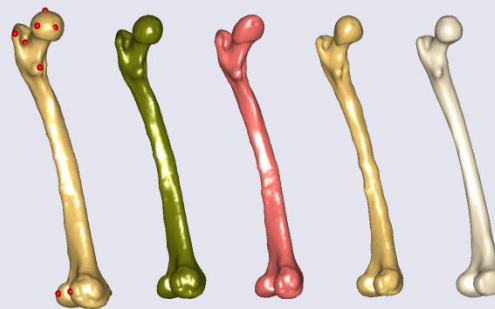
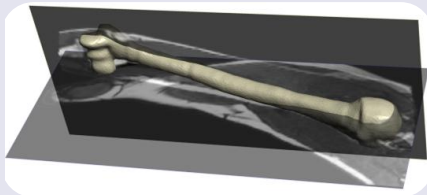
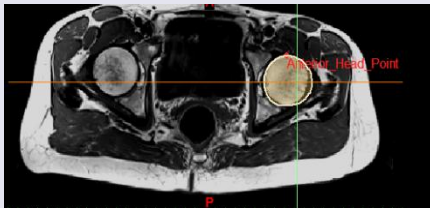
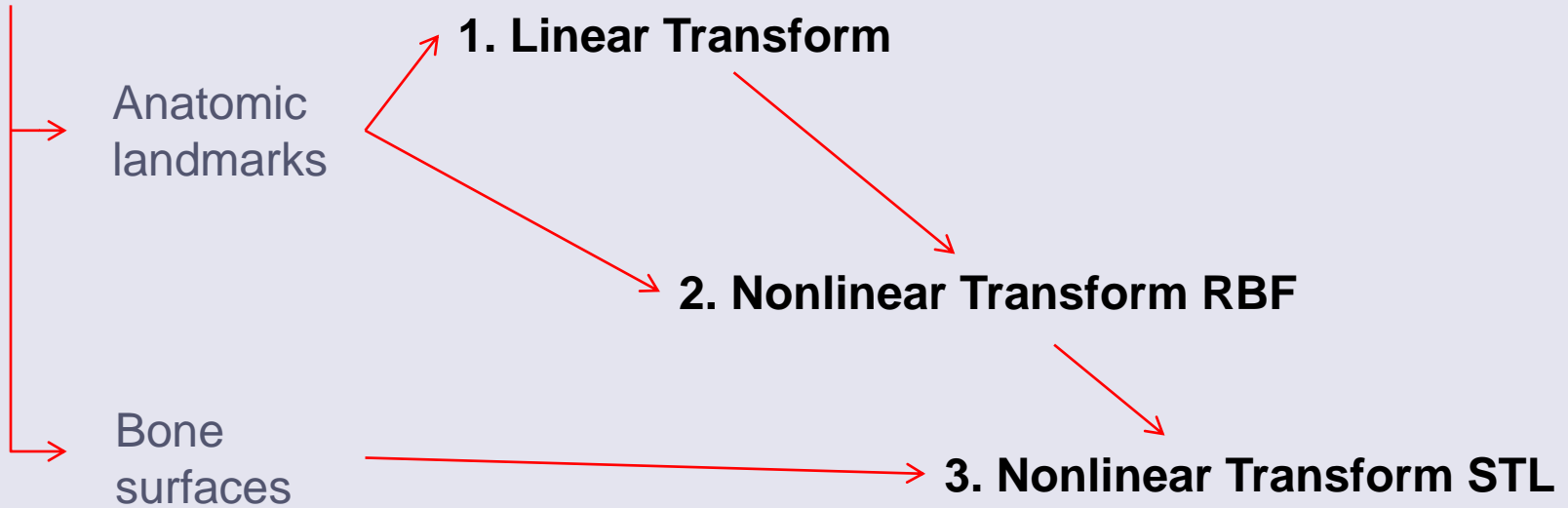
Increase Accuracy of Your Model:

- Subject-Specific Details (Inter-Subject Variability)
- Individualized Results for Patient-Specific Planning.
- Precise Geometry for e.g.:
  - Facet Joint Contact in Spine
  - Impingement in Hip

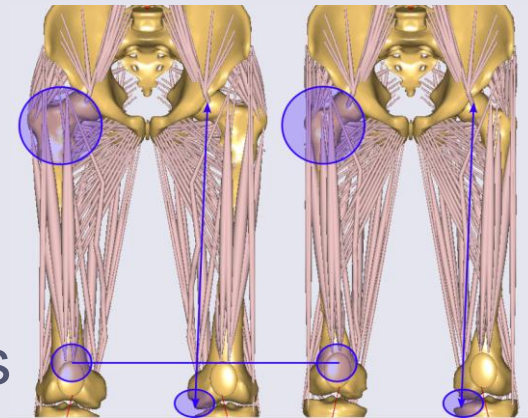


# Patient Specific Scaling

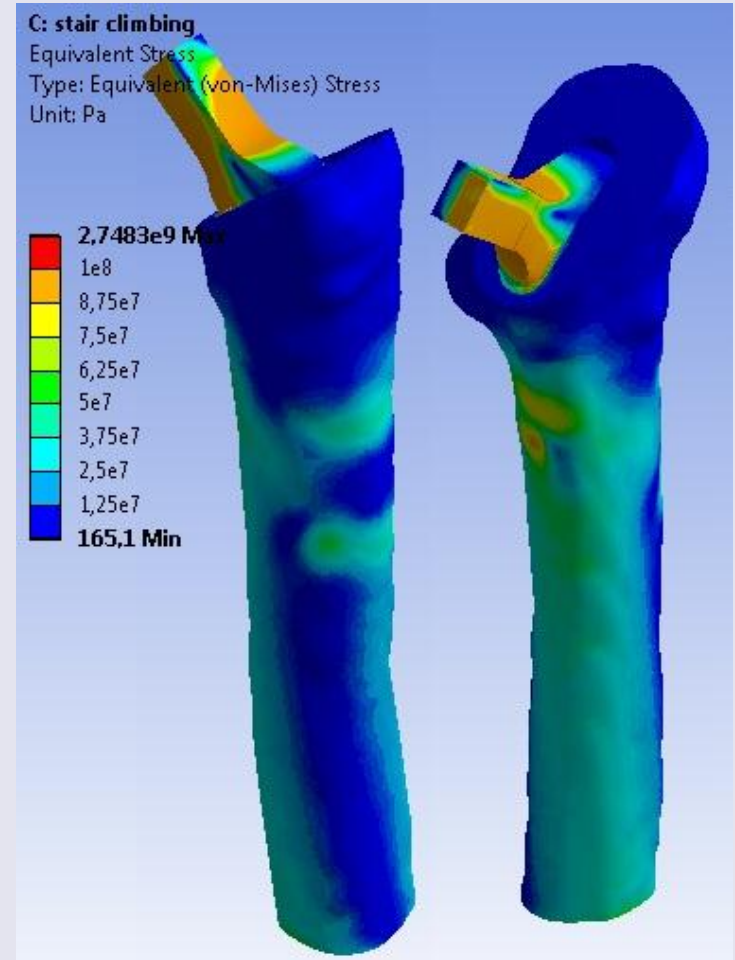
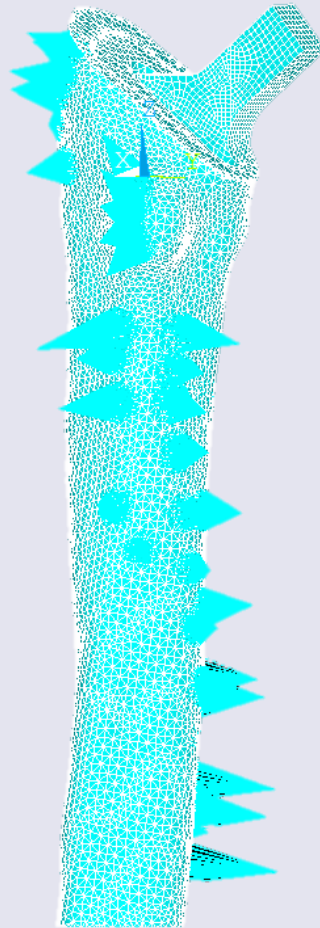
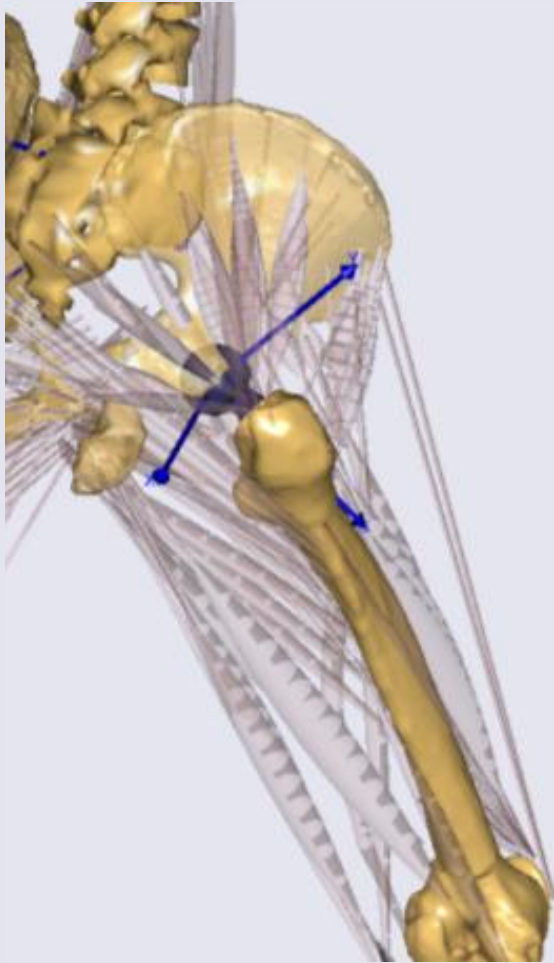
Medical Image to  
3D Geometry:



New 5.2: combine 3 methods

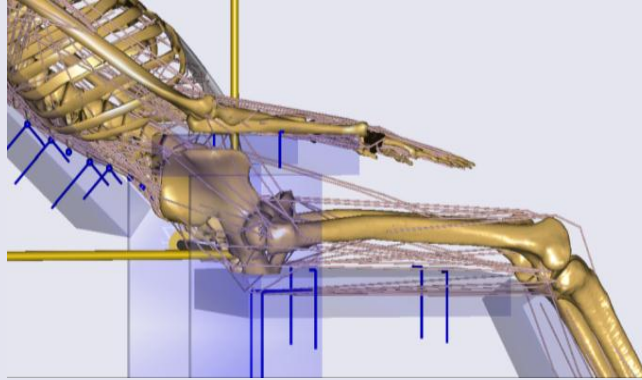


# Hip Replacements

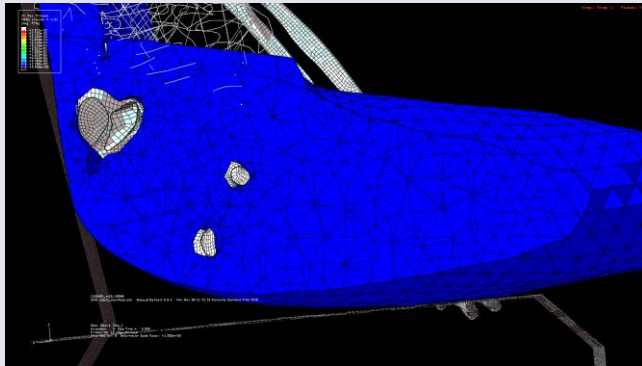




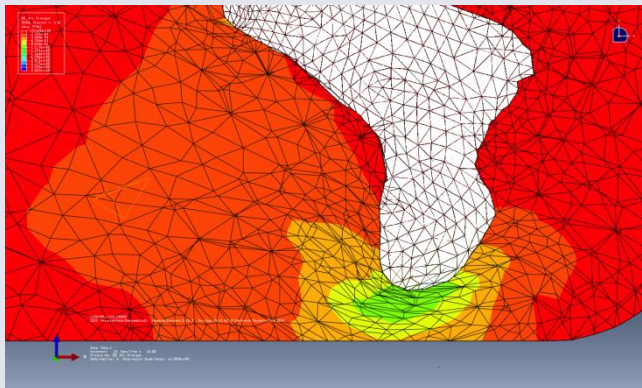
# Sitting-acquired deep tissue necrosis



**AnyBody Seated Human**  
Boundary conditions



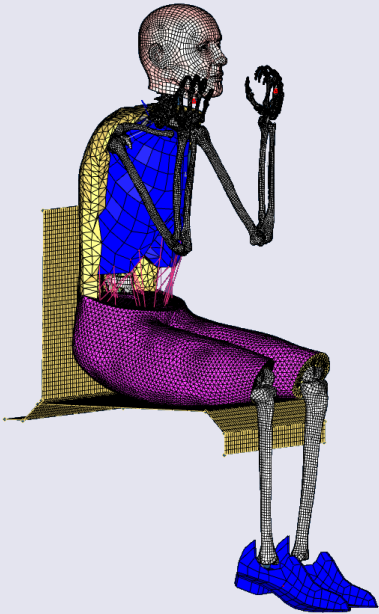
**CASIMIR**  
Non-linear  
material & geometry



**Abaqus**  
Buttock strain

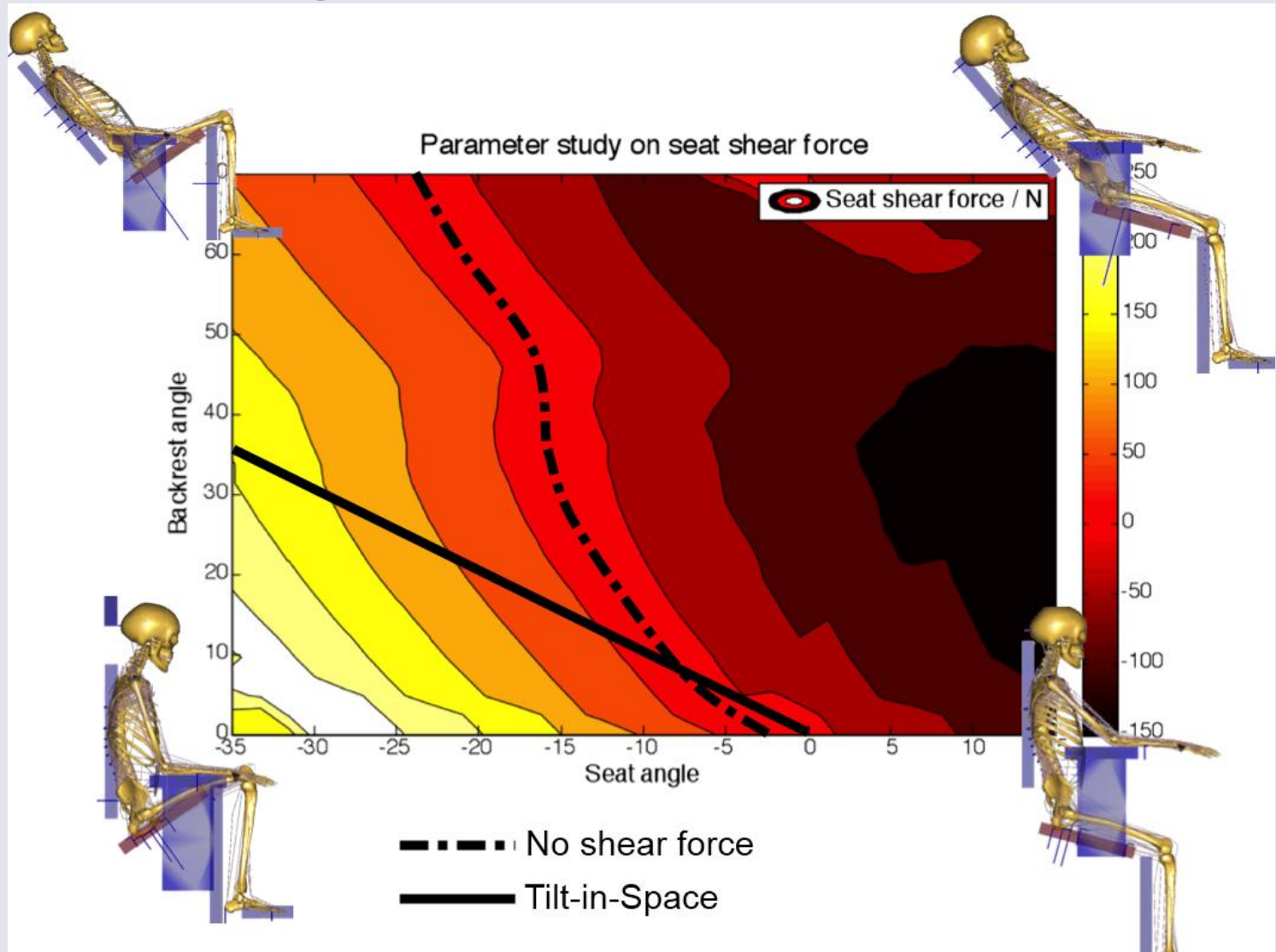


*Cell necrosis*  
*Pressure ulcer*



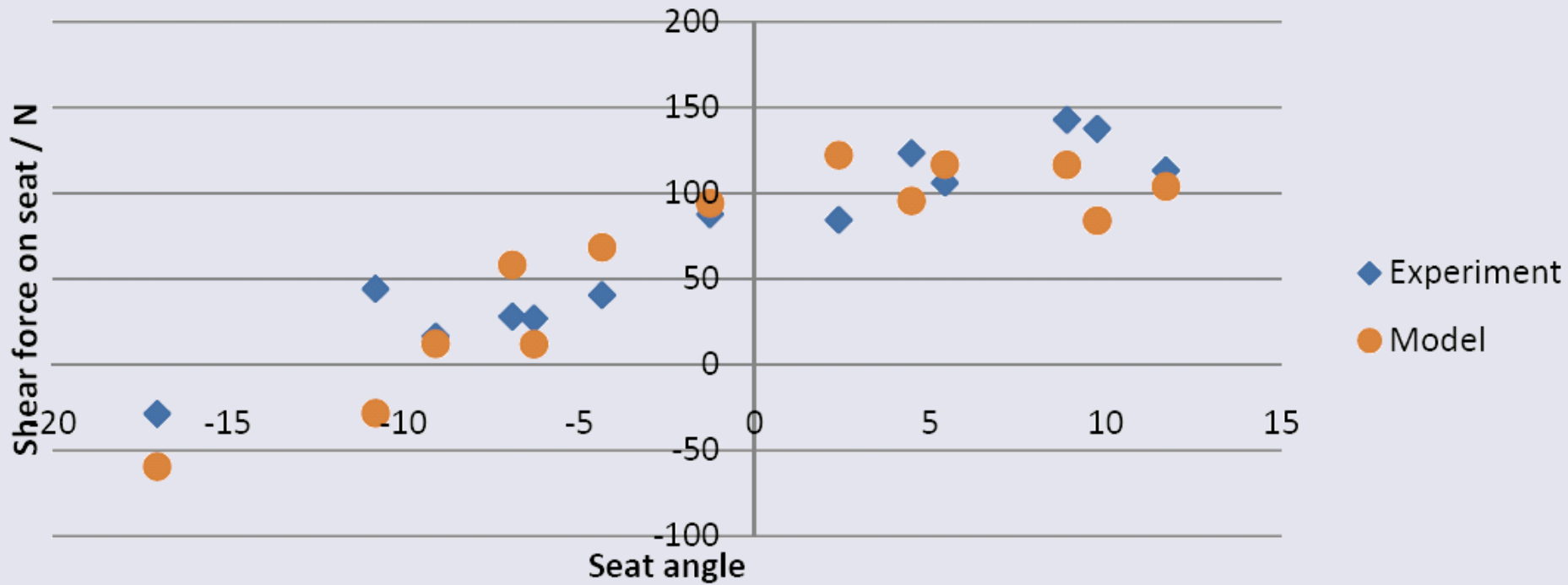


# Design of intervention



# Validation

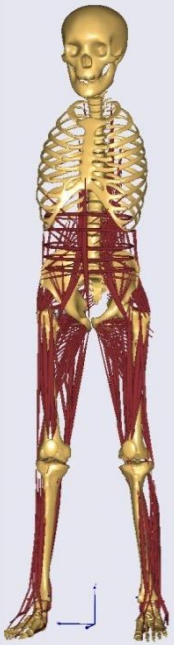
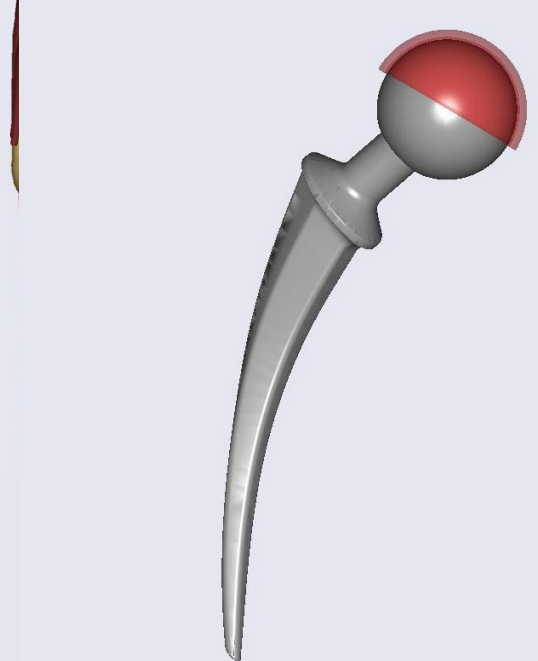
## Seat angle / Shear force



# Surgical Planning

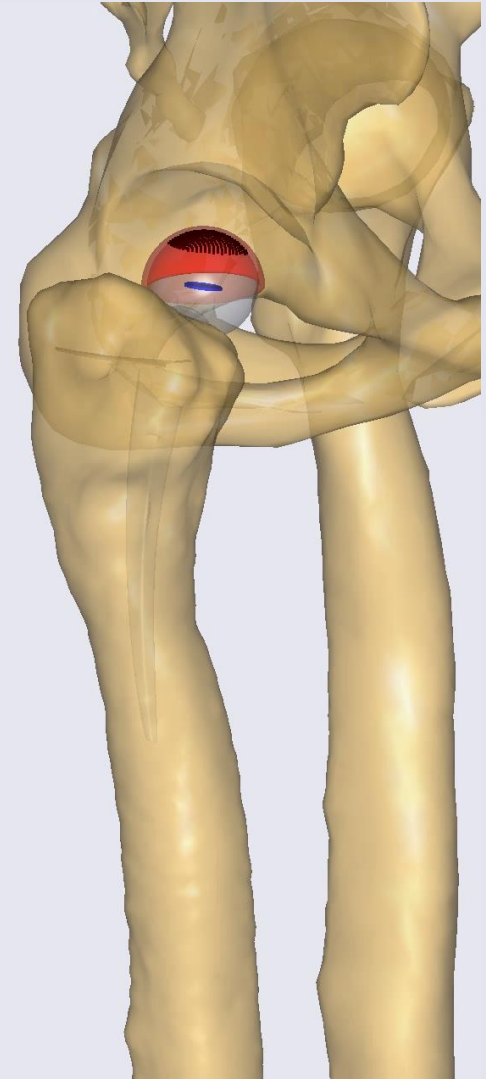
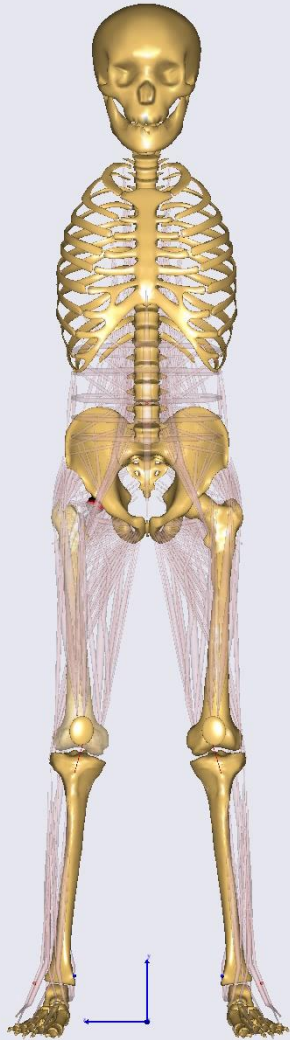
## THA-KneeBend Model

- Exchange of Hip Joint
- Hip as idealised joint or fdk joint
- Widgets for Implant position
- Implants exchangeable



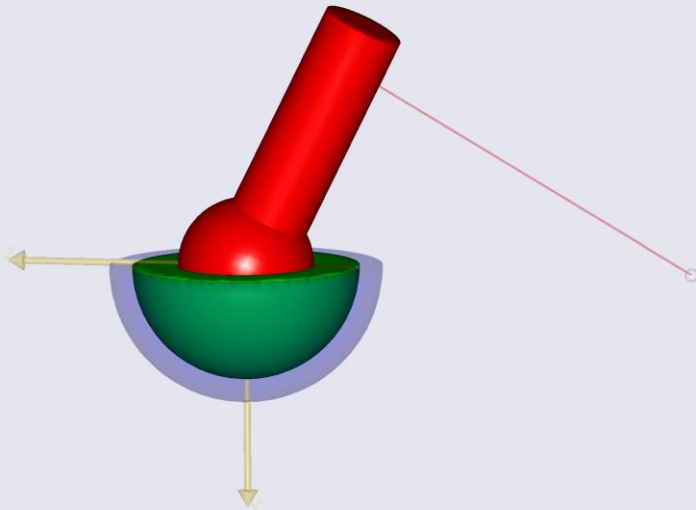
Implant from GrabCAD

# THA-KneeBend Model





# Explain FDK & Contact



see previous Webcasts on FDK from:

- John Rasmussen
  - Michael S Andersen
  - Michael Damsgaard
- at [www.anybodytech.com](http://www.anybodytech.com)



Andersen et al., 2011

see previous Webcasts from:

- Michael S Andersen
- at [www.anybodytech.com](http://www.anybodytech.com)

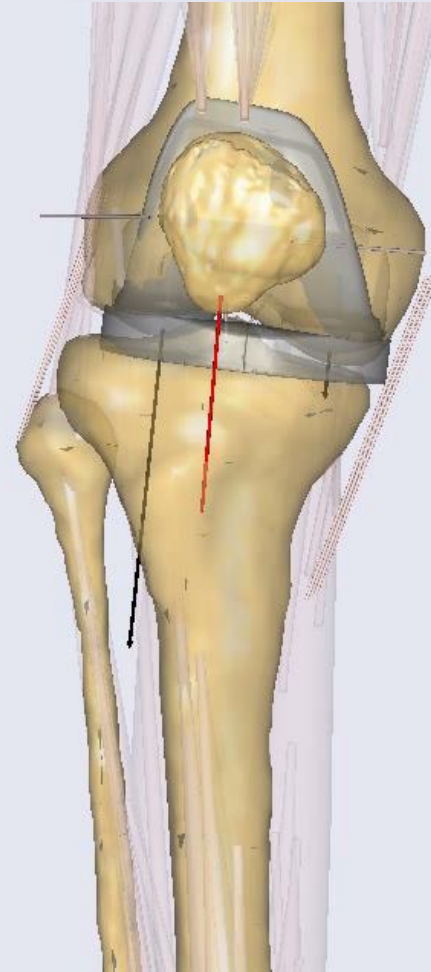
Knee Implant from Grand Challenge 1

# Knee replacement

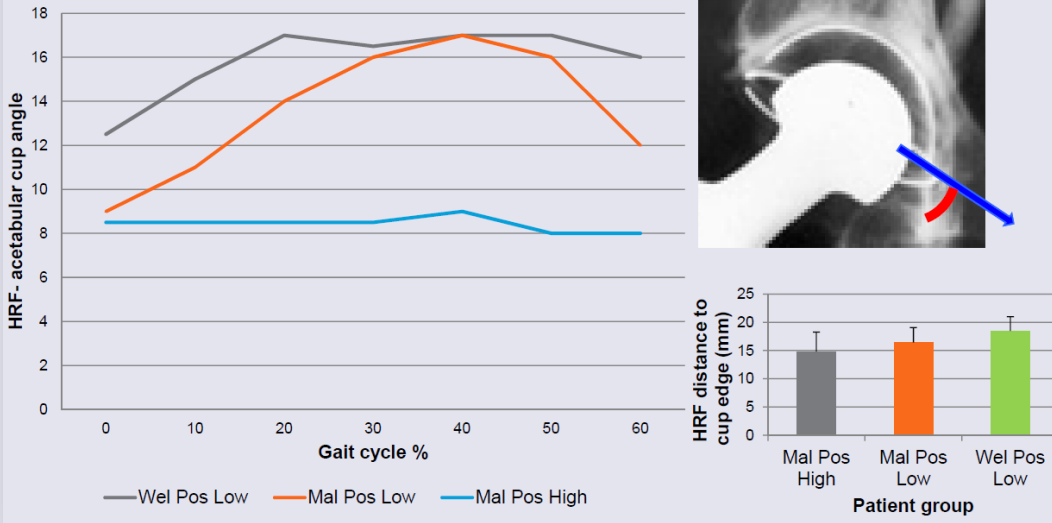


Andersen et al., 2011

Knee Implant from Grand Challenge 1

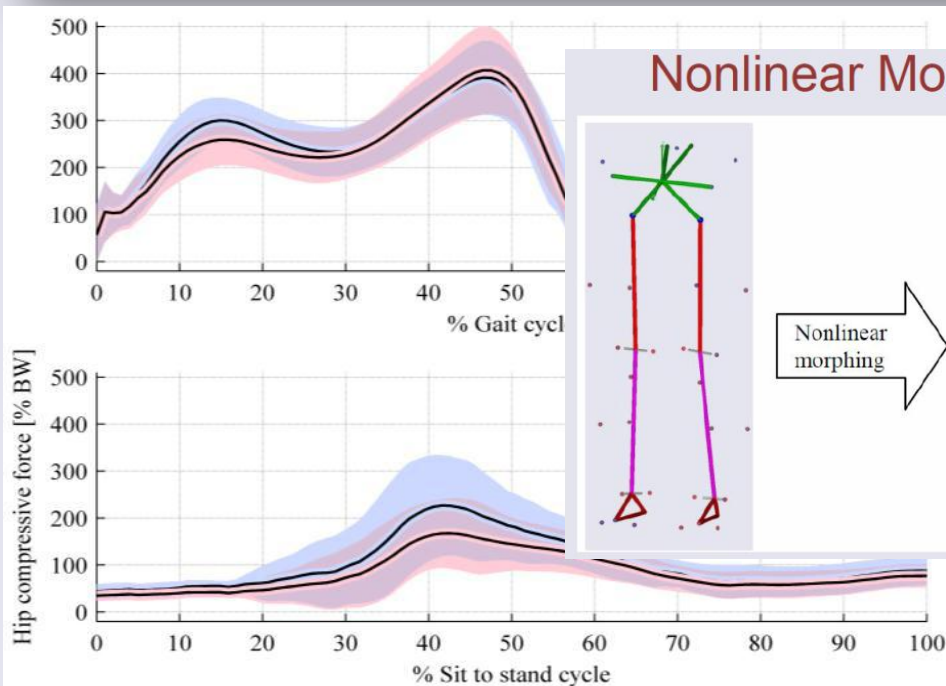


# Patient-specific motion analysis



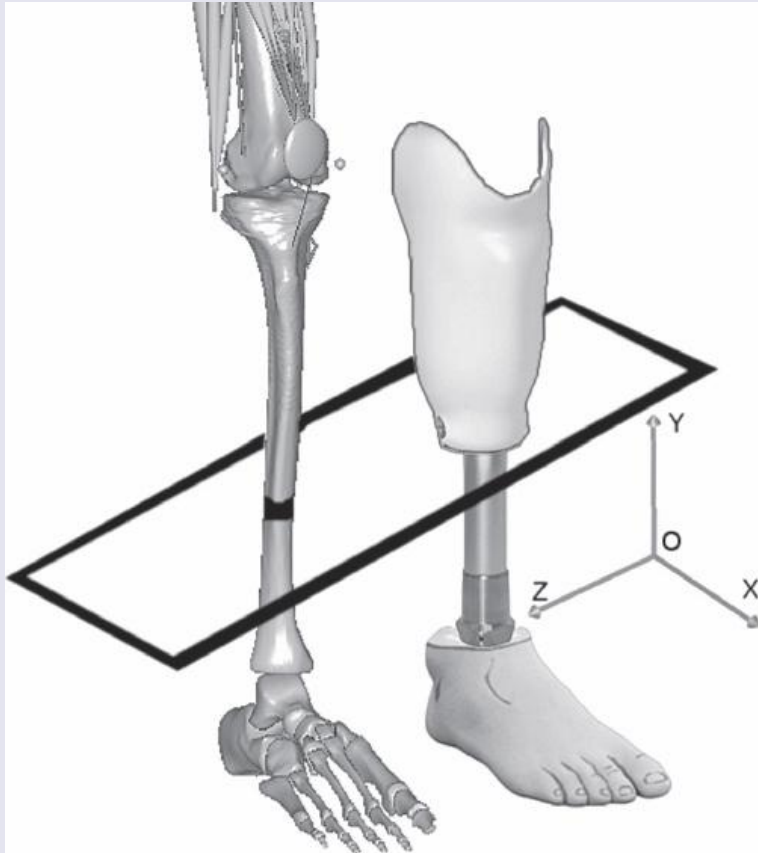
Grammatopolous et al. 2012

Mellon et al. 2012

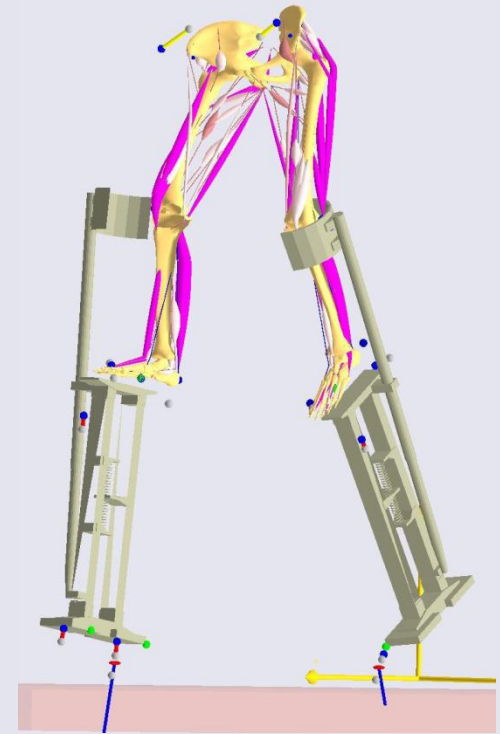


Andersen et al. 2012

# Estimation of the forces generated by the thigh muscles for transtibial amputee gait



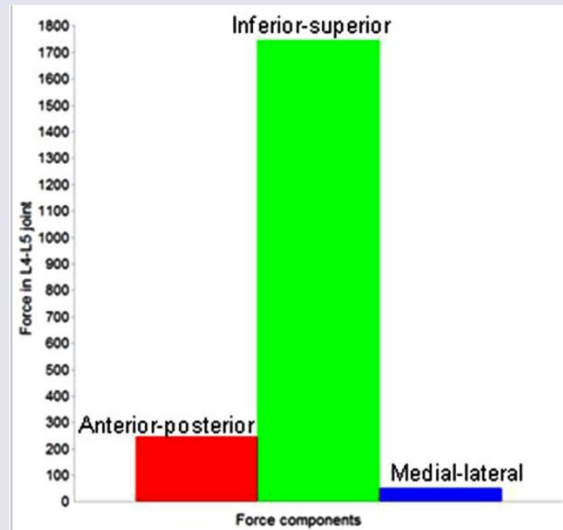
Voinescu et al. 2012



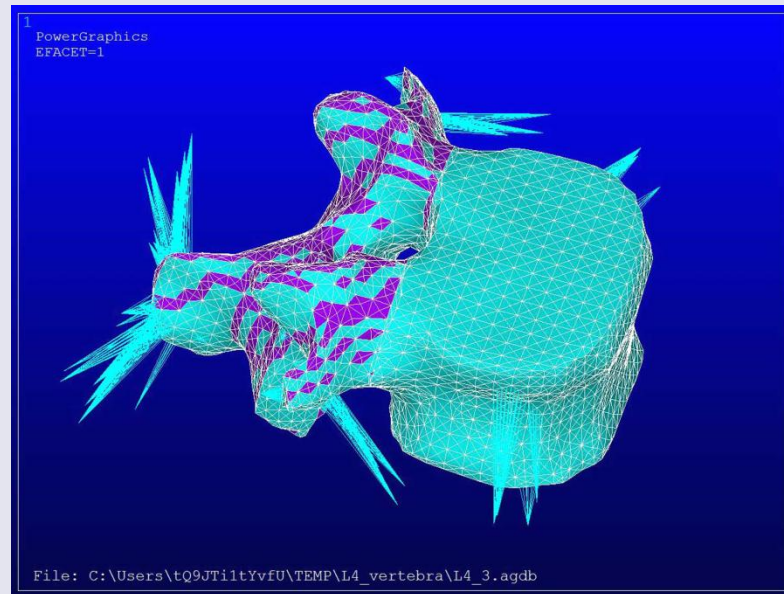
Wu et al. 2009



# The Influence of Muscle Forces on the Stress Distribution in the Lumbar Spine

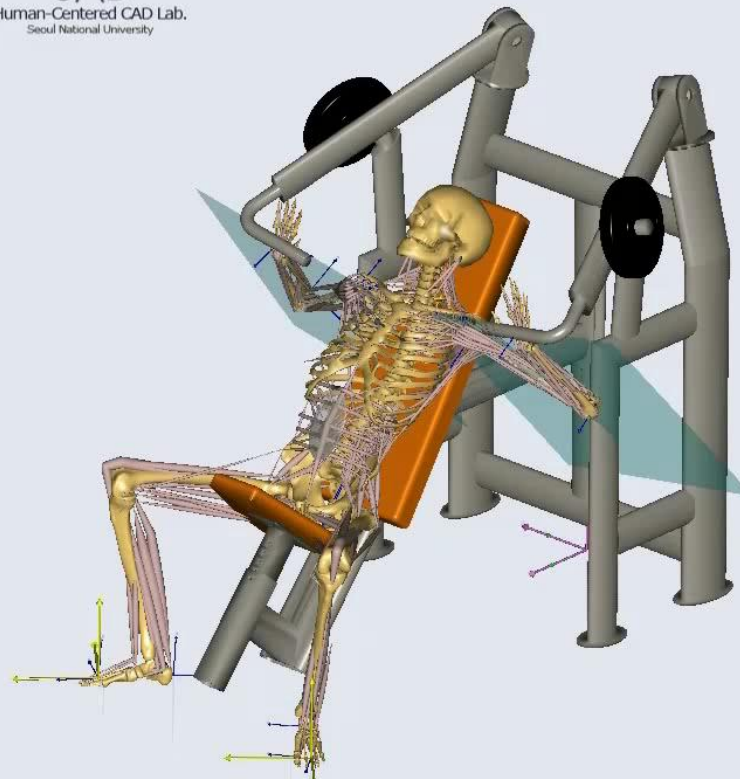


Wong et al. 2011



# Future

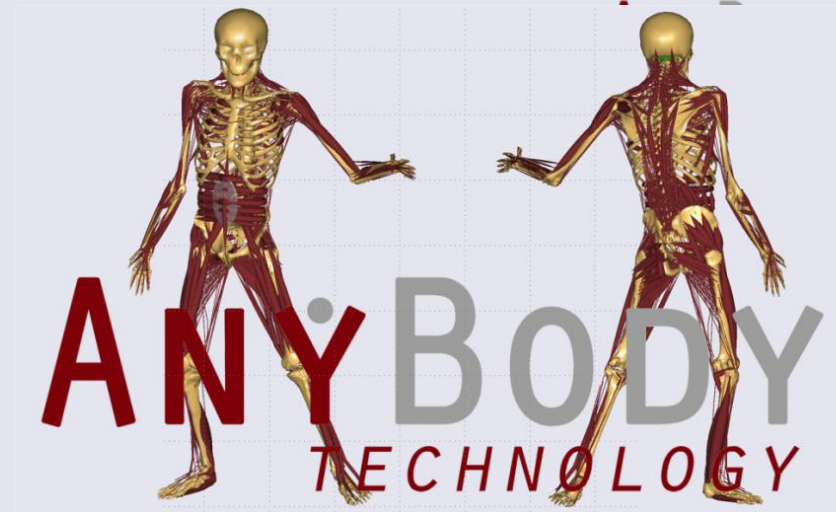
- SolidWorks Interface



Jung et al. ASB 2011

# Q & A

- [aa@anybodytech.com](mailto:aa@anybodytech.com)
- [www.anybodytech.com](http://www.anybodytech.com)
- [www.anyscript.org](http://www.anyscript.org)



## Webcast

- 5<sup>th</sup> Sept: Orthopedic Applications in the Hip
- 3<sup>rd</sup> Oct: Orthopedic Applications in the Spine

## Meet AnyBuddies at:

- 18-20 July: *3D Analysis of Human Movement*, Bologna, Italy
- 15-18 Aug: *Am. Soc. Biomechanics*, Gainesville, FL
- 13-15 Sep: *ESMAC*, Stockholm, Sweden